## Circus Solution of ESELSpec for the ESEL System

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## 1 Header

```
section ESELHeader parents circus_toolkit
```

This section gives all basic definitions that will be used in all three *Circus* models. And gateway related definitions are only used in the ESEL System 2.

First of all, three constants are defined.  $MAX\_ESEL$  and  $MAX\_PID$  stand for maximum number of displays and maximum number of product categories (or, products for short) in the system separately. And constant  $MAX\_GATEWAY$  stands for maximum number of gateways.

```
MAX\_ESEL: \mathbb{N}
MAX\_PID: \mathbb{N}
```

Then all displays and products are identified by a tag plus a unique number which are defined in the free types ESID and PID below where the constructors ES and PD are the tags for displays and products. For an instance, number ten of the display is given ES 10 or ES(10). Similarly, GID gives all identities for gateways.

```
ESID ::= ES\langle\langle 1 ... MAX\_ESEL \rangle\rangle
PID ::= PD\langle\langle 1 ... MAX\_PID \rangle\rangle
```

The type of product price is defined as an abbreviation to natural numbers N.

```
Price == \mathbb{N}
```

The unit response is defined as a free type with two constants: *uok* and *ufail*.

```
UStatus ::= uok \mid ufail
```

The response from this program to the environment is a set of product identities of which the price is not updated successfully due to 1) no linked ESEL ID to the product or 2) failed update to its linked ESEL. The first reason is given the status constant NA and the second is provided the constructor  $fail \langle\langle ESID \rangle\rangle$ .

```
FStatus ::= fail \langle \langle ESID \rangle \rangle \mid NA
```

Two channels are provided to update the map from ESEL ID to product ID. *updateallmap* will clear all stored map and use the input map as new map, while *updatemap* just updates a partial map. In this map, one ESEL can be linked to up to one product. However, one product may associate with multiple ESELs.

```
channel updateallmap : ESID \rightarrow PID channel updatemap : ESID \rightarrow PID
```

Similarly, two channels are provided to update the price information. *updateallprice* will clear all price information and use the input price information as new price, while *updateprice* just updates price partially.

```
channel updateallprice : PID \rightarrow Price
channel updateprice : PID \rightarrow Price
```

The *update* channel gives a signal to the program to start update process.

```
channel update
```

The failures channel returns all failed products and related error reasons after update. Since one product may associate with multiple displays, the return status is a power set of FStatus to denote which specific displays that the product links are updated unsuccessfully. But it is worth noting that NA and fail must not occur in a product's return set at the same time because they can not be both no associate display and associate display update fail.

```
channel failures : PID \rightarrow \mathbf{P} FStatus
```

The internal *resp* event is used to collect update responses from all displays and *terminate* event is for completing the collection.

```
\begin{array}{l} \textbf{channel} \ \textit{resp}: \textit{PID} \times \textit{FStatus} \\ \textbf{channel} \ \textit{terminate} \\ \textbf{channelset} \ \textit{RespInterface} == \{ \{\textit{resp}, \textit{terminate} \} \} \end{array}
```

This *uupdate* event is to update one ESEL to the specific price, and *ures* for update response from this ESEL. And *udisplay* is used to synchronise the show of price on all ESELs at the same time and *finishdisplay* is used to wait for display completion of all ESELs. That is the similar case for *uinit* and *ufinishinit* that are for initialisation synchronisation.

```
channel uupdate : ESID \times Price
channel ures : ESID \times UStatus
channel uinit, finishuinit
channel udisplay, finishudisplay
```

And display is used to synchronise the show of price on all gateways (or ESELs) at the same time and finishdisplay is used to wait for display completion of all gateways (or ESELs). That is the similar case for init and finishinit that are for initialisation synchronisation.

```
channel init, finishinit
channel display, finishdisplay
```

The channels below are for communication between the ESEL system and displays. The *write* event writes price to a display, and the *read* event reads price from the display. *ondisplay* turns on the related display and *offdisplay* turns off it conversely.

```
\begin{array}{ll} \textbf{channel} & \textit{write}: \textit{ESID} \times \textit{Price} \\ \textbf{channel} & \textit{read}: \textit{ESID} \times \textit{Price} \\ \textbf{channel} & \textit{ondisplay}: \textit{ESID} \\ \textbf{channel} & \textit{offdisplay}: \textit{ESID} \\ \end{array}
```

## 2 ESELSpec

```
section ESELSpec parents ESELHeader
```

**Controller Process** The process for overall control of the system, named *Controller*, is defined as an explicitly defined process.

```
process Controller = \mathbf{begin}
```

Controller has three state components: pumap for mapping from displays to products, ppmap for mapping from products to their price, and response for the response of one update to the environment.

```
state State == [pumap : ESID \rightarrow PID ; ppmap : PID \rightarrow Price; response : PID \rightarrow (P FStatus)]
```

Initially, these three state components all are empty.

```
Init == [(State)' \mid pumap' = \emptyset \land ppmap' = \emptyset \land response' = \emptyset]
```

The *UpdateMap* schema updates part of the displays to products map according to the input map, while the *UpdateAllMap* schema discards stored map and uses new input map as *pumap*.

```
 \begin{array}{l} \textit{UpdateMap} == [ \, \Delta \textit{State} \; ; \textit{map?} : \textit{ESID} \rightarrow \textit{PID} \; | \\ \textit{pumap'} = \textit{pumap} \oplus \textit{map?} \land \textit{ppmap'} = \textit{ppmap} \land \textit{response'} = \textit{response} \, ] \\ \textit{UpdateAllMap} == [ \, \Delta \textit{State} \; ; \textit{map?} : \textit{ESID} \rightarrow \textit{PID} \; | \\ \textit{pumap'} = \textit{map?} \land \textit{ppmap'} = \textit{ppmap} \land \textit{response'} = \textit{response} \, ] \\ \end{array}
```

The NewPrice updates part of price information stored, while the AllNewPrice discards all price information stored and uses input price as ppmap.

```
NewPrice == [\Delta State ; price? : PID \rightarrow Price \mid ppmap' = ppmap \oplus price? \land pumap' = pumap \land response' = response]
AllNewPrice == [\Delta State ; price? : PID \rightarrow Price \mid ppmap' = price? \land pumap' = pumap \land response' = response]
```

AUpdatemap is an action defined to update displays to products map: either partial update by updatemap event or complete update by updateallmap event.

```
AUpdatemap \cong updatemap?map \rightarrow (UpdateMap)
\Box updateallmap?map \rightarrow (UpdateAllMap)
```

Similarly, ANewPrice is an action defined to update products to price map: either partial update by updateprice event or complete update by updateallprice event.

```
ANewPrice \stackrel{\frown}{=} updateprice?price \rightarrow (NewPrice)
\Box updateallprice?price \rightarrow (AllNewPrice)
```

A parameterised action, AUpdateUnitPrice, is given to update the price (specified by the formal pid parameter) to a display (given by the formal uid parameter). It sends the price to the specified display by the write event, and then read back the price from the display by the read event. If the write price matchs with the read price, then the update is successful. Otherwise, it fails (ufail) and sends the result to response collection action CollectResp below, then terminates.

```
AUpdateUnitPrice \stackrel{\frown}{=} uid : ESID ; pid : PID \bullet \\ write.uid.(ppmap pid) \rightarrow read.uid?y \rightarrow \\ ((y = (ppmap pid)) \otimes \mathbf{Skip} \\ \Box (y \neq (ppmap pid)) \otimes resp.pid.(fail uid) \rightarrow \mathbf{Skip})
```

The parameterised action AUpdateProductUnits aims to update one product's price specified by the formal pid parameter in case the product has associated displays. Since one product may have more than one associated displays, this action updates the product's price to all associated displays. Furthermore, the update to each display is independent. Therefore, they are combined together into an interleave. It is worth noting that each AUpdateUnitPrice action will not update state or local variables and thus its name set is empty.

```
\begin{array}{l} \textit{AUpdateProductUnits} \ \widehat{=} \ \textit{pid} : \textit{PID} \bullet \\ (\left|\left|\left| \ \textit{uid} : \left(\text{dom}\left(\textit{pumap} \rhd \{\textit{pid}\}\right)\right) \right.\right| \left[\varnothing\right]\right| \right| \bullet \textit{AUpdateUnitPrice}(\textit{uid},\textit{pid})) \end{array}
```

Otherwise, if the product has not been allocated the corresponding displays, it sends back a response to state this error NA. The behaviour is defined in the AUpdateNoUnit action.

```
\textit{AUpdateNoUnit} \; \widehat{=} \; \textit{pid} : \textit{PID} \; \bullet \; \textit{resp.pid.NA} \to \mathbf{Skip}
```

The behaviour of the price update for a product given in pid is the update of product either with associated displays, guarded AUpdateProductUnits, or without associated displays, guarded AUpdateNoUnit.

Then the update of all products is given in the action AUpdateProducts. At first, it is an interleave of all updates of the products which have associated price, then follows a terminate event to finish the update.

```
\begin{array}{l} \textit{AUpdateProducts} \ \widehat{=} \ ((\left|\left|\right| pid : (\textit{dom ppmap}) \parallel [\varnothing] \parallel \bullet \textit{AUpdateProduct}(pid)) \\ ; \textit{terminate} \ \rightarrow \textbf{Skip}) \end{array}
```

The AddOneFailure schema adds one failure (either update failure or no associate failure) for a product to the state component response.

```
AddOneFailure == [\Delta State ; pid? : PID ; fst? : FStatus | \\ (pid? \in dom \ response \Rightarrow \\ response' = response \oplus \{pid? \mapsto (response(pid?) \cup \{fst?\})\}) \land \\ (pid? \notin dom \ response \Rightarrow \\ response' = response \cup \{pid? \mapsto \{fst?\}\}) \land \\ ppmap' = ppmap \land pumap' = pumap]
```

The *CollectResp* action is to collect responses from all units and write them into the *response* variable by *AddOneFailure* schema expression. It recursively waits for the response from the units, or terminates if required.

```
CollectResp \cong \mu X \bullet  ((resp?pid?fst \rightarrow (AddOneFailure); X) \Box terminate \rightarrow \mathbf{Skip})
```

Then update of all products and response collection behaviours are put together into AUpdateResp action. It is a parallel composition of AUpdateProducts and CollectResp actions and they are synchronised with resp and terminate events. Furthermore, the

left action AUpdateProducts will not update state variables (its name set is empty set) while the right action CollectResp will update response (its name set has only one variable response). Finally, these internal events are hidden.

```
\begin{array}{l} \textit{AUpdateResp} \; \widehat{=} \\ & (\textit{AUpdateProducts} \; [\![ \varnothing \mid \textit{RespInterface} \mid \{\textit{response}\} \,]\!] \; \textit{CollectResp}) \\ & \land \textit{RespInterface} \end{array}
```

All displays will synchronise on display event to show the price at the same time, which is defined in ADisplay. Whether a display should be turned on or off is decided based on the logic below.

- If the display is not mapped to a product, then turn it off.
- Otherwise, if the display linked product is not to be updated, then turn it off.
- Otherwise, if the display has been written the price successfully, then turn it on.
- Otherwise, then turn it off.

```
ADisplay \stackrel{\frown}{=}
        (\llbracket\{\mid display\mid\} \rrbracket \ uid : ESID \bullet \llbracket\varnothing \rrbracket \ display \to (
               \mathbf{if} \ \mathit{uid} \not \in \mathrm{dom} \ \mathit{pumap} \longrightarrow \mathit{offdisplay.uid} \rightarrow \mathbf{Skip}
                \parallel uid \in \text{dom } pumap \longrightarrow
                       if pumap(uid) \not\in dom\ ppmap \longrightarrow offdisplay.uid \rightarrow \mathbf{Skip}
                       if pumap(uid) \not\in dom \ response \longrightarrow
                                        ondisplay.uid \rightarrow \mathbf{Skip}
                                \parallel pumap(uid) \in \text{dom } response \longrightarrow
                                       if (fail\ uid) \not\in response(pumap(uid)) \longrightarrow
                                                ondisplay.uid \rightarrow \mathbf{Skip}
                                        [] (fail\ uid) \in response(pumap(uid)) \longrightarrow
                                                offdisplay.uid \rightarrow \mathbf{Skip}
                               fi
                        fi
       )) \setminus \{ | display | \}
```

The overall price update action is given in AUpdatePrice, which accepts a update event from its environment, then clears response, updates the price, sends display event to make all ESELs show their price at the same time, then feeds back the response to the environment.

```
AUpdatePrice = update \rightarrow response := \varnothing;

AUpdateResp; ADisplay; failures.response \rightarrow Skip
```

Initially, state components are cleared and all displays are turned off.

```
AInit \stackrel{\frown}{=} (Init); (|||u:ESID|||\varnothing|| \bullet offdisplay.u \to \mathbf{Skip})
```

The overall behaviour of the *Controller* process is given by its main action. It initializes at first, then repeatedly provides display map update, price map, or price update to its environment.

• AInit;  $(\mu X \bullet (AUpdatemap \Box ANewPrice \Box AUpdatePrice); X)$ 

end

 ${\bf System}\quad \hbox{The ESEL Specification is simply the $Controller$ process.}$ 

 $\mathbf{process}\ \mathit{ESELSpec} \ \widehat{=}\ \mathit{Controller}$