



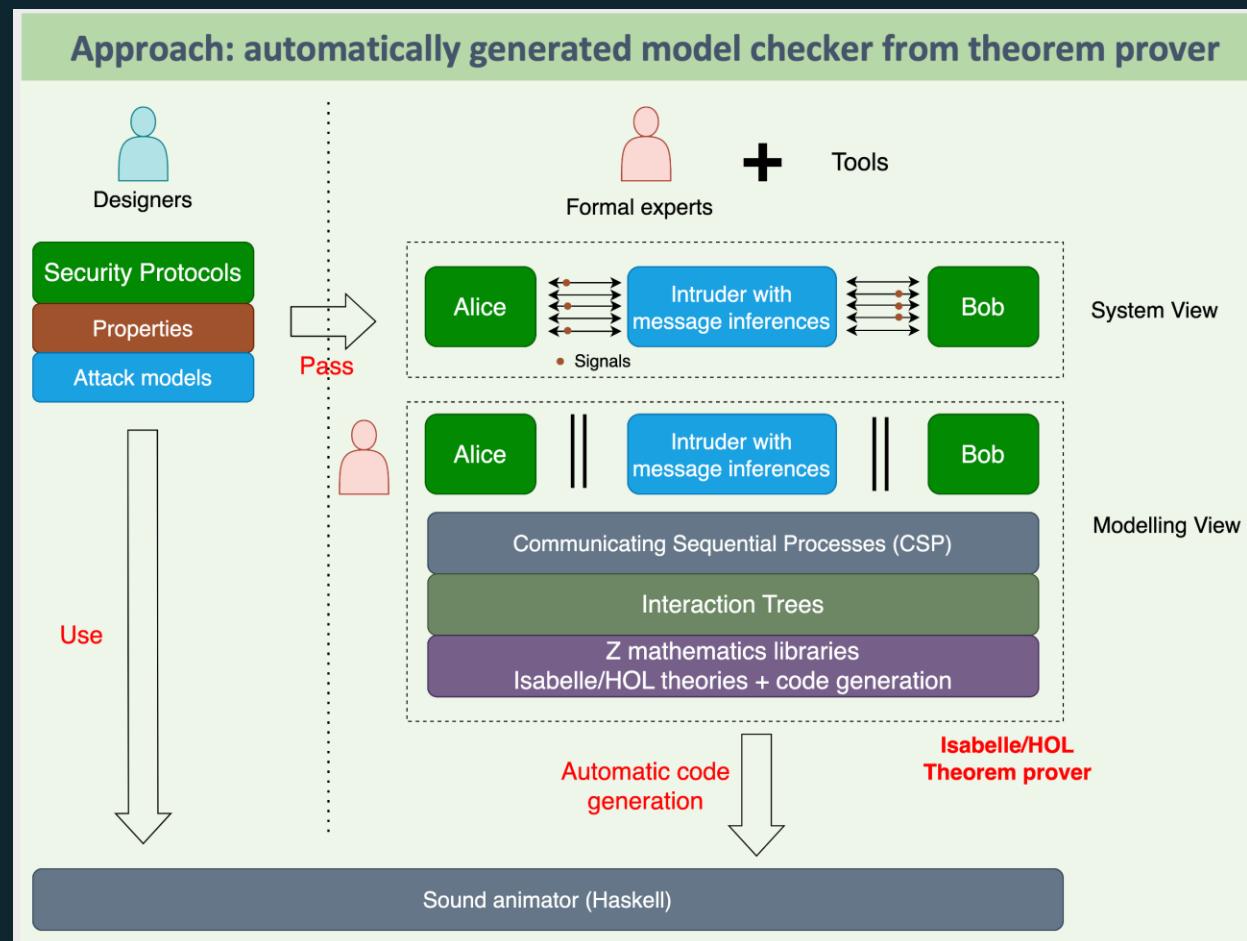
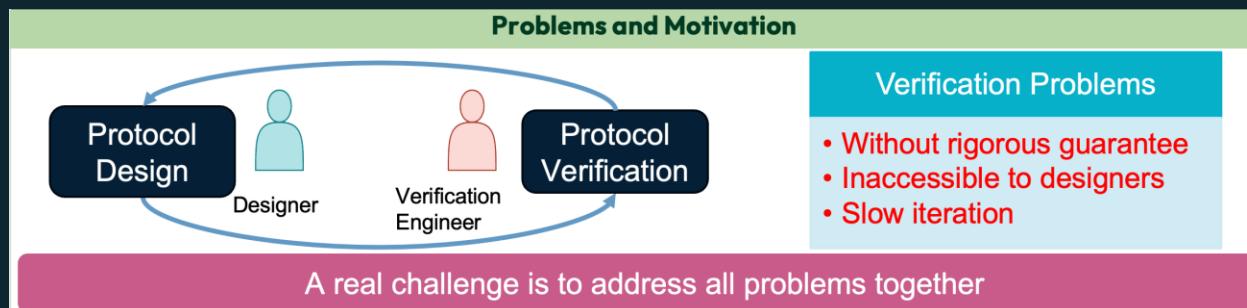
CHEDDAR



3.2 Accessible Formal Verification and Debugging Framework for Secure Protocol Design and Deployment in O-RAN Systems



Communications Hub for Empowering Distributed cloud computing Applications and Research



Terminal and web interfaces

```
/private/tmp/isabelle-ky582/process15874344610300865240/itree-simulate61782612> ./simulate/Simulation
/private/tmp/isabelle-ky582/process15874344610300865240/itree-simulate61782612>
Starting ITTree Animation...
Events:
(1) Env [Agent (Snatmake (Nat 0))] Agent (Snatmake (Nat 1));
(2) Env [Agent (Snatmake (Nat 0))] Intruder;
(3) Recv [Agent (Snatmake (Nat 1))<=Intruder] {<Nnatmake (Nat 2), Agent (Snatmake (Nat 0))>}^a_Kp (Knatmake (Nat 1));
(4) Recv [Agent (Snatmake (Nat 1))<=Intruder] {<Nnatmake (Nat 2), Intruder>}^a_Kp (Knatmake (Nat 1));

[Choose: 1-4]: |
```

No.	EventID	Channel	Source	Medium	Dest	Message
1	3	Send	Bob	Intruder	Intruder	(g^N1)^w_BM1:1
2	460	Recv	Intruder	Intruder	Alice	(g^N2)^w_BM2:1
3	475	Send	Alice	Intruder	Intruder	(g^N0)^w_BM0:1

Which event to animate? 1 ▾

Animate It. Reset.

Eve location:

- Eve1 - Within Alice's Jamming Range but not Bob's
- Eve2 - Within Bob's Jamming Range but not Alice's
- Eve3 - Within Both Alice's and Bob's Jamming Ranges
- Eve4 - Not within Both Alice's and Bob's Jamming Ranges

Select Eve location

Security check:

- Secrecy/Reachability check - should not be reached
- Correspondence check - event 1 occurs before event 2
- Injective correspondence check - exactly one event 1 occurs before event 2

Choose a channel for monitoring:

Type a message for monitoring (optional):

Choose a channel for checking:

Type a message for checking (optional):

Automatic checking

Protocol

Soundness

- Formal Verification
- Mathematics Proofs
- Model checker from theorem prover

Efficiency

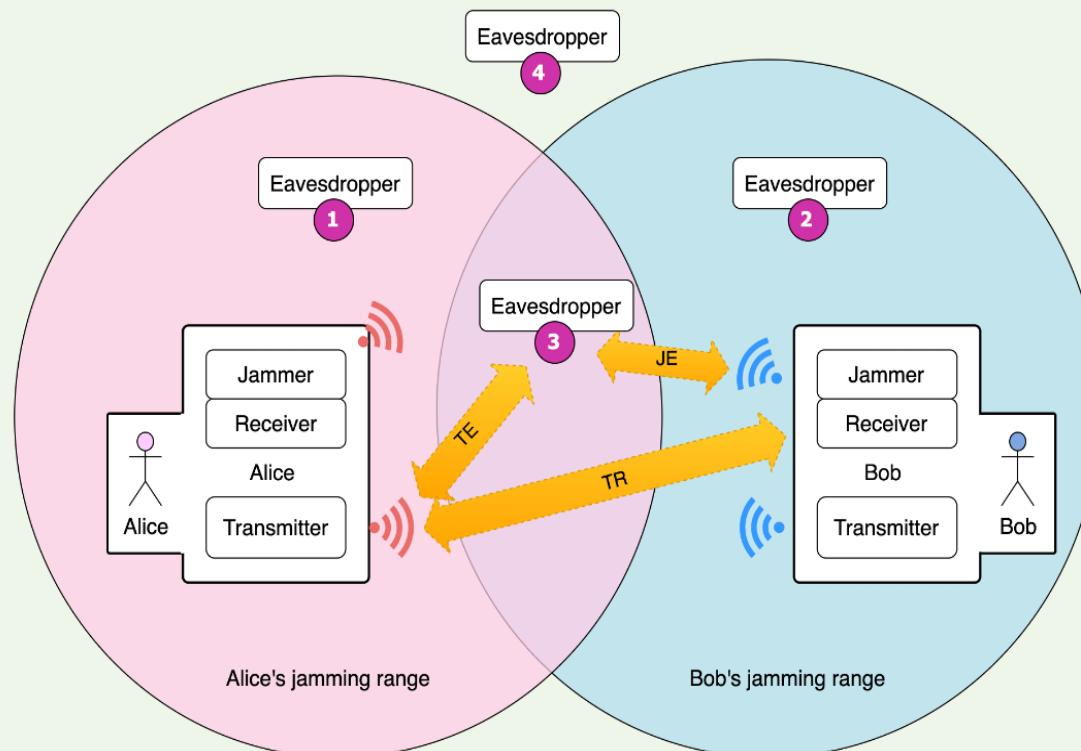
- Automatic code generation
- Manual exploration
- Automated model checking

Accessibility

- Zero-Knowledge Requirement
- User-Friendly Interfaces: Terminal + Web
- User-guided verification

Applications: PLS-based protocols

Verification of Physical Layer Security protocols using **watermarking** and **jamming** with two legitimate agents (Alice and Bob) and an eavesdropper in different spatial locations in terms of the agents' jamming ranges. There are four combinations of locations, denoted as Eve1, Eve2, Eve3, and Eve4.



Findings

Properties	NSPK	NSWJ				NSWJ Passive [†]				DH	DHWJ			
		E1	E2	E3	E4	E1	E2	E3	E4		E1	E2	E3	E4
Secrecy	○	○	○	●	○	○	○	●	○	○	○	○	●	○
Authenticity for Alice	●	●	●	●	●	●	●	●	●	○	●	●	●	●
Authenticity for Bob	○	●	●	●	●	●	●	●	●	○	●	●	●	●

- Needham-Schroeder public key protocol (NSPK) and Diffie-Hellman key exchange protocol (DH). Original versions are cryptographic and not secure.
- Their PLS versions (NSWJ and DHWJ): the secrecy relies on the Eve location, and authenticity always hold
- DHWJ now supports authentication though DH itself doesn't
- No difference between active and passive attackers

Visible Light Communication (VLC) with Reflective Intelligent Surface (RIS)-aided is a possible technology to implement the PLS to ensure Eve within the secure region.

Future interests

- Model and verify security protocols used in IoT devices in 6G
- DTLS + Zero Knowledge Proof in Thread MeshCoP
 - Ephemeral Diffie-Hellman Over COSE (EDHOC) - RFC 9528
 - Privacy
- Fully automated approach for Designers

Problems and Motivation

O-RAN: Open interfaces and AI-driven applications for real-time network optimization and energy efficiency

Challenges in balancing energy efficiency vs service availability:

Continuous, highly dynamic, and adaptive management of network resources

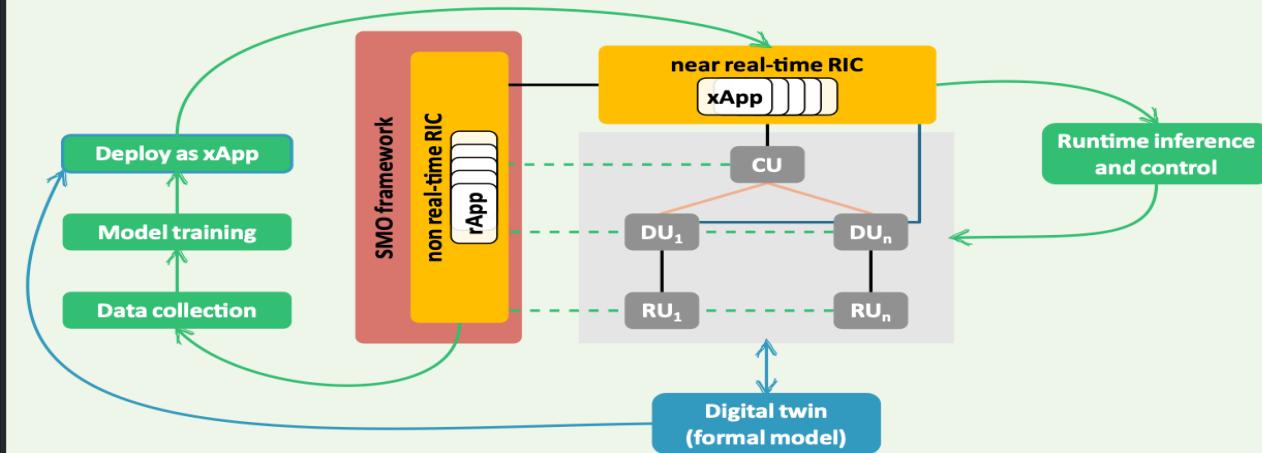
Wrong data

- Wrong adaptation to real-time changes: less efficient
- Misconfigurations

Wrong algorithms in xApps

- Logic inconsistencies

Approach: formal verification using probabilistic model checking



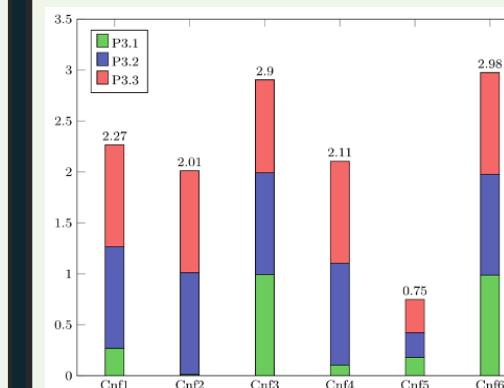
Create a small-scale **digital formal models** to verify properties before xApp deployment.

Scenario

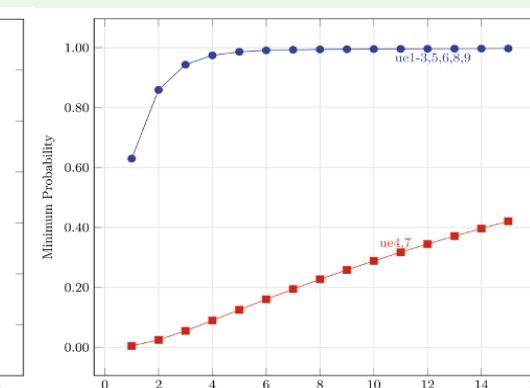
- Fixed location
 - Uncertainty: UE on and off
 - RC: On-demand dynamic switch on and off
 - Each RC has serving capacity
-

Goal: minimise the total power consumption by RCs while maintaining the QoS for each UE

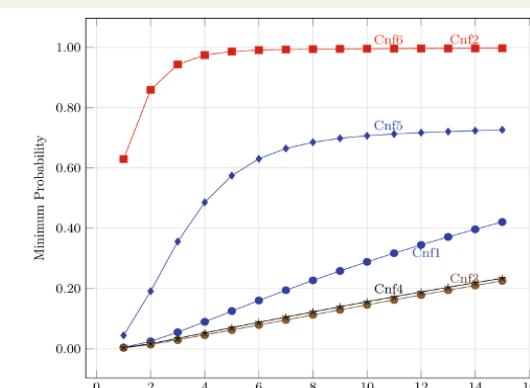
Results



Energy consumption for each RC in six configurations: capacity, uncertainty, and location differ.



The probability of a successful service connection in terms of time for each UE in a configuration



The probability of a successful service connection in terms of time for UE4 in different configurations