2021/2022 学年 第二学期《线性代数 B》试卷 A 答案(大农类专业 2 学分)

- 一、选择题: (每题3分,共18分)
- 1. D; 2. A; 3. D; 4. B; 5. C; 6. A.
- 二、填空题: (每题3分,共18分)
- 7.-1; 8. -1; 9. 1; 10. 3; 11. 2; 12. -2 < t < 1.
- 三、计算与证明
- 13. 解法一: 因为 $|A| = 6 \neq 0$, 所以 A 可逆, 因此 $X = A^{-1}B$.

$$(A|B) = \begin{pmatrix} 1 & -2 & 0 & -1 & 4 \\ 4 & -2 & -1 & 2 & 6 \\ -3 & 0 & 2 & 3 & -4 \end{pmatrix}^{r_2 - 4r_1} \begin{pmatrix} 1 & -2 & 0 & -1 & 4 \\ 0 & 6 & -1 & 6 & -10 \\ 0 & -6 & 2 & 0 & 8 \end{pmatrix}$$

$$\begin{array}{c} r_3 + r_2 \\ -3 & 0 & 1 & 6 & -10 \\ 0 & 0 & 1 & 6 & -2 \end{pmatrix}^{r_2 + r_3} \begin{pmatrix} 1 & -2 & 0 & -1 & 4 \\ 0 & 6 & 0 & 12 & -12 \\ 0 & 0 & 1 & 6 & -2 \end{pmatrix}$$

$$\begin{array}{c} \frac{1}{6} \times r_2 \\ -3 \times r_2 & -1 \times r_2 \\$$

解法二: 因为 $|A| = 6 \neq 0$, 所以 A 可逆, 因此 $X = A^{-1}B$.

$$(A|I) = \begin{pmatrix} 1 & -2 & 0 & 1 & 0 & 0 \\ 4 & -2 & -1 & 0 & 1 & 0 \\ -3 & 0 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{r} \begin{pmatrix} 1 & 0 & 0 & -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ 1 & 0 & 0 & 0 & -\frac{5}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 0 & -\frac{5}{6} & \frac{1}{3} & \frac{1}{6} \\ 0 & 0 & 1 & -1 & 1 & 1 \end{pmatrix},$$

$$\therefore A^{-1} = \begin{pmatrix} -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ -\frac{5}{6} & \frac{1}{3} & \frac{1}{6} \\ -1 & 1 & 1 \end{pmatrix}, \qquad 4$$

$$\therefore X = A^{-1}B = \begin{pmatrix} -\frac{2}{3} & \frac{2}{3} & \frac{1}{3} \\ -\frac{5}{6} & \frac{1}{3} & \frac{1}{6} \\ -1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -1 & 4 \\ 2 & 6 \\ 3 & -4 \end{pmatrix} = \begin{pmatrix} 3 & 0 \\ 2 & -2 \\ 6 & -2 \end{pmatrix}. \qquad 8$$

14. 将行列式的第2,3,4,5列都加到第1列,再按第1列展开,得

$$D_5 = \begin{vmatrix} 1 & a & 0 & 0 & 0 \\ 0 & 1-a & a & 0 & 0 \\ 0 & -1 & 1-a & a & 0 \\ 0 & 0 & -1 & 1-a & a \\ -a & 0 & 0 & -1 & 1-a \end{vmatrix} = D_4 + (-a)(-1)^{5+1}a^4 = D_4 + (-1)^5a^5,$$

于是有 $D_5 = D_4 + (-1)^5 a^5 = D_3 + (-1)^4 a^4 + (-1)^5 a^5 = D_2 + (-1)^3 a^3 + (-1)^4 a^4 + (-1)^5 a^5$ $= D_2 - a^3 + a^4 - a^5.$

15.

$$(\alpha_{1}, \alpha_{2}, \alpha_{3}, \alpha_{4}) = \begin{pmatrix} 1 & 2 & 0 & 3 \\ 2 & 0 & -4 & -2 \\ -1 & t & 5 & t+4 \\ 1 & 0 & -2 & -1 \end{pmatrix} \xrightarrow{\text{fT}} \begin{pmatrix} 1 & 2 & 0 & 3 \\ 0 & -4 & -4 & -8 \\ 0 & t+2 & 5 & t+7 \\ 0 & -2 & -2 & -4 \end{pmatrix} \xrightarrow{\text{fT}} \begin{pmatrix} 1 & 2 & 0 & 3 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 3-t & 3-t \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

(1) t=3时, $R(\alpha_1,\alpha_2,\alpha_3,\alpha_4)=2$, 故 α_1,α_2 为其一个极大线性无关组,………6分

(2)
$$t \neq 3$$
时, $R(\alpha_1, \alpha_2, \alpha_3, \alpha_4) = 3$, 故 $\alpha_1, \alpha_2, \alpha_3$ 为其一个极大线性无关组. . 8 分

16. 必要性:设 β 是任-n维向量,

$$:: \alpha_1, \alpha_2, \cdots, \alpha_n$$
 线性无关,

 $\therefore \alpha_1, \alpha_2, \cdots, \alpha_n, \beta$ 线性相关,

充分性: :: 任一n维向量都能由 $\alpha_1, \alpha_2, \dots, \alpha_n$ 线性表示,

 $\therefore n$ 维单位坐标向量组 $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n$ 可由 $\alpha_1, \alpha_2, \dots, \alpha_n$ 线性表示,

$::$ 任 $-n$ 维向量都可由 n 维单位坐标向量组 $\varepsilon_1, \varepsilon_2, \cdots, \varepsilon_n$ 线	线性表示,
---	-------

$$\therefore$$
 向量组 $\alpha_1,\alpha_2,\cdots,\alpha_n$ 可由向量组 $\varepsilon_1,\varepsilon_2,\cdots,\varepsilon_n$ 线性表示,

$$\therefore$$
 向量组 $\alpha_1,\alpha_2,\cdots,\alpha_n$ 与向量组 $\varepsilon_1,\varepsilon_2,\cdots,\varepsilon_n$ 等价,

$$\therefore R(\alpha_1, \alpha_2, \dots, \alpha_n) = R(\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n) = n,$$

17. 设存在一组数
$$x_1, x_2, x_3$$
 使得 $x_1\alpha_1 + x_2\alpha_2 + x_3\alpha_3 = \beta$,即
$$\begin{cases} x_1 + x_2 + x_3 = 1, \\ x_2 - x_3 = b, \\ 2x_1 + 3x_2 + ax_3 = 4, \\ 3x_1 + 5x_2 + x_3 = 7. \end{cases}$$

方程组的增广矩阵为:
$$\overline{A} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & b \\ 2 & 3 & a & 4 \\ 3 & 5 & 1 & 7 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & b \\ 0 & 0 & a-1 & 2-b \\ 0 & 0 & 0 & 2-b \end{pmatrix}$$
, 3 分

(1) 当
$$a \neq 1$$
且 $b = 2$ 时,增广矩阵 $\overline{A} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & a - 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$

$$R(A)=R(\overline{A})=3$$
,方程组有唯一解: $x=\begin{pmatrix} x_1\\x_2\\x_3\end{pmatrix}=\begin{pmatrix} -1\\2\\0\end{pmatrix}$,

(2) 当 $a \in R$ 且 $b \neq 2$ 时, $R(A) \neq R(A)$,方程组无解,

(3) 当
$$a=1$$
且 $b=2$ 时,增广矩阵 $\overline{A} \rightarrow \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 2 & | & -1 \\ 0 & 1 & -1 & | & 2 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$

R(A)=R(A)=2<3,方程组有无穷多解,

 β 可由 $\alpha_1,\alpha_2,\alpha_3$ 线性表示,但表示式不唯一,.

其同解方程组为
$$\begin{cases} x_1 + 2x_3 = -1, \\ x_2 - x_3 = 2, \end{cases}$$

 $\Leftrightarrow x_3 = k$, \emptyset $y_1 = -2k - 1$, $y_2 = k + 2$,

18. 二次型的矩阵为
$$A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

当 $\lambda_1 = 0$ 时,求(A - 0E)x = 0的基础解系:

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$
,同解方程组为 $\begin{cases} x_1 & -x_3 = 0 \\ x_2 = 0 \end{cases}$,

令
$$x_3=k$$
 ,则 $x_1=k, x_2=0$,得通解为 $x=\begin{pmatrix} k\\0\\k\end{pmatrix}=k\begin{pmatrix} 1\\0\\1\end{pmatrix}$,

故
$$A$$
 对应于特征值 $\lambda_1=0$ 的特征向量为 $p_1=\begin{pmatrix}1\\0\\1\end{pmatrix}$;4 分

当 $\lambda_2 = \lambda_3 = 2$ 时,求(A - 2E)x = 0的基础解系:

$$A-2E = \begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \Box \text{ \mathbb{R} \widehat{P} $$$

令
$$x_2 = k_1, x_3 = k_2$$
,则 $x_1 = -k_2$,得通解为 $x = \begin{pmatrix} -k_2 \\ k_1 \\ k_2 \end{pmatrix} = k_1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + k_2 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$,

由于 p_1, p_2, p_3 已两两正交,故只需将 p_1, p_2, p_3 单位化:

$$\diamondsuit \, Q = (e_1, e_2, e_3) = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{pmatrix},$$

则
$$Q$$
为正交矩阵,且 $Q^{-1}AQ = Q^TAQ = \Lambda = \begin{pmatrix} 0 & & \\ & 2 & \\ & & 2 \end{pmatrix}$.

作正交变换
$$x = Qy$$
,即 $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$,

经过正交x = Qy, 二次型化为:

$$f(x_1, x_2, x_3) = x^T A x = (Q y)^T A (Q y) = y^T (Q^T A Q) y = y^T \Lambda y$$

$$= (y_1, y_2, y_3) \begin{pmatrix} 0 & & \\ & 2 & \\ & & 2 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = 2y_2^2 + 2y_3^2 . \dots 12$$

19. (1)设
$$A$$
 的对应于特征值 $\lambda_2 = \lambda_3 = 1$ 的特征向量为 $p = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$,

因为A为实对称矩阵,故 $(p_1,p)=0$,即 $0x_1+x_2+x_3=0$,

$$(2) \Leftrightarrow e_1 = \frac{p_1}{\|p_1\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, e_2 = p_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, e_3 = \frac{p_3}{\|p_3\|} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix},$$

$$\diamondsuit \ Q = (e_1, e_2, e_3) = \begin{pmatrix} 0 & 1 & 0 \\ \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{pmatrix}, \quad \text{iff } Q^{-1}AQ = \Lambda = \begin{pmatrix} -1 & \\ & 1 \\ & & 1 \end{pmatrix},$$

所以 $A = Q\Lambda Q^{-1}$,

从而
$$A^{2022} = (Q \Lambda Q^{-1})(Q \Lambda Q^{-1}) \cdots (Q \Lambda Q^{-1}) = Q \Lambda^{2022} Q^{-1} = Q E Q^{-1} = E \dots 6$$