

CO2IBTECH11002

Aayush Kumar

Assignment 5

1/

a/

Mass gain in r -direction = $\frac{\partial(\rho V_r dr \pi d\theta)}{\partial r} dr$

Mass gain in θ -direction = $\frac{\partial(\rho V_\theta dr \pi d\theta)}{\partial \theta} d\theta$

Net mass gain = $\left(\frac{\partial(\rho V_r \pi)}{\pi \partial r} + \frac{\partial(\rho V_\theta)}{\pi \partial \theta} \right) \pi dr d\theta$

For steady state, incompressible flow,

Net mass gain = 0, $\rho = \text{constant}$

$$\Rightarrow \left(\frac{\partial(\rho V_r \pi)}{\pi \partial r} + \frac{\partial(\rho V_\theta)}{\pi \partial \theta} \right) \pi dr d\theta = 0$$

$$\Rightarrow \frac{\partial(V_r \pi)}{\pi \partial r} + \frac{\partial V_\theta}{\pi \partial \theta} = 0$$

$$\Rightarrow \frac{\partial V_r}{\partial r} + \frac{V_r}{r} + \frac{\partial V_\theta}{\pi \partial \theta} = 0$$

6/ In cartesian coordinates (-

$$\nabla^2 T = \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2}$$

In cylindrical coordinates;

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$\Rightarrow r = \sqrt{x^2 + y^2}$$

$$\cos \theta = \frac{x}{\sqrt{x^2 + y^2}}$$

$$\sin \theta = \frac{y}{\sqrt{x^2 + y^2}}$$

$$\frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2}} = \frac{x}{r} = \cos \theta$$

$$\frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2}} = \frac{y}{r} = \sin \theta$$

$$\text{Also, } \frac{\partial T}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial T}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial T}{\partial \theta}$$

$$\frac{\partial T}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial T}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial T}{\partial \theta}$$

$$\text{Also, } -\sin \theta \frac{d\theta}{dx} = \frac{1}{\sqrt{x^2 + y^2}} - \frac{x^2}{(x^2 + y^2)^{3/2}} = \frac{\sin^2 \theta}{r}$$

$$\Rightarrow -\frac{\partial \theta}{\partial x} = -\frac{\sin \theta}{r}$$

$$\cos \theta \frac{d\theta}{dy} = \frac{1}{\sqrt{x^2 + y^2}} - \frac{y^2}{(x^2 + y^2)^{3/2}} = \frac{\cos^2 \theta}{r}$$

$$\Rightarrow \frac{\partial \theta}{\partial y} = \frac{\cos \theta}{r}$$

$$\text{Now, } \frac{\partial^2 T}{\partial x^2} = \left(\cos \theta \frac{\partial T}{\partial r} - \frac{\sin \theta}{r} \frac{\partial T}{\partial \theta} \right) \left(\cos \theta \frac{\partial T}{\partial r} - \frac{\sin \theta}{r} \frac{\partial T}{\partial \theta} \right)$$

$$\frac{\partial^2 T}{\partial y^2} = \left(\sin \theta \frac{\partial T}{\partial \eta} + \frac{\cos \theta}{\eta} \frac{\partial T}{\partial \lambda} \right) \left(\sin \theta \frac{\partial T}{\partial \eta} + \frac{\cos \theta}{\eta} \frac{\partial T}{\partial \lambda} \right)$$

From the above two equations,

$$\boxed{\frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial x^2} = \frac{\partial^2 T}{\partial \eta^2} + \frac{1}{\eta} \frac{\partial T}{\partial \eta} + \frac{1}{\eta^2} \frac{\partial^2 T}{\partial \theta^2}}$$

2x

$$\frac{\partial T}{\partial x} = \frac{k \partial^2 T}{\partial x^2}$$

$$\Rightarrow \frac{T_i^{n+1} - T_i^n}{\Delta t} = \frac{k}{(\Delta x)^2} \left[\frac{4}{3} (T_i^n + T_{i-1}^n) - \frac{1}{12} (T_{i+2}^n + T_{i-2}^n) - \frac{5}{2} T_i^n \right]$$

$$\Rightarrow T_i^{n+1} = T_i^n + \lambda \left[\frac{4}{3} (T_i^n + T_{i-1}^n) - \frac{1}{12} (T_{i+2}^n + T_{i-2}^n) - \frac{5}{2} T_i^n \right]$$

$$\Rightarrow T_i^{n+1} = T_i^n \left(1 - \frac{5\lambda}{2} \right) + \frac{4\lambda}{3} (T_i^n + T_{i-1}^n) - \frac{\lambda}{12} (T_{i+2}^n + T_{i-2}^n)$$

$$\Rightarrow \varepsilon_i^{n+1} = \varepsilon_i^n \left(1 - \frac{5\lambda}{2} \right) + \frac{4\lambda}{3} (\varepsilon_i^n + \varepsilon_{i-1}^n) - \frac{\lambda}{12} (\varepsilon_{i+2}^n + \varepsilon_{i-2}^n)$$

Putting $\varepsilon_i^n = e^{\sigma_n t^n} e^{i k x_j}$

where $x_j = jh$, $t^n = n \Delta t$

$$\Rightarrow e^{\sigma_n \Delta t(n+1)} e^{i k j h} = e^{\sigma_n n \Delta t} e^{i k j h} \left(1 - \frac{5\lambda}{2} \right) + \frac{4\lambda}{3} \left(e^{\sigma_n n \Delta t} e^{i k (j+1) h} + e^{\sigma_n n \Delta t} e^{i k (j-1) h} \right) - \frac{\lambda}{12} \left(e^{\sigma_n n \Delta t} e^{i k (j+2) h} + e^{\sigma_n n \Delta t} e^{i k (j-2) h} \right)$$

$$\Rightarrow e^{\sigma \Delta t} = 1 - \frac{5\lambda}{2} + \frac{4\lambda}{3} (e^{ikh} + e^{-ikh}) - \frac{\lambda}{12} (e^{2ikh} + e^{-2ikh})$$

$$\left| \frac{\varepsilon_j^{n+1}}{\varepsilon_j^n} \right| = |e^{\sigma \Delta t}| < 1$$

$$\Rightarrow \left| 1 - \frac{5\lambda}{2} + \frac{4\lambda}{3} (e^{ikh} + e^{-ikh}) - \frac{\lambda}{12} (e^{2ikh} + e^{-2ikh}) \right| < 1$$

$$\Rightarrow \left| 1 - \frac{5\lambda}{2} + \frac{4\lambda}{3} 2\cos kh - \frac{\lambda}{12} 2\cos 2kh \right| < 1$$

$$\Rightarrow \left| 1 - \frac{5\lambda}{2} + \frac{8\lambda}{3} \cos kh - \frac{\lambda}{6} \cos 2kh \right| < 1$$

$$\Rightarrow \left| 1 - \frac{5\lambda}{2} + \frac{8\lambda}{3} \cos kh - \frac{\lambda}{6} (2\cos^2 kh - 1) \right| < 1$$

$$\Rightarrow \left| 1 - \frac{5\lambda}{2} + \frac{8\lambda}{3} \cos kh - \frac{\lambda}{3} \cos^2 kh + \frac{\lambda}{6} \right| < 1$$

$$\Rightarrow \left| 1 - \frac{7\lambda}{3} + \frac{\lambda}{3} (8\cos kh - \cos^2 kh) \right| < 1$$

$$\Rightarrow -2 < -\frac{7\lambda}{3} + \frac{\lambda}{3} (8\cos kh - \cos^2 kh) < 0$$

$$\Rightarrow \frac{7\lambda}{3} - \frac{\lambda}{3} (8\cos kh - \cos^2 kh) < 2$$

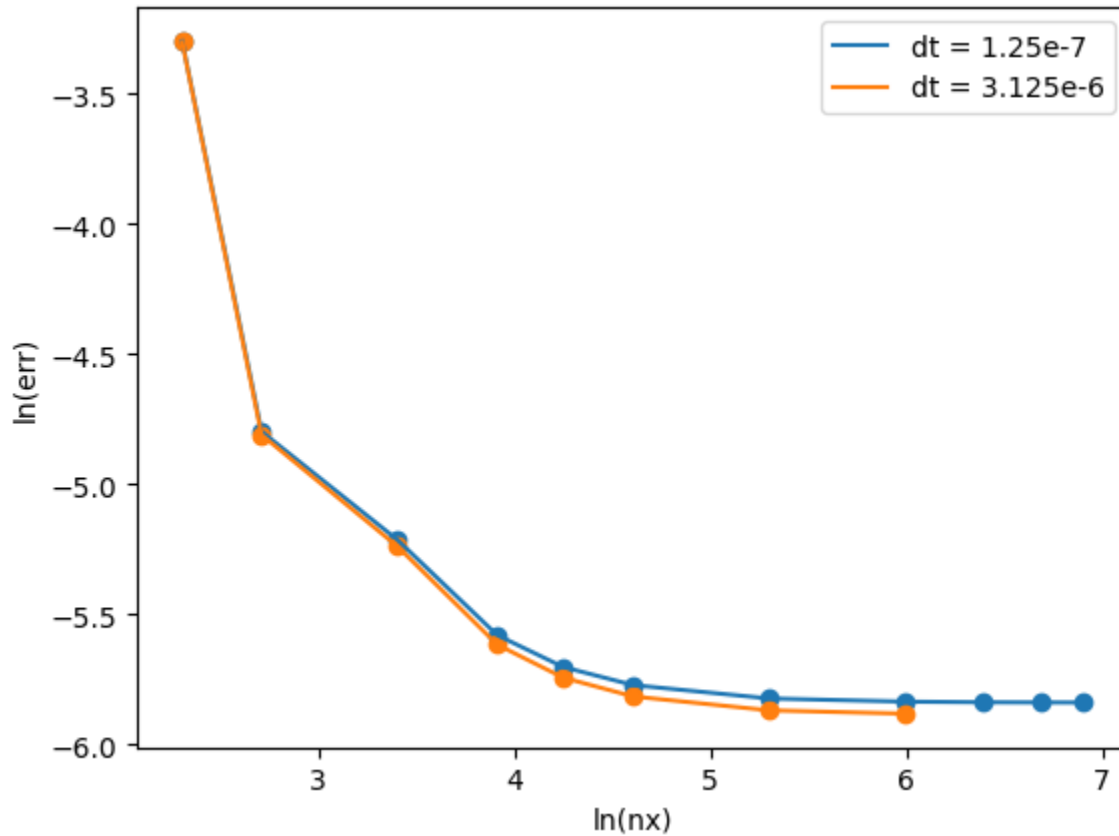
Max value of $-(8\cos kh - \cos^2 kh) = 9$
when $\cos kh = -1$

$$\Rightarrow \frac{7\lambda}{3} + \frac{9\lambda}{3} < 2 \Rightarrow \frac{16\lambda}{3} < 2$$

$$\Rightarrow \boxed{\lambda < \frac{3}{8}}$$

where $\lambda = \frac{\kappa \Delta t}{(\Delta x)^2}$

c)



Observations:

- Near the start, value of slope = -3.86 which shows that this scheme is 4th order.
- After nx becomes greater than about 100, the decrease in error almost saturates.
- For $dt = 3.125e-6$, max value of nx is 565 (from the relation $\lambda < \frac{3}{8}$). After that the solution blows up and we get inf as the error value.
- For $dt = 1.25e-7$, max value of nx is 2828. Hence, we get a complete curve till $nx = 1000$ without the solution blowing up.
- For larger value of dt , the solution has a faster convergence rate.