

# Runze Zhao

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## ABOUT

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**Research Interest:** Pose estimation, EMD, ML algorithms

**Programming Language:** Python, C, C++, MATLAB, R, Java

**Technologies:** L<sup>A</sup>T<sub>E</sub>X, Maching Learning, Mathematical Modelling, Git, Docker, MediaPipe, Webots, MMAction, ROS

## EDUCATION

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**Chinese University of Hong Kong, Shenzhen**

Shenzhen, China

*Bachelor in Financial Engineering; GPA: 3.489/4.0*

*Sep 2020 – Jul 2024*

- **Coursework:** Probability Theory, Stochastic Process, Calculus, Mathematical Modeling, Discrete Mathematics, Machine Learning, Advanced Machine Learning, Optimization in Data Science and Machine Learning, Data Structures and Algorithms, Computer Programming Paradigm
- **Honor:** Dean's list (2020-2021)
- **Scholarship:** Bowen II Scholarship (2020-2024)
- TOFEL: 110, R:30, L:27, S:24, W:29 (MyBest™ Scores)

## RESEARCH

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**Shenzhen Research Institute of Big Data (SRIBD)**

Shenzhen

*Estimation of EMD calculation for incomplete 2D and 3D images (ongoing)*

*Sept.2022 – Now*

- Summarized current computation models of EMD on point clouds and boosting algorithms for EMD.
- Compared the performance of different EMD algorithms on sparse data.
- Analyzed the computational complexity of different EMD algorithms.

**Shenzhen Research Institute of Big Data (SRIBD)**

Shenzhen

*Boosting Spectral Clustering on Incomplete Data via Kernel Correction and Affinity Learning*

*Feb.2023 – May.2023*

- Formulated an intrinsic similarity matrix by extending the self-expressive learning (SEL) model.
- Incorporated the  $\ell_p$  norm ( $0 < p < 1$ ) to further boost the SEL framework.
- Orchestrated the theoretical derivation and code implementation of proposed algorithm using optimization methods like ADMM.

## INTERN

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**Zhuhai Hanglok Interventional Robotics Co., Ltd**

Shenzhen, China

*Algorithm Intern (in field of pose estimation)*

*Aug.2023 – Now*

- Constructed a teleoperation platform that recognizes and predicts human motions in an inverse kinematics approach.
- Designed a system where the robot mimics human movements in real-time through different mapping way.
- Enabled the robot to perform predefined actions upon detecting specific human gestures.

## PROJECTS

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**Recommendation system with focus on user privacy and scalability**

Apr. 2023

- Adopt hash encryption with Laplacian noise to encode data, ensuring the customers' privacy.
- Design an algorithm to maintain prediction accuracy in a noisy data environment and handle new inputs efficiently, achieving fast computation for different dataset sizes.

**Rumor Propagation Model Based on Continuous Time Markov Chain**

Dec. 2022

- Summarized models in field of infectious deceases and the performance in field of rumor.
- Design a variant model of the SIRS model (SBRs model) and try the performance of its prediction under the continuous time Markov chain (CTMC) framework.

## PUBLICATIONS

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- [1] Fangchen Yu, **Runze Zhao**, Zhan Shi, Yiwen Lu, Jicong Fan, Yicheng Zeng, Jianfeng Mao, Wenye Li. Boosting Spectral Clustering on Incomplete Data via Kernel Correction and Affinity Learning (*NeurIPS 2023 under revision*)