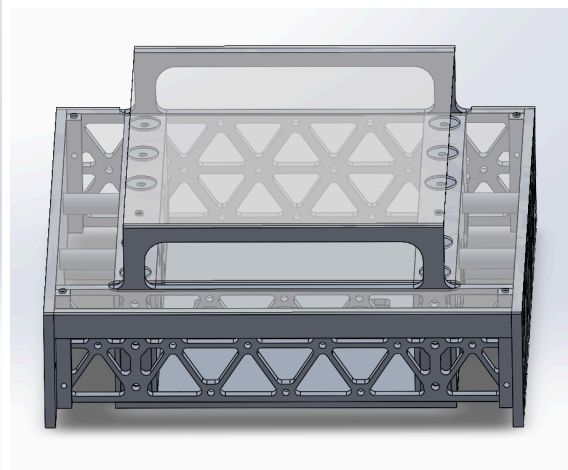
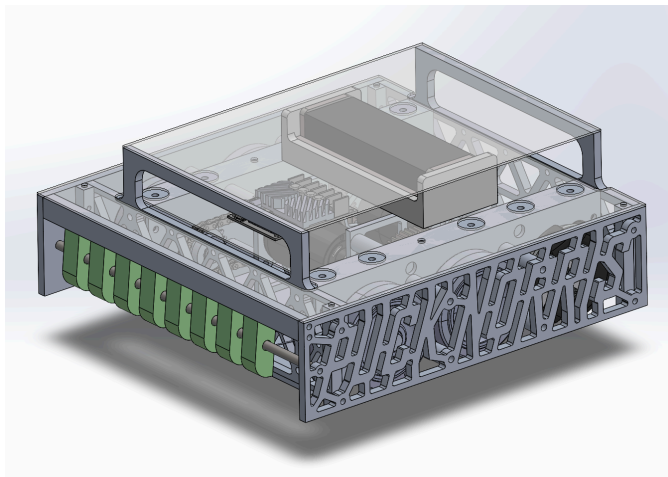


2. Upgraded battery to a 11.1V Lipo battery with 8000mAh whereas previously we had the same Lipo battery but with 5000mAh. This battery will provide enough power to continuously run each of our motors at its maximum torque requirements for 6 minutes (more time than the 5 minute rounds we compete in). The previous battery could only do this for 4 minutes.
 - a. The math for 5200 mAh:
 - i. Each motor draws 40A at their maximum torque, which creates a total maximum torque of 80A
 - ii. $5.2\text{Ah}/80\text{A} = 0.065\text{ hrs}$ or 3.9 minutes (multiplied by 60 min/1hr for conversion)
 - b. The math for 8000 mAh:
 - i. Each motor draws 40A at their maximum torque, which creates a total maximum torque of 80A
 - ii. $8.0\text{Ah}/80\text{A} = 0.1\text{ hrs}$ or 6 minutes (multiplied by 60 min/1hr for conversion)
3. The first design of the battery holder for the skater bot is ready to print on Monday when the techlab first opens.
4. Modified CAD to include brushed motors and added important details such as mounting holes and lightening patterns (skeletonization).



Technical Issues:

- When we added brushed motors to our first skater bot instead of brushless, our robot became overweight (above 15lbs). Some possible solutions include:

- **Pocketing side/front/back walls/belly pan**
- **Using thinner polycarb**
- Using thinner front/back metal walls
- Using thinner belly pan
- Milling holes/slots into the tubes
- **Pocketing gearboxes**
- **Smaller infill/thinner walls on battery holder**
- Using smaller bolts

The bolded selections were chosen.

Resources Needed:

- Submitted Order #1 - *Includes free electronic components, official puck, aluminum, magnets, and a wheel/gear/motor for subsystem tests. See the below spreadsheet for the complete list of components with suppliers.*

	MEMBERS	SUPPLIER	PART #	DESCRIPTION	QTY	INDIVIDUAL COST	SUBTOTAL	TOTAL
Team Name: Puckboiz	Alexis Herfurth Audrey Wong Kristi Sevier Kyle Chen Kyro Bastawros Randy Ngo	Amazon	B07CVDLM5R	OVONIC 3s 11.1V Lipo Battery 8000mAh 50C Deans T Connector (2 Packs)	1	FREE	FREE	\$284.65
		Amazon	12247F1	Franklin Sports NHL Street Roller Hockey Pucks - Single Puck	1	FREE	FREE	
		Amazon	B0CCX9ZJKN	Small Magnets, 30 Pack Refrigerator Magnets 20x3mm	1	\$13.99	\$13.99	
		AndyMark	am-4967	3 in. Aluminum Omni Wheel With 3/8 Hex Bore	1	\$25.00	\$25.00	
		Banebots	M7-RS775-18	RS775 Motor - 18V	1	\$17.50	\$17.50	
		BasicMicro	IMC419	RoboClaw ST 2x45A Motor Controller	1	FREE	FREE	
		McMaster	8574K38	Clear Polycarbonate Sheet 12" x 48" x 1/16"	1	\$16.75	\$16.75	
		Online Metals	1248	0.25" Aluminum Plate 6061-T651 (12" X 36")	1	\$87.82	\$87.82	
		Online Metals	1247	0.19" Aluminum Sheet 6061-T6 (12" x 12")	1	\$29.37	\$29.37	
		Online Metals	21112	0.16" Aluminum Sheet 6061-T6 (12" x 24")	1	\$52.04	\$52.04	
		Online Metals	6994	1" x 3" x 0.125" Aluminum Rectangle Tube 6061-T6-Extruded (24")	1	\$7.98	\$7.98	
		Online Metals	23284	0.5" x 2.75" Aluminum Rectangle Bar 6061-T6511-Extruded (12")	1	\$13.71	\$13.71	
		Online Metals	1112	0.375" Aluminum Square Bar 6061-T6511-Extruded (36")	1	\$5.58	\$5.58	
		Online Metals	1084	0.5" Aluminum Round Bar 6061-T6511-Extruded (24")	1	\$4.92	\$4.92	
		WCP	WCP-1150	6t Steel Spur Gear (20 DP, 8t Center Distance, RS550/775 Bore)	1	\$9.99	\$9.99	

- Planned Order #2 - Springs (puck-handling mechanism), silicon (battery holder)

Work in Progress:

1. Rethink/develop ideas for puck-handling and scoring attachments: Despite settling on a traffic spike inspired handling mechanism, we should investigate alternative methods (in case a shooting mechanism can be developed) or devise a simple solution in case the puck-handling mechanism doesn't meet our expectations.
2. Submit Order #2 - Once we measure the depth of the puck indentation, we can form a clearer picture of the feasibility of our puck-handling mechanism. If we decide the indentation is deep enough to try prototyping the mechanism, we will submit an order for torsion springs.
3. Redesign the electronic circuit - with the original brushless motor now being switched to a brushed motor, we will have to switch out some specific brushless motor components like an ESC for brushed motor components like a RoboClaw.
4. Create GD&T drawings: Before we start machining, we will take our CAD models (once they are finalized) and make official drawings.
 - a. Relating to this, we will also lay out where each part is cut on our sheet metal so that they are arranged in the most space-efficient manner possible, minimizing wasted metal.
5. Divide Gantt chart tasks among team members and include more specific deadlines.