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# General Linear Model — 3 — Residual Analysis



Sandeep Sharma · [Follow](#)

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*A residual is a measure of how far away a point is vertically from the regression line. In simple words, difference between actual and predicted value.*

Residual is a diagnostic measure used when assessing the quality of a model. They are also known as errors.

# What is a Residual?

- Formula:

Residual = Observed value - Predicted value

$$e = y - \hat{y}$$

- Tells us how far off our prediction is
- Tells us if our prediction was too high or too low
- Both the sum and the mean of the residuals are equal to zero

**We can check the assumptions of regression by examining the residuals**

*Examine for linearity assumption (Linearity)*

*Evaluate independence assumption (Independence of errors)*

*Evaluate normal distribution assumption (Normality of errors)*

Examine for constant variance for all levels of  $X$  (**homoscedasticity/ Equal variance**)

**Linearity:** The relationship between  $x$  and  $y$  must be linear. Check this assumption by examining a scatterplot of  $x$  and  $y$ .

**Independence of errors:** There should not a relationship between the residuals and the predicted values. We can check this assumption by examining a scatterplot of “residuals versus fits”. The correlation should be approximately 0.

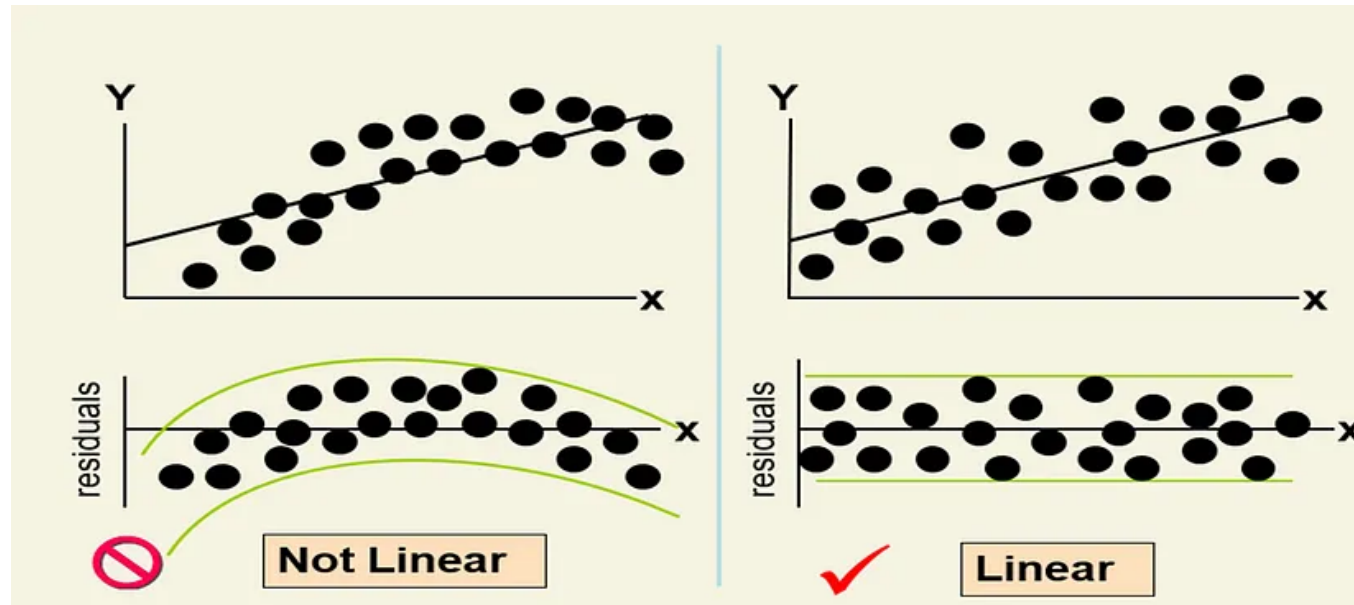
**Normality of errors:** The residuals must be approximately normally distributed. We can check this assumption by examining a normal probability plot.

**Equal variances:** The variance of the residuals should be consistent across all predicted values. We can check this assumption by examining the scatterplot of “residuals versus fits”.

## **Residual Analysis for Linearity**

A residual plot is a graph that shows the residuals on the vertical axis and the independent variable on the horizontal axis. If the points in a residual plot are

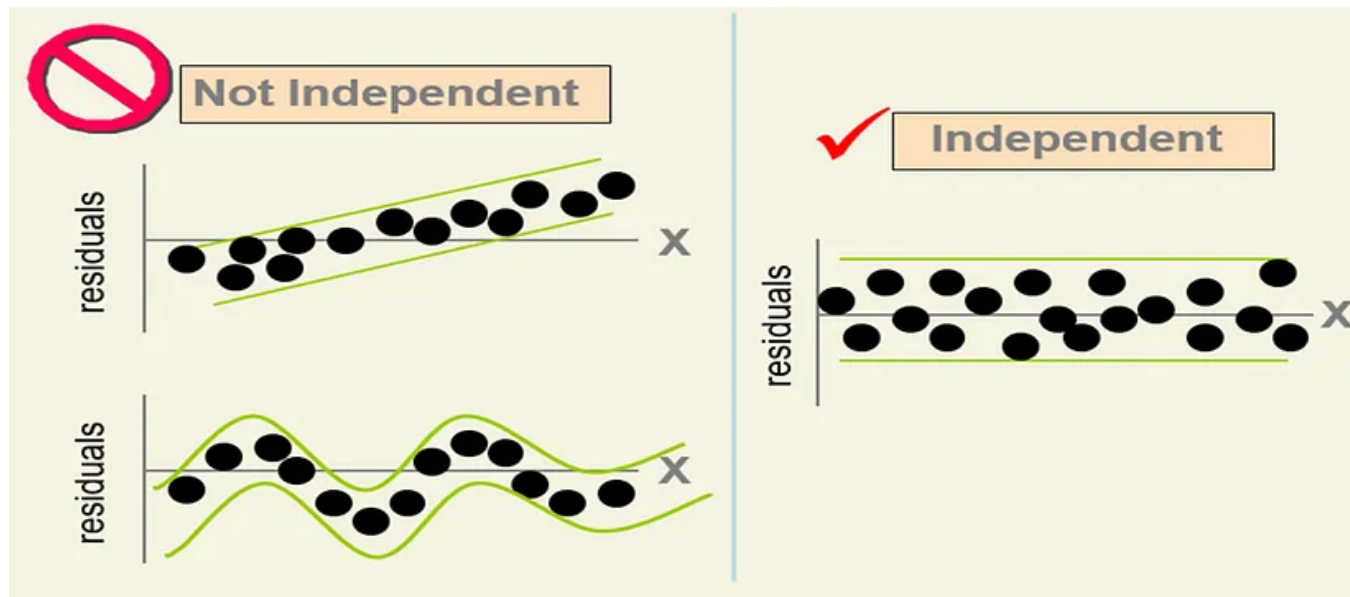
*randomly dispersed around the horizontal axis, a linear regression model is appropriate for the data; otherwise, a nonlinear model is more appropriate.*



Linear and Non-Linear

## Residual Analysis for Independence

*we can plot the residuals vs. the sequential number of the data point. If we notice a pattern, we say that there is an autocorrelation effect among the residuals and the independence assumption is not valid.*



## Residual Analysis for Independence — Another Method — Durbin Watson (D-W) Statistics

It's the sum of the squares of the differences between consecutive errors divided by the sum of the squares of all errors.

Another way to look at the Durbin-Watson Statistic is:  $D = 2(1-\rho)$   
where  $\rho$  = the correlation between consecutive errors.

*There are 3 important values for D:*

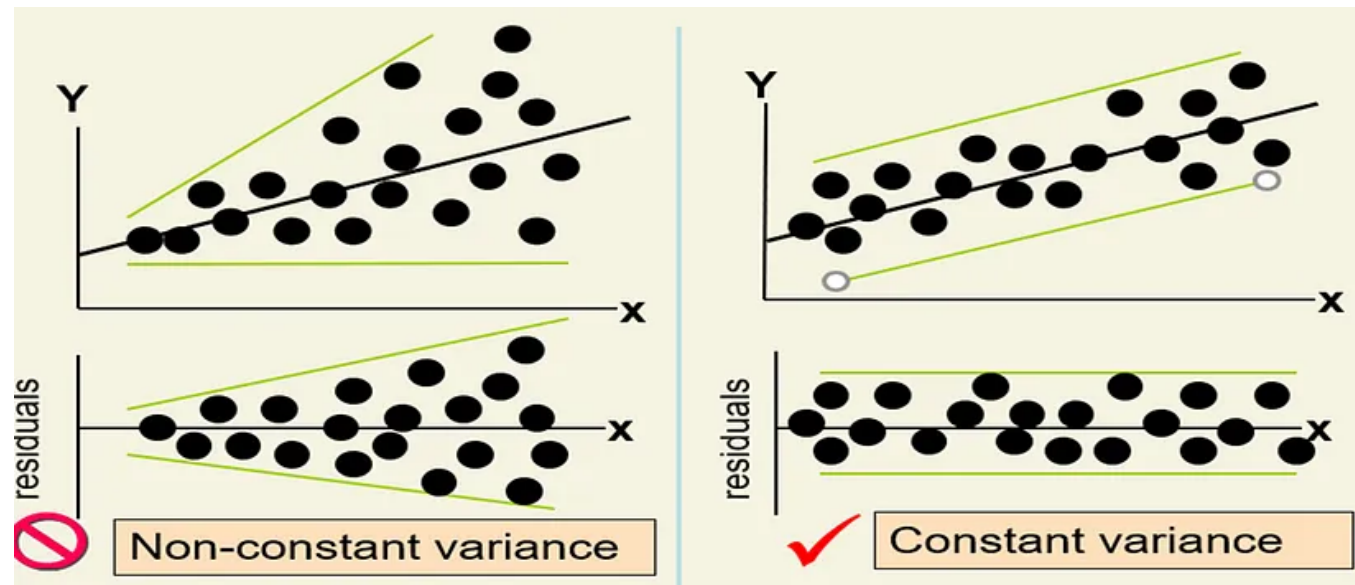
*D=0: This means that  $\rho=1$ , indicating a positive correlation.*

$D=2$ : In this case,  $\rho=0$ , indicating no correlation.

$D=4$ :  $\rho=-1$ , indicating a negative correlation

## Residual Analysis for Equal Variance

1. White test statistics
2. Residual vs fitted value plot



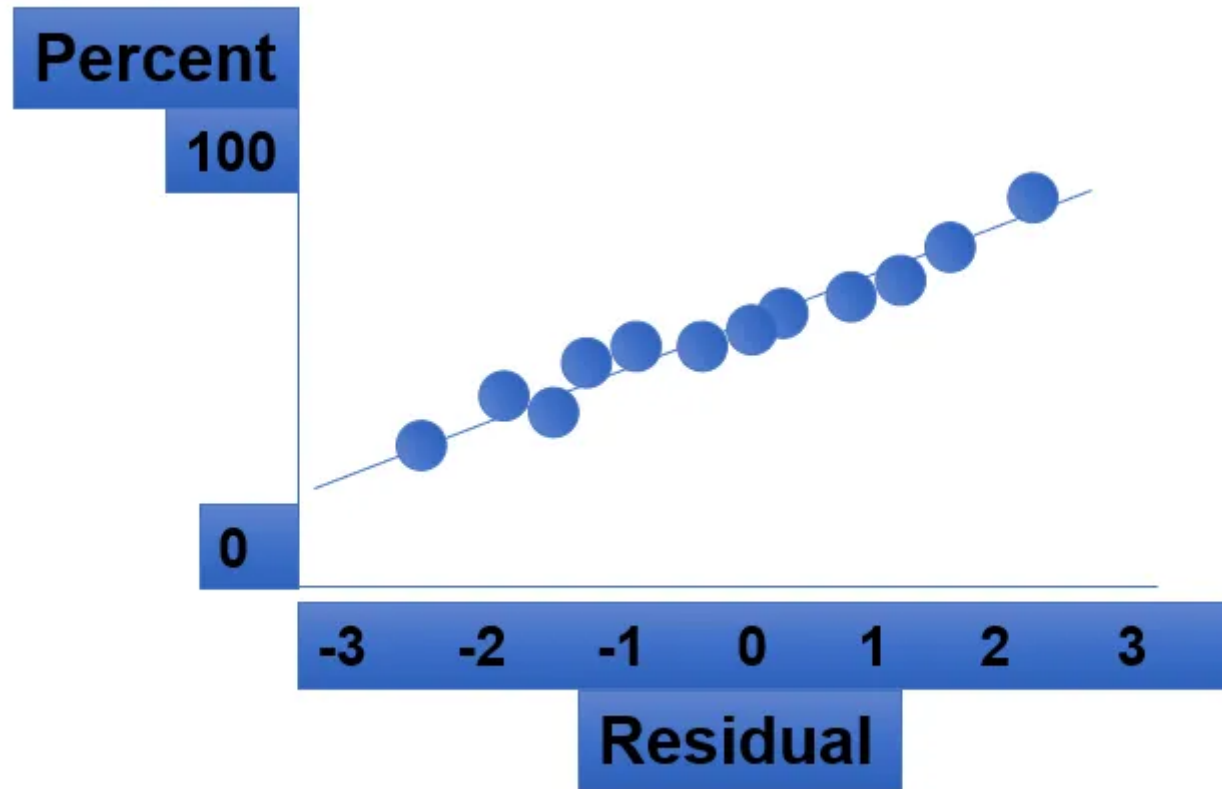
## Checking for Normality

1. Examine the Stem-and-Leaf Display of the Residuals.

2. Examine the Boxplot of the Residuals
3. Examine the Histogram of the Residuals
4. Construct a Normal Probability Plot of the Residuals

### **Residual Analysis for Normality**

When using a normal probability plot, normal errors will approximately display in a straight line.



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ikov:  $K(\cdot) = \frac{3}{4}(1 - d^2)$ ,  $d^2 < 1$ ,  $0$   
var:  $K(\cdot) = \frac{3}{8}(1 - 5d^2)$ ,  $d^2 < 1$ ,  $0$   
density:  $\exp(-\frac{x-x_i}{h})$   
inction:  $W(z) = (1 - |z|^3)^3$  for  $|z|$



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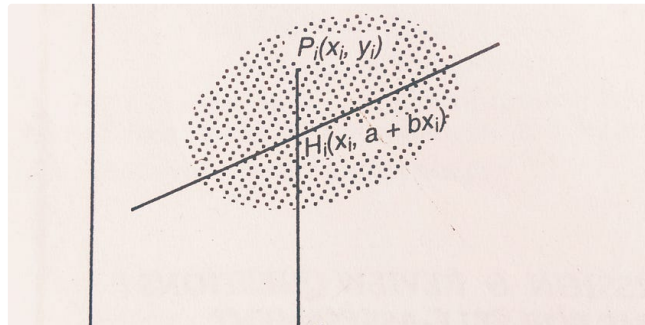
ID3 = Iterative Dichotomiser 3

- given a goal class to build the tree for
- create a root node for the tree
- if all examples from the test set belong to the same goal class C then label the root with C
- else
  - select the 'most informative' attribute A
  - split the training set according to the values  $V_1 \dots V_n$  of A
  - recursively build the resulting subtrees  $T_1 \dots T_n$
  - generate decision tree T:

A1=weather	A2=day	happy
sun	odd	yes +
rain	odd	no -
rain	even	no -
sun	even	yes +
rain	odd	no -
sun	even	yes +

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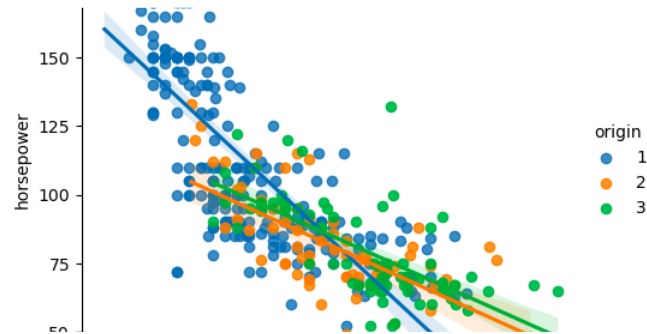
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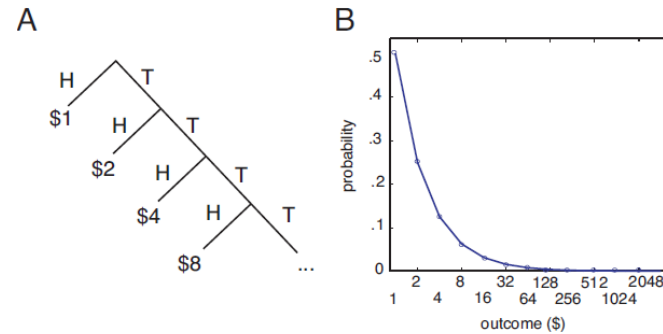
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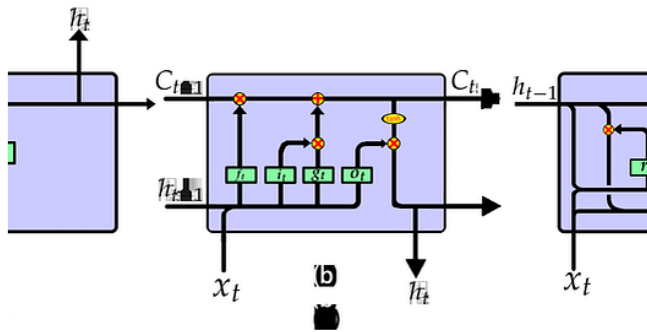
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


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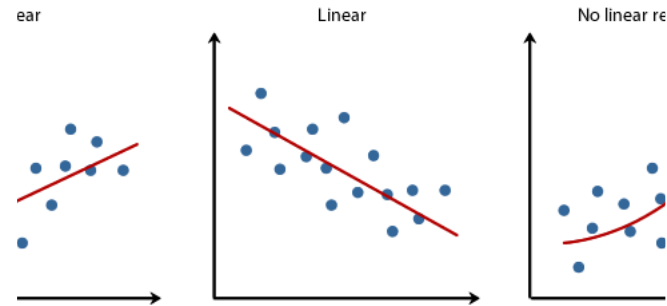
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