nang, Nepal

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in <u>linkedin.com/Ranish-Devkota</u>

github.com/Ranish-Devkota

<u>ranishdevkota.com.np</u>

EDUCATION

Bachelor's degree in Electronics Communication and Information Engineering | NOV, 2018 – AUG, 2023 **TRIBHUWAN UNIVERSITY, INSTITUTE OF ENGINEERING (IOE)**

RANISH DEVKOTA

EASTERN REGIONAL CAMPUS(ERC)

Dharan, Nepal

WORK EXPERIENCES

Research & Development Engineer | June, 2023 - Present

Orion Space PTV. LTD., Kathmandu, Nepal

- Embedded System, Communication system and Electrical Power Subsystem design of PocketQube.
- Sensor interfacing, Deconstruction and Testing for Pico/Nano satellites.
- Firmware & Mission design for Low Voltage / High Frequency systems and Testing.

Undergraduate Researcher | JAN, 2020 - MAY, 2023

Robotics Club, IOE Purwanchal Campus

Supervisor Asst. Prof. Deependra Neupane

- Control and Dynamics of Two wheeled Robot.
- System identification and Mathematical modelling.
- Computer Vision and Robot Perception with ROS
- Involved in Other Projects like Robotic arm, Drone Control systems, CNC Machines etc.

PUBLICATIONS

Baskota, G., Devkota, R., Paneru, S., Yadav, S., Neupane, D., Dhakal, O.

Analytical and Experimental Approach for Modeling, Simulation and Validation of Two-Wheeled Self-Balancing Robot 2023 ICICT, IEEE.

Paneru, S., Yadav, S., **Devkota, R.**, Baskota, G., Guragai, M. K., Dhakal, O. P., Neupane P., Shrestha, A.

Mapping and Localization of Mobile Robot with Monocular Camera Using VSLAM.

Int. J. Adv. Engr. 2023, 6(2), pp.24-36.

PRESENTATIONS

- Analytical and Experimental Approach for Modeling, Simulation and Validation of Two-Wheeled Self-Balancing Robot. | ICICT 2023
- Comparison of Controls for Two wheeled Robots | DELTA 2020
- PCB Designing and Fabrication Process. | YARSA 2023
- Al and IOT in Agriculture. | DELTA 2020

TECHNICAL SKILLS

Embedded System Design, Control System Design, Robotics & IOT, Satellite System Design, Robot Perception & Machine Vision, Signal Analysis and Processing.

Software: Robot Operating system (ROS), MATLAB/Simulink, KiCad, Fusion360, GNU Radio & HFSS

Programming: C/C++, Python

Others: Linux, Git/Version Control

PROJECTS AND RESEARCHS

Design and Development of fully functional PocketQube for Nepal (SANOSAT-2). | Ongoing (Orion's Funding)

Upgrade on SANOSAT-1.

Mathematical Modelling, Simulation and Validation of Permanent Magnet DC Motor

• Second Order Modelling of Cheap PMDC for Robot.

Modelling, Simulation and Validation of Two Wheeled Self-Balancing Robot

Control system design and mathematically modelling of the robot along with all its components

Mapping and Localization of Mobile Robots with Monocular Camera using V-SLAM.

Implemented SLAM in fabricated robot with monocular USB camera.

Autonomous multi-colored line follower and Maze Solver robot

• Multi-colored wall-line maze solver robot with camera assistance for decoding information

Firmware development for environmental sensing iot system.

Developed C++ Firmware with implementation of MQTT protocol as well as energy saving mode.

Vegetable Grading Machine

 Developed a computer vision algorithm and robotic systems for grading and categorizing different sizes of vegetables, in collaboration with Swiss-contact's SAHAJ Project and DELTA 3.0.

HONOURS & AWARDS

- First Runner Up in Model Based simulation using MATLAB/SIMULINK at DELTA 2.0 | 2021
- Winner of Yantra 8.0 Automatic Akhada (Autonomous path solving Robo on Raspberry Pi) | 2020
- First Runner up in Robo race at VECTOR 2.0 | 2020
- Winner on Robo War & Robo Race at PRAYOG EXPOSITION | 2019

NOTEABLE LEARNING

KARI International Space Training 2023 | 11 SEPT – 15 SEPT, 2023

Korea Aerospace Research Institute

· Gained insights into satellites, satellite system engineering, orbital mechanics, and more

SEEDS FOR THE FUTURE | 29 NOV - 6 DEC 2021

NEPAL'S FIRST SEEDS FOR FUTURE PROGRAM BY HUAWEI

Learned about 5G, AI, Cloud technologies, and developed Tech for Good projects.

Deep Learning Specialization | 15 JUL – 29 AUG, 2020

Deeplearning.AI

• Studied foundations of deep learning, neural networks, CNNs, and sequential models like Hyper Parameter tuning, Regularization and Optimization.

VOLUNTEERING & LEADERSHIP

Event Coordinator | Jan 11 -- Jan 13, 2023

X-Tech Studio 3.0

Advisor | Jun 2022- Mar 2023

ELECTRONICS & COMMUNICATION ENGINEERING STUDENT SOCIETY(EXCESS)

Secretary | Jun 2021- Jun 2022

ELECTRONICS AND COMMUNICATION ENGINEERING STUDENT SOCIETY(EXCESS)

Member | Sep 2020 - Present

ROBOTICS ASSOCIATION OF NEPAL (RAN)

Member | Sep 2018 - June, 2023

ROBOTICS CLUB, IOE PURWANCHAL CAMPUS

REFERENCES

Asst. Prof. Deependra Neupane

HOD, Department of Electrical Engineering Institute of Engineering, Eastern Regional Campus deependra@ioepc.edu.np

Asst. Prof Pukar Karki

DHOD, Department of Electronics & Computer Engg. Institute of Engineering, Eastern Regional Campus pukar@ioepc.edu.np