Assignment 3

CSC 8260 – Advanced Image Processing

Due Date: February 24th Friday, 2023, 11:59 pm

Q1. As the figure below shows the Fourier transform of a tent function(on the left) is a squared sinc function(on the right). Advance an argument that shows that the Fourier transform of a tent function can be obtained from the Fourier transformation of a box function. (Hint: The tent itself can be generated by convolving two equal boxes.)



- Q2. What is the convolution of two 1-D impulses:
 - a. $\delta(t)$ and $\delta(t-t_0)$
 - b. $\delta(t-t_0)$ and $\delta(t+t_0)$
- Q3. Show that $\Im\{e^{j2\pi t_0 t}\}=\delta(\mu-t_0)$, where t0 is a constant. (Hint: Study Example 4.2 to be followed from textbook, pasting sample below for reference)

EXAMPLE 4.2: Fourier transform of an impulse and an impulse train.

The Fourier transform of a unit impulse located at the origin follows from Eq. (4-20):

$$\Im\{\delta(t)\} = F(\mu) = \int_{-\infty}^{\infty} \delta(t) e^{-j2\pi\mu t} dt = \int_{-\infty}^{\infty} e^{-j2\pi\mu t} \delta(t) dt = e^{-j2\pi\mu}$$

where we used the sifting property from Eq. (4-12). Thus, we see that the Fourier transform of an impulse located at the origin of the spatial domain is a constant in the frequency domain (we discussed this briefly in Section 3.4 in connection with Fig. 3.30).

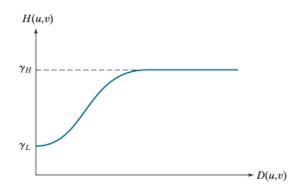
Similarly, the Fourier transform of an impulse located at $t = t_0$ is

$$\Im\{\delta(t-t_0)\} = F(\mu) = \int_{-\infty}^{\infty} \delta(t-t_0) e^{-j2\pi\mu t} dt = \int_{-\infty}^{\infty} e^{-j2\pi\mu t} \, \delta(t-t_0) dt = e^{-j2\pi\mu t_0}$$

- Q4. Show that the following expressions are true. (Hint: Make use of the solution to Problem Q3):

 - a. $\Im\{\cos(2\pi\mu_0 t)\} = \frac{1}{2} [\delta(\mu \mu_0) + \delta(\mu + \mu_0)]$ b. $\Im\{\sin(2\pi\mu_0 t)\} = \frac{1}{2i} [\delta(\mu \mu_0) \delta(\mu + \mu_0)]$
- Q5. Use a Butterworth highpass filter to construct a homomorphic filter transfer function that has the same general shape as the function in Fig. 4.59.

Radial cross section of a homomorphic filter transfer function..



Q6. Highpass fiter transfer functions

- a. Write a function H = hpFilterTF4e(type, P, Q, param) to generate a P X Q high pass filter transfer function, H, with the following properties, If type = 'ideal', param should be a scalar equal to the cut-off frequency D_0 in Eq. (4-119). If type = 'gaussian', param should be a scalar equal to the standard deviation D_0 , in Eq(4-120). If type = 'butterworth', param should be a 1x2 array (vector) the cutoff frequents and filter order, $[D_0, n]$, in Eq (4-121)
- b. Generate an ideal highpass filter transfer function of size 512×512 with $D_0 = 96$. Display your result as an image.
- c. Generate a highpass Gaussian filter transfer function of size 512×512 with $D_0 = 96$. Display your result as an image.
- d. Generate a highpass Butterworth filter transfer function of size 512×512 . Choose $D_0 = 96$ and n = 2.

IDEAL, GAUSSIAN, AND BUTTERWORTH HIGHPASS FILTERS FROM LOWPASS FILTERS

As was the case with kernels in the spatial domain (see Section 3.7), subtracting a lowpass filter transfer function from 1 yields the corresponding highpass filter transfer function in the frequency domain:

$$H_{\rm HP}(u,v) = 1 - H_{\rm LP}(u,v)$$
 (4-118)

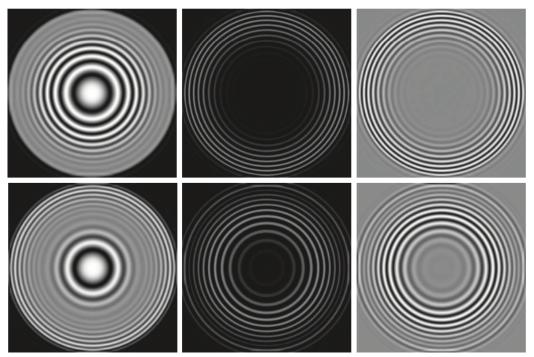
where $H_{\rm LP}(u,v)$ is the transfer function of a lowpass filter. Thus, it follows from Eq. (4-111) that an ideal highpass filter (IHPF) transfer function is given by

$$H(u,v) = \begin{cases} 0 & \text{if } D(u,v) \le D_0 \\ 1 & \text{if } D(u,v) > D_0 \end{cases}$$
 (4-119)

The above equation is referred in 4th edition. Use below image to find the equations in other editions of textbook.

- Q7. Lowpass filtering in the frequency domain. Show the image resulting after each of the following:
 - a. Read the image testpattern512.tif and lowpass filter it using a Gaussian filter so that the large letter "a" is barely readable, and the other letters are not.

- b. Read the image testpattern512.tif. Lowpass filter it using a Butterworth filter of your specification so that, when thresholded, the filtered image contains only part of the large square on the top, right. (Hint: It is more intuitive to work with the negative of the original image.)
- Q8. The objective of this project is to duplicate the results in below using frequency domain filtering. The image used is zoneplate.png. [5]For consistency scale the intensity range of this image to [0,1] using MATLAB function im2double or project function intScaling4e with the default setting. To simplify experimenting, do the filtering without padding. (Hint: To separate frequency bands requires filters with sharp cutoffs, so use Butterworth filter transfer functions with n = 3 [Left throughout.)



Extra Credit

- Q1. Show the validity of the following 2-D discrete Fourier transform pairs from Table 4.4 of textbook(check the below screenshot of the table from 4th edition and refer with the one in your textbook)
 - a. $\delta(x,y) \Leftrightarrow 1$

 - b. $1 \Leftrightarrow MN\delta(u,v)$ c. $\delta(x-x_0,y-y_0) \Leftrightarrow e^{-j2\pi(\frac{ux_0}{M} + \frac{vy_0}{N})}$ d. $e^{j2\pi(\frac{ux_0}{M} + \frac{vy_0}{N})} \Leftrightarrow MN\delta(u-u_0,v-v_0)$ e. $\cos(\frac{2\pi u_0x}{M} + \frac{2\pi v_0y}{N}) \Leftrightarrow (MN/2) [\delta(u+u_0,v+v_0) + \delta(u-u_0,v-v_0)]$

$$\text{f.} \quad \sin{(\frac{2\pi u_0 x}{M} + \, \frac{2\pi v_0 y}{N})} \Leftrightarrow (jMN/2) \left[\delta(u + u_0, v + v_0) - \delta(u - u_0, v - v_0)\right]$$

	Name	DFT Pairs
1)	Symmetry properties	See Table 4.1
2)	Linearity	$af_1(x,y) + bf_2(x,y) \Leftrightarrow aF_1(u,v) + bF_2(u,v)$
3)	Translation (general)	$f(x,y)e^{j2\pi(u_0x/M+v_0y/N)} \Leftrightarrow F(u-u_0,v-v_0)$ $f(x-x_0,y-y_0) \Leftrightarrow F(u,v)e^{-j2\pi(ux_0/M+vy_0/N)}$
4)	Translation to center of the frequency rectangle, $(M/2, N/2)$	$f(x,y)(-1)^{x+y} \Leftrightarrow F(u-M/2,v-N/2)$ $f(x-M/2,y-N/2) \Leftrightarrow F(u,v)(-1)^{u+v}$
5)	Rotation	$f(r,\theta+\theta_0) \Leftrightarrow F(\omega,\varphi+\theta_0)$ $r = \sqrt{x^2 + y^2} \qquad \theta = \tan^{-1}(y/x) \qquad \omega = \sqrt{u^2 + v^2} \qquad \varphi = \tan^{-1}(v/u)$
6)	Convolution theorem [†]	$f \star h)(x,y) \Leftrightarrow (F \cdot H)(u,v)$ $(f \cdot h)(x,y) \Leftrightarrow (1/MN)[(F \star H)(u,v)]$

Q2. Consider the images shown. The image on the right was obtained by: (a) multiplying the image on the left by $(-1)^{X+y}$; (b) computing the DFT;(c) taking the complex conjugate of the transform; (d) computing the inverse DFT; and (e) multiplying the real part of the result by $(-1)^{X+y}$. Explain (mathematically) why the image on the right appears as it does.

