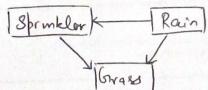
## Explanation ?

Given detaset A & dataset B & the graphical Model Now we must use the Dataset A to train the graphical model to estimate the probabilities in the cond probability table.

When we consider the Bayesian belief Network, Nodes "in the graph are treated as "Variables", "Arrows "refresent the "dependence of variables".

-> Given graphical model is



from this graph, we can observe that "Rain" is the root node (check the arrows) & it is independent.

Child Nodes are sprukler of Grass which are @ dependent on Rain, El if we consider Grass it is also a child of sprukler el is dependent on.

→ Let us consider Pataset A

Model /varible "Rain":-

In the Rain column, the Data Contains

-: Probability for Ram P(Rain= Yes) = 4/16 = 0.25 P(Rain= No) = 12/16 = 0.75

Similarly Consider

Sprinkler: Here sprinkler is a defendant of Rain, so the conditional brobilities considered will be as follows:

Check all the remains probabilities:

Similarly, Calculate the conditional probabilities for Grass . Since Gress is dependent on Both sprimkler & Rain check it for both.

$$P(6rass = Wet | sprinkler = No, Rain = Yes) = (4/16) = 4/5 = 0.80$$

Trom the above calculated conditional probabilities the Joint Probability Distribution is given as follows:

Rown	P(Sprinkler) Yes No	Sprinkler   Rain
Yes	0.25 075	
No	0.42 0.58	
		(Grass)

P(Rain)		
0.25		
0.75		

314 5000		P(G1988)	
Sprinkle	ar Rowin	Wet	Pry
Yes	Yes	1	0
Yes	No	0.67	0.33
No	Yes	0.30	020
No	No.	0	

Orckeall the renamy probabilities