## **Assignment 3 - report - Soft Computing**

Mtech - 2nd Sem

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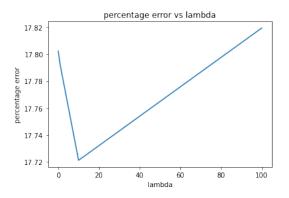
**IIIT Allahabad** 

### edit google collab link for code

# **CLICK HERE**

#### problem 1a

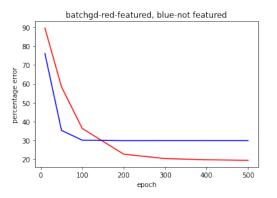
plot of percentage error wrt to lambda



- 1. lambda = 10,we will get best model with percentage error in prediction 17.7211
- 2. however for no regulization i.e lambda = 0, error percentage is 17.802
- 3. so after regulization we get better model

#### problem 1b - batch gradient decent

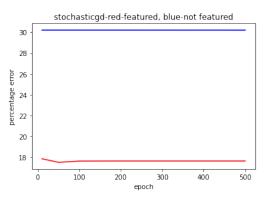
hyperparameters [no-train = 382, no-test = 163, alpha-normal = 0.000000001, alpha-featured = 0.01, ]



- we will get a better model after feature scaling as the model converges to 18.2 percentage error
- 2. so we can conclude that after feature scaling performance of gradient decent increases

#### problem 1b - stochastic gradient decent

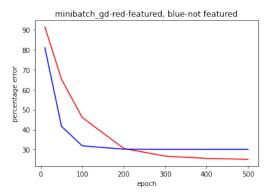
hyperparameters [no-train = 382, no-test = 163, alpha-normal = 0.000000001, alpha-featured = 0.01 ]



- we will get a better model after feature scaling as the model converges to 17.8
  percentage error
- 2. so we can conclude that after feature scaling performance of stochastic gradient decent increases and convergence is faster

#### problem 1b - minbatch gradient decent

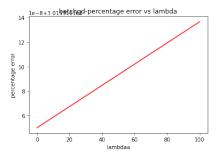
hyperparameters [no-train = 382, no-test = 163, alpha-normal = 0.000000001, alpha-featured = 0.01, batch-size = 100 ]



- we will get a better model after feature scaling as the model converges to 24.44
  percentage error
- 2. so we can conclude that after feature scaling performance of stochastic gradient decent increases and convergence is faster

#### problem 1c - gradient decent

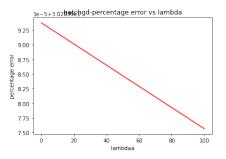
hyperparameters [no-train = 382, no-test = 163, alpha= 0.000000001, lambda = [0, 0.1, 1, 10, 100]]



- adding regulization only leads to more time complexity and doesnt yeild good results
- $\begin{array}{lll} 2. & \text{even after regulization percentage errors doesnt change much. for lambda} = & [0, \\ 0.1, 1, 10, 100] & \text{percentage error} = & [30.153101050116145, 30.153101050202512, \\ 30.153101050979718, 30.153101058752014, 30.153101136474838] \\ \end{array}$

#### problem 1c -stochastic gradient decent

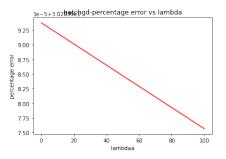
hyperparameters [no-train = 382, no-test = 163, alpha= 0.000000001, lambda =[0, 0.1, 1, 10, 100]



- adding regulization only leads to more time complexity and doesnt yeild good results
- 2. even after regulization percentage errors doesnt change much. for lambda =[0, 0.1, 1, 10, 100] percentage error = [30.203993775198366, 30.203993757100566, 30.203993594220297, 30.203991965400824, 30.203975675525893]

#### problem 1c -mini batch gradient decent

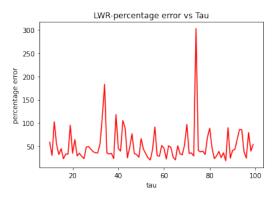
hyperparameters [no-train = 382, no-test = 163, alpha= 0.000000001, lambda =[0, 0.1, 1, 10, 100]



- adding regulization only leads to more time complexity and doesnt yeild good results
- 2. even after regulization percentage errors doesnt change much. for lambda =[0, 0.1, 1, 10, 100] percentage error = [31.892907662751604, 31.89290766345898, 31.892907669825433, 31.8929077334899, 31.892908370134418]

#### problem 1d -LWR algorithm

hyperparameters [no-train = 382, no-test = 163, alpha= 0.000000001]



- 1. lowest percentage error is = 18.842937027158193 for tau value = 87
- model with normal equations (problem 1a) works better than this model remaining all models (problem 1b,problem 1c) works poorly comparitive to this model

10/10