AMIT SHARMA

Objective

An Embedded Software, ML, IOT, Robotics, Computer Vision and Python Developer enthusiast looking for an opportunity to learn, practice and work for an organization.

EDUCATIONAL QUALIFICATION

Examination	University/Board (Location)	Year	CPI/%
M.Des. (Electronic Systems)	IIITDM (Kancheepuram)	2018	8.25
B.Tech (Instrumentation and Control Engineering)	GCET (Greater Noida)	2014	65.24%
HSC	Pragati College of Science (Dombivali East)	2008	60%
SSC	R. C. Maruti High School (Andheri East)	2006	80.40%

INTERNSHIPS

Research Inter - Ericsson Global Services, Chennai, India

4th Dec, 2017 - 31 Aug, 2018

- IoT based Human Monitoring System
- IoT base indoor plant monitoring.
- Path planning in Mobile Robot using A* search algorithm
- Preparation of image dataset for building, testing and deploying a CNN based image classification on Raspberry Pi
- Development of cognitive system of a mobile robot autonomous navigation in an indoor environment using Reinforcement Learning and Deep Learning

CERTIFICATIONS

Certification in DAT257x: Reinforcement Learning Explained offered by Microsoft on EDX

Django 2 & Python: The Ultimate Web Development Bootcamp by Nick
Walter on Udemy

TECHNICAL SKILLS

Languages: Python, C++, Java, Scala, C, Data Structure and
Algorithms

Embedded System: GPIOs, I2C, UART, Interrupts, ADC, DAC, SPI, CAN, TCP/IP, Bluetooth, ZigBee, LoRa, Wi-Fi, RTOS, Embedded Linux

Hardware Modules: Tiva C, ST32, Raspberry Pi, Arduino, DC Motor, Stepper Motor, Ultrasonic Distance Sensor, IR-Sensors, LCD Screen, Servo Motor, ESC, BLDC, NB-IoT, Sensor Modules, RP-LIDAR

Python Modules: Django, Numpy, Scipy, Matplotlib, Tensorflow, Pandas, Keras, OpenCV, TkInter, wxPython

Databases: Postgresql, SQL, MongoDB

Operating System: Linux

Cloud Computing: DigitalOcean

Algorithms: A*,Linear Regression, Logistic Regression, CNN, RNN, LSTM, Q Learning, Reinforcement Learning, Decision Tree, Supervised, Unsupervised

PROJECTS

Wall Climbing Mobile Robot for Industrial Inspection (M.Des. Final Project) — Guide: Dr. S. R. Pandian , Email: srp@iiitdm.ac.in

- An IGCAR funded project for inspection of a nuclear tunnel
- It includes:
 - o GUI control panel(Python, wxPython, OpenCV)
 - A four wheeled mobile robot(Raspberry pi, DC Geared motors)
 - A negative thrust propulsion mechanism(ESC, BLDC ducted fan)
 - o UART connection between Raspberry Pi and Arduino

Autonomous Surface Cleaning Mobile Robot using TM4C1234GH6PM (M.Des, Embedded System Course Project) — Guide: Dr. S. R. Pandian , Email: srp@iiitdm.ac.in

- It involved utilisation of GPIOs of Tiva C launchpad for interfacing motor drivers and practicing PWM to control the motors
- Practicing ADC for obstacle avoidance with SHARP analog IR sensors
- Practicing Complete swipe algorithm on 32 kb ram size device to clean the room

MRI Brain Image Segmentation Using Fuzzy C-Mean Clustering Algorithm (M.Des, Digital Signal Processing Course Project) – Guide: Dr. Priyanka Kokil, Email: priyanka@iiitdm.ac.in

• Implemented modified fuzzy-c means clustering algorithm for the segmentation of brain tumour using MRI brain images using Matlab

Please Check out this YouTube Channel to get insights of my other projects —

https://www.youtube.com/channel/UC3osQYEtp53TzJ0QamLZavA?view a
s=subscriber OR - https://www.onebookall.com/

LANGUAGES

English (Proficient) Hindi (Proficient) Marathi (Proficient)