

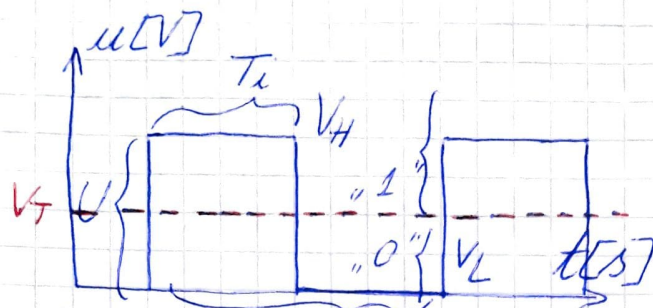
a)



$\Rightarrow$  f. logică  
 $\Rightarrow$  f. electronică

DA (repetitor)  
 Și NU (inversor)  
 ȘI ȘI-NU  
 ȘI-NU

b)



semnalul de bază  
 (ideal) se numește impuls

$V_T$  - tensiune de prag

Circuitul e comandat de un semnal de bază.

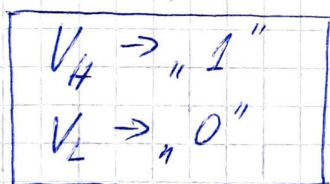
$T_i$  - durată Impulsul are 3 parametri

1)  $U$  - amplitudinea  $U = V_H - V_L$  [V]

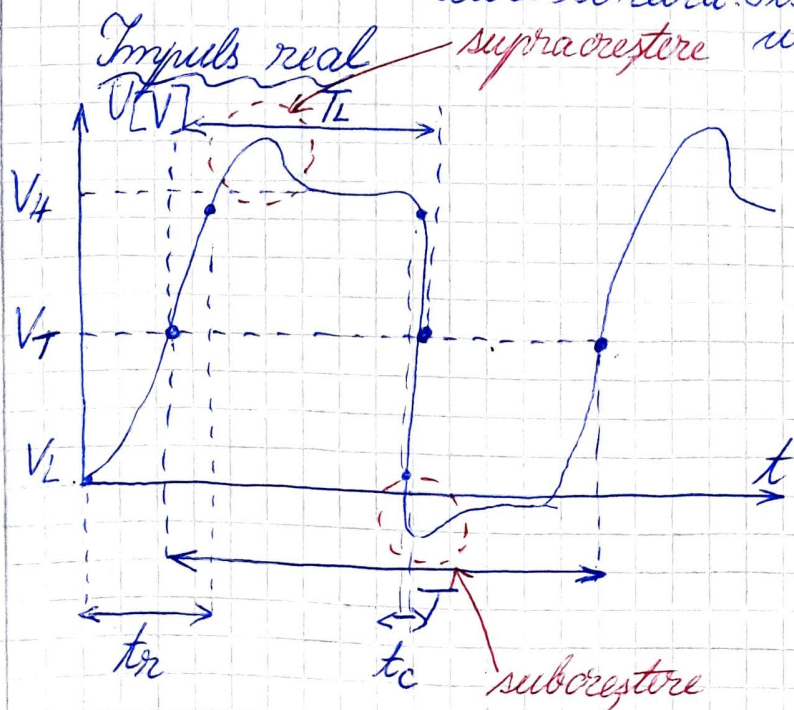
2)  $T_i$  - durată impulsului [ms,  $\mu$ s, ns, ps]

3)  $T$  - durată de repetiție

$F = \frac{1}{T}$  - frecvență de repetiție [Hz, kHz, MHz, GHz]



semnale binare  $V_T$  - tensiunea de prag  
 circuitului numeric i se atribuie o valoare binară. Sistemele numerice lucrează cu sisteme binare, 0 și 1.



Front

$t_r$  - front ridicător

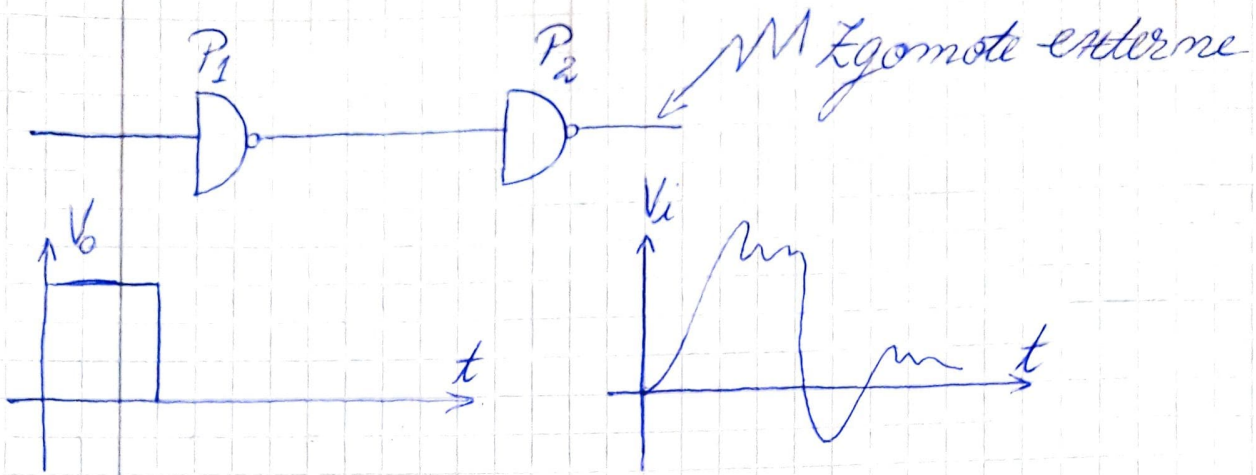
$t_f$  - front coborător

Timpi de tranziție

$t_r = t_{TLH}$

$t_f = t_{THL}$

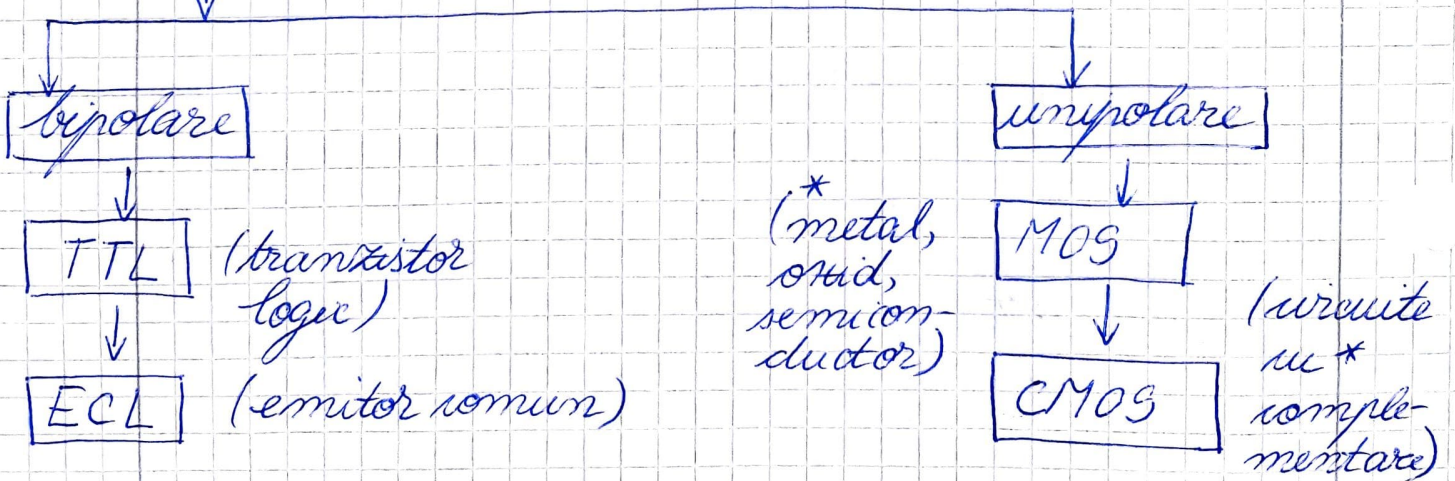




Componente electronice:

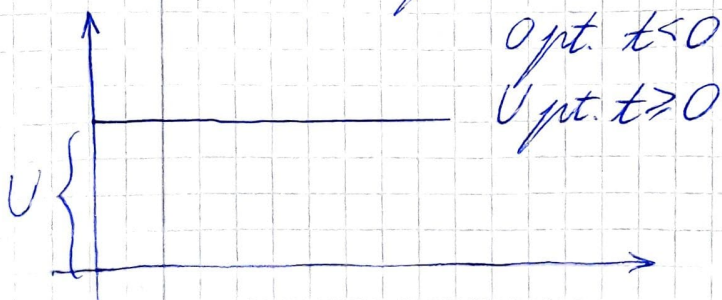
- rezistențe
- diode
- tranzistori 
 $\swarrow$  bipolare  
 $\searrow$  unipolare
- capacități

Circuitele integrate numerice se clasifică prin familie

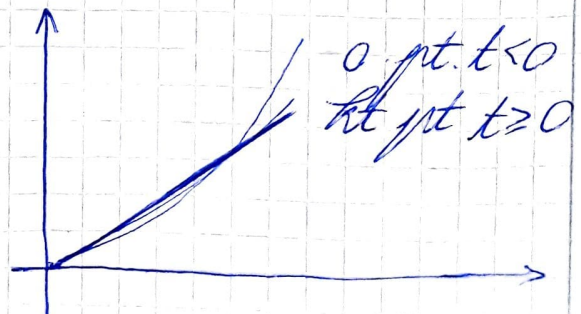


3 semnale de bază

a) semnal treaptă

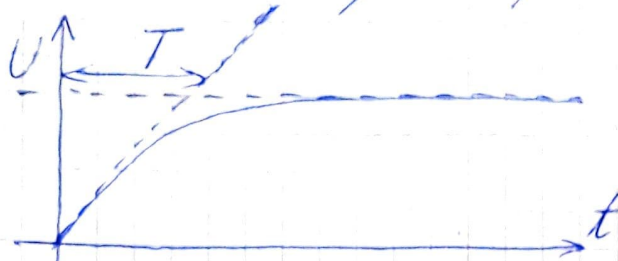


b) semnal liniar variabil





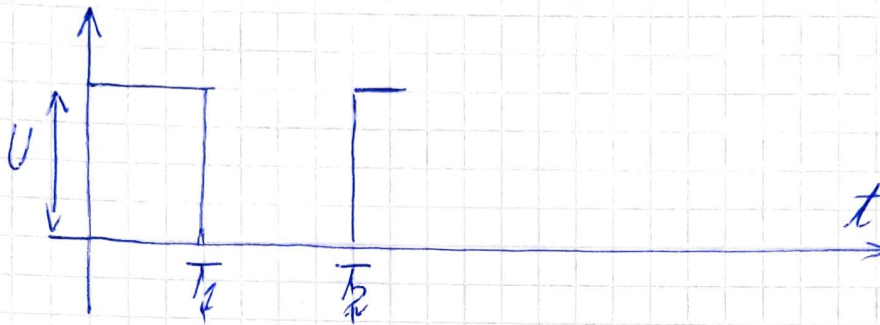
c) semnal exponential



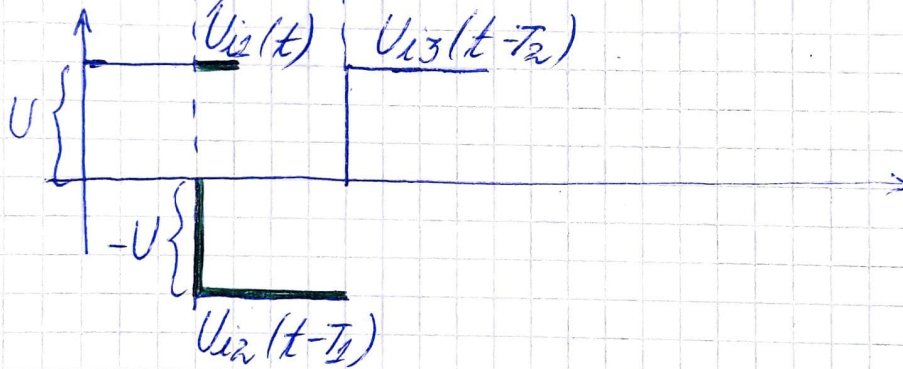
$$0 \text{ pt. } t < 0$$

$$U(1 - e^{-\frac{t}{\tau}}) \text{ pt. } t \geq 0$$

Cu ajutorul unui semnal putem reconstrui orice semnal de bază.



Descompun semnalul elementar



Analiza circuitelor numerice în cazul aplicării unui semnal la intrare

- ① ec. integro-diferențială
- ② suprapunerea efectelor

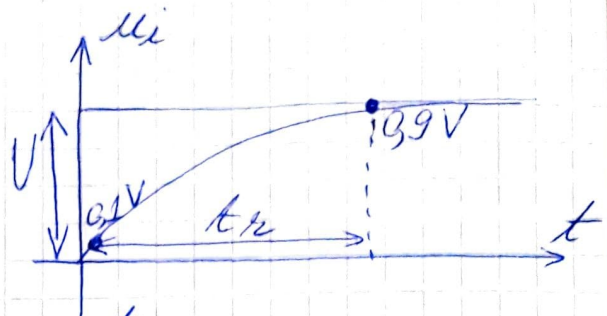
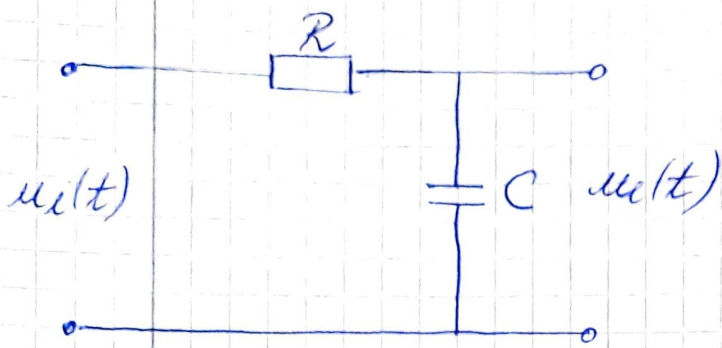
1a)



ec. dif.:  $\tau \frac{du_e(t)}{dt} + u_e(t) = u_i(t)$ , dacă  $u_i(t) = U \cdot \square$

$$u_e(t) = u_e(\infty) + [u_e(0) - u_e(\infty)] e^{-\frac{t}{\tau}}$$





$$u_e(t) = u_e(\infty) + [u_e(0) - u_e(\infty)] \cdot e^{-\frac{t}{\tau}}$$

$\tau$  - timp de ridicare  
 $\tau = \text{constantă de timp} = RC$

$$X_c = \frac{1}{\omega \cdot C} \quad \omega = 2\pi f$$

a) pt.  $t=0 \quad F \rightarrow \infty \Rightarrow \omega \rightarrow \infty \Rightarrow X_c = 0$   
 $u_e(0) = 0$

b) pt.  $t=\infty \quad F=0 \Rightarrow \omega=0 \Rightarrow X_c \rightarrow \infty$

$$u_e(t) = U + [0 - U] \cdot e^{-\frac{t}{RC}} = U(1 - e^{-\frac{t}{RC}})$$

$$\tau = RC \cdot \ln \frac{u_e(\text{final}) - u_e(\text{init})}{u_e(\text{final}) - u_e(*)}$$

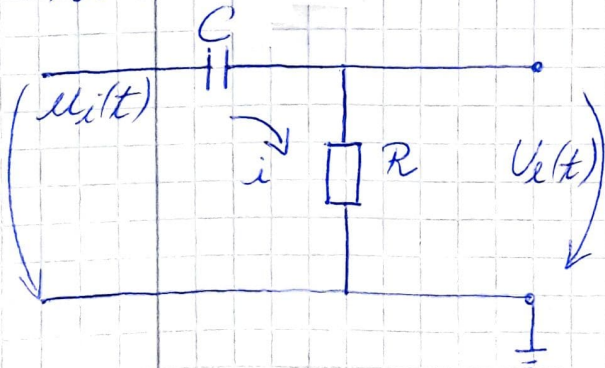
$$u_e(\text{final}) = U$$

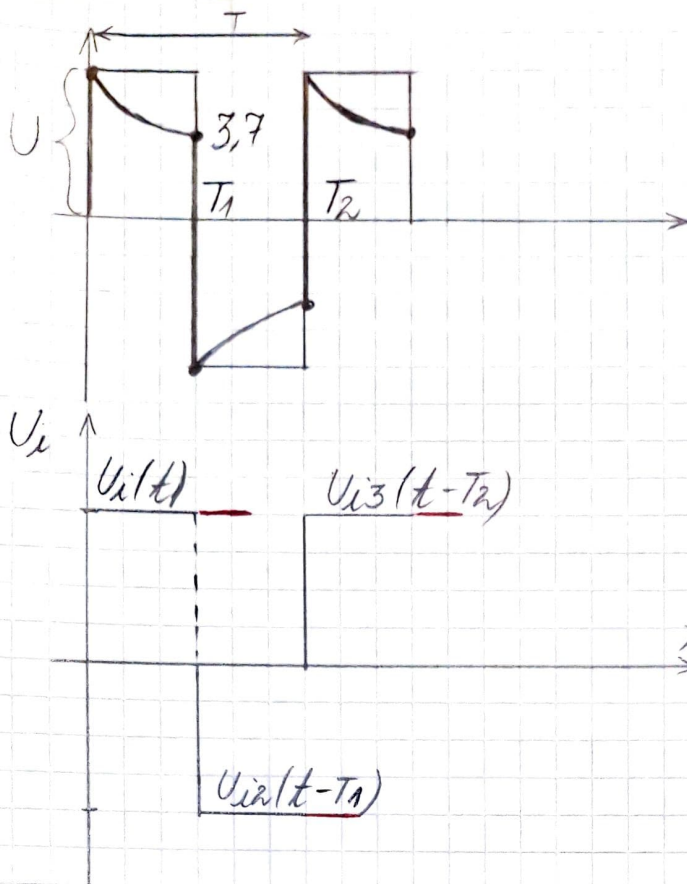
$$u_e(\text{init}) = 0,1V$$

$$u_e(\text{unde vrem să ajungem}^*) = 0,9U$$

$$\tau = RC \cdot \ln \frac{U - 0,1U}{U - 0,9U} = RC \cdot \ln 9 \approx 2,2 RC$$

RC trece sus





$$\begin{aligned}
 T_1 &= 10 \mu s \\
 T_2 - T_1 &= 10 \mu s \\
 R &= 1 k\Omega \\
 C &= 10 nF \\
 \tau &= 10 \mu s \\
 U &= 10 V
 \end{aligned}$$

a) pt.  $0 \leq t < T_1$

$$U_e(t) = U \cdot e^{-\frac{t}{\tau}}$$

b) pt.  $t = T_1 \Rightarrow U_e(T_1) = U \cdot e^{-\frac{T_1}{RC}}$

$$U_e(T_1) = U \cdot e^{-1} = 3,7 V$$

c) pt.  $T_1 < t < T_2$

$$U_e(t) = U \cdot e^{-\frac{t}{RC}} - U \cdot e^{-\frac{(t-T_1)}{RC}}$$

d) pt.  $T = T_2$

$$\begin{aligned}
 U_e(t) &= U \cdot e^{-\frac{T_2}{RC}} - U \cdot e^{-\frac{(T_2-T_1)}{RC}} = U \cdot e^{-\frac{20}{10}} - U \cdot e^{-\frac{(20-10)}{10}} \\
 &= U \cdot e^{-2} - U \cdot e^{-1} = U(0,15 - 0,37) \\
 U_e(t) &= -2,2 V
 \end{aligned}$$