

Hutchinson's Estimator is bad at Kronecker Trace Estimation

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Matrix-Vector Complexity

Many matvec-optimal algorithms proven recently

Great for applications where matvecs are:

- ① Efficiently Computable
- ② Computational Bottleneck

E.g. $\underline{x} \rightarrow f(A)\underline{x}$ via Lanczos Iteration

But what if ① does not hold?

We can only compute $A\underline{x}$ for some \underline{x} !

Kronecker Product

Let $A \in \mathbb{R}^{m \times n}$, $B \in \mathbb{R}^{p \times q}$. Then $A \otimes B \in \mathbb{R}^{mp \times nq}$

$$A \otimes B := \begin{bmatrix} [A]_{11}B & [A]_{12}B & \dots & [A]_{1m}B \\ [A]_{21}B & [A]_{22}B & \dots & [A]_{2m}B \\ \vdots & \vdots & \ddots & \vdots \\ [A]_{n1}B & [A]_{n2}B & \dots & [A]_{nm}B \end{bmatrix}$$

For vectors $\underline{x} \in \mathbb{R}^m$, $\underline{y} \in \mathbb{R}^p$, $\underline{x} \otimes \underline{y} \in \mathbb{R}^{mp}$

$$\underline{x} \otimes \underline{y} = \begin{bmatrix} x_1 y \\ x_2 y \\ \vdots \\ x_m y \end{bmatrix}$$

vectors
are
underlined

Kronecker-Matrix-Vector Oracle Model

Before: $A \in \mathbb{R}^{d \times d}$. We can compute $A\mathbf{x}$ for any $\mathbf{x} \in \mathbb{R}^d$

Now: $A \in \mathbb{R}^{d^K \times d^K}$. We can compute $A\mathbf{x}$ for any $\mathbf{x} = \underline{\mathbf{x}}_1 \otimes \underline{\mathbf{x}}_2 \otimes \dots \otimes \underline{\mathbf{x}}_K$
 $\underline{\mathbf{x}}_1, \dots, \underline{\mathbf{x}}_K \in \mathbb{R}^d$

Can we still solve linear algebra
problems efficiently?



$\text{poly}(d, K, \frac{1}{\epsilon})$?

Core Issue: d^K vs dk parameters

Trace Estimation

Estimate $\text{tr}(A)$ from few matvecs

Find $\tilde{\tau}$ such that

$$(1-\varepsilon) \text{tr}(A) \leq \tilde{\tau} \leq (1+\varepsilon) \text{tr}(A)$$

Classically,

Hutchinson's Estimator uses $\Theta(\frac{1}{\varepsilon^2})$ matvecs

Hutch++ uses $\Theta(\frac{1}{\varepsilon})$ matvecs

Variance Reduction

Our Contribution: Analyze Kronecker-Hutchinson

Hutchinson's Estimator can easily be made Kronecker

How many matvecs are needed for $\text{std dev} \leq \varepsilon \text{tr}(A)$?

Answer: $\ell = \Theta\left(\frac{3^k}{\varepsilon^2}\right)$ are needed

[Ahle et al. '20]

Further: Exact variance,

$O\left(\frac{2^k}{\varepsilon^2}\right)$ for random rank-one matrices

$\Theta\left(\frac{2^k}{\varepsilon^2}\right)$ needed for complex matvecs



The matrices where $\exp(K)$ matvecs are needed are either:

① Low Rank or ② $A = A_1 \otimes A_2 \otimes \cdots \otimes A_k$

We can compute $\text{tr}(A)$ exactly efficiently in both cases



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Hutchinson's Estimator

$$H_e(A) := \frac{1}{k} \sum_{i=1}^k g_i^T A g_i \quad \text{where} \quad g_i \sim N(\underline{0}, I)$$

Let $\hat{A} = \frac{1}{2}(A + A^T)$ be the symmetrized A

$$= U \Lambda U^T$$

eigenvalues

Then $g^T A g = g^T \hat{A} g \stackrel{\text{dist}}{=} g^T \Lambda g = \sum_i \lambda_i g_i^2$

$$\begin{aligned} \text{So } \mathbb{E}[g^T A g] &= \text{tr}(\hat{A}) \\ &= \text{tr}(A) \end{aligned}$$

$$\begin{aligned} \text{Var}[g^T A g] &= 2 \|\hat{A}\|_F^2 \\ &\leq 2 \|A\|_F^2 \\ &\leq 2 (\text{tr}(A))^2 \quad \text{for PSD } A \end{aligned}$$

Kronecker Hutchinson

Let $\underline{x} = \underline{x}_1 \otimes \cdots \otimes \underline{x}_n$ for $\underline{x}_i \stackrel{iid}{\sim} N(\underline{0}, \mathbf{I})$
Sample $\underline{x}^\top A \underline{x}$

What is $\mathbb{E}[\underline{x}^\top A \underline{x}]$? $\text{Var}[\underline{x}^\top A \underline{x}]$?

Problem: \underline{x} is not rotationally invariant!

Solution: "Extract" one \underline{x}_i at a time

Extraction

$$\mathbf{x} \otimes \mathbf{y} = (\mathbf{I}_n \otimes \mathbf{y})\mathbf{x} = (\mathbf{x} \otimes \mathbf{I}_m)\mathbf{y}$$

$K=2$

$$\underline{x}_1^T (\underline{x}_1 \otimes \underline{x}_2)^T A (\underline{x}_1 \otimes \underline{x}_2) \quad \underline{x}_1^T (\underline{x}_1 \otimes \underline{x}_2)^T A (\underline{x}_1 \otimes \underline{x}_2) \underline{x}_1$$

$$\underline{x}_1^T M \underline{x}_1$$

$$\mathbb{E}_{\underline{x}_1}[\underline{x}^T A \underline{x}] = \text{tr}(M) = \underline{x}_2^T \text{tr}_1(A) \underline{x}_2 \quad \text{Partial Trace of } A$$

$$\text{Var}_{\underline{x}_1}[\underline{x}^T A \underline{x}] = 2 \left\| \frac{1}{2}(M + M^T) \right\|_F^2 \quad \text{Partially Symmetrize } A$$

Core Theorem

Let $\bar{A} = \frac{1}{2^K} \sum_{\nu \subseteq \{1, \dots, K\}} A^{\tau_\nu}$ be the average of all partial symmetrizations of A .

$$\begin{aligned}
 \text{Then } \text{Var}[\underline{x}^T A \underline{x}] &= \sum_{S \subseteq \{1, \dots, K\}} 2^{K-|S|} \|\text{tr}_S(A)\|_F^2 \\
 &\leq \sum_{S \subseteq \{1, \dots, K\}} 2^{K-|S|} \|\text{tr}_S(\bar{A})\|_F^2 \\
 &\leq 3^K (\text{tr}(\bar{A}))^2 \quad \text{for PSD } A
 \end{aligned}$$

Proof: Lots of induction

Conclusions

- Introduce Kron-Mat-Vec Complexity
- Variance of Kron-Hutchinson Algo
- Surprising connection to Partial Trace, Partial Transpose
- $\Omega\left(\frac{3^K}{\varepsilon^2}\right)$ lower bound when A is the all-ones matrix
- $\Omega\left(\frac{\sqrt{K}}{\varepsilon^2}\right)$ lower bound against all Kron-Mat-Vec Algos

Double-Sparse Model

Suppose $A \in \mathbb{R}^{d \times d}$ on hard drive, but d is huge

You cannot store $\underline{x} \in \mathbb{R}^d$ in memory (RAM)

But cols of A are c -sparse

E.g. banded matrices

If \underline{x} is s -sparse, then $A\underline{x}$ is cs -sparse

Allow $O(d)$ time but $o(d)$ memory

[Jonathan Weare, Robert Webber]