

Does block size matter in randomized block Krylov low-rank approximation?

Raphael A. Meyer

UC Berkeley

With: Tyler Chen, Ethan Epperly, Chris Musco, and Akash Rao

JPM Chase

UC Berkeley

NYU

WSU

Low-Rank Approximation

Given $A \in \mathbb{R}^{n \times n}$, K , $\varepsilon > 0$ find ortho $Q \in \mathbb{R}^{n \times K}$ with

$$\|A - QQ^T A\|_{F,2} \leq (1 + \varepsilon) \|A - A_K\|_{F,2}$$

Ideally, Q = top K eigenvectors of A , so use Krylov

[Rokhlin et al. '09], [Halko et al. '11], [Drineas Ipsen '19], [Tropp '22], ...

Block Krylov

1. Pick a start block

$$B \in \mathbb{R}^{n \times b}$$

Usually Gaussian

$b =$ **block size**

2. Build Krylov subspace

$$Z = \text{orth}(K) = \text{orth}([B \quad AB \quad \dots \quad A^t B])$$

*Compute Ortho.
Basis for cols of K*

3. Return a solution

$$Q = Z^T U_k \quad \text{where} \quad U_k = \text{top } k \text{ eigvecs of } Z^T A A^T Z$$

Runtime is $O(n^2 b t)$. How should we pick b ?

How should we pick b ?

1. Theory: Use either $b \approx 1$ or $b \approx K$

Rich line of work [Tropp, Halko, Martinson, Gu, Drineas, Ipsen, Woodruff, ...]

Large Block Convergence

[Musco Musco '15]

$$b \geq K \implies t = \tilde{O}\left(\frac{1}{\sqrt{\epsilon}}\right) \text{ suffices}$$

$$\tilde{O}\left(n^2 b \frac{1}{\sqrt{\epsilon}}\right) \text{ time}$$

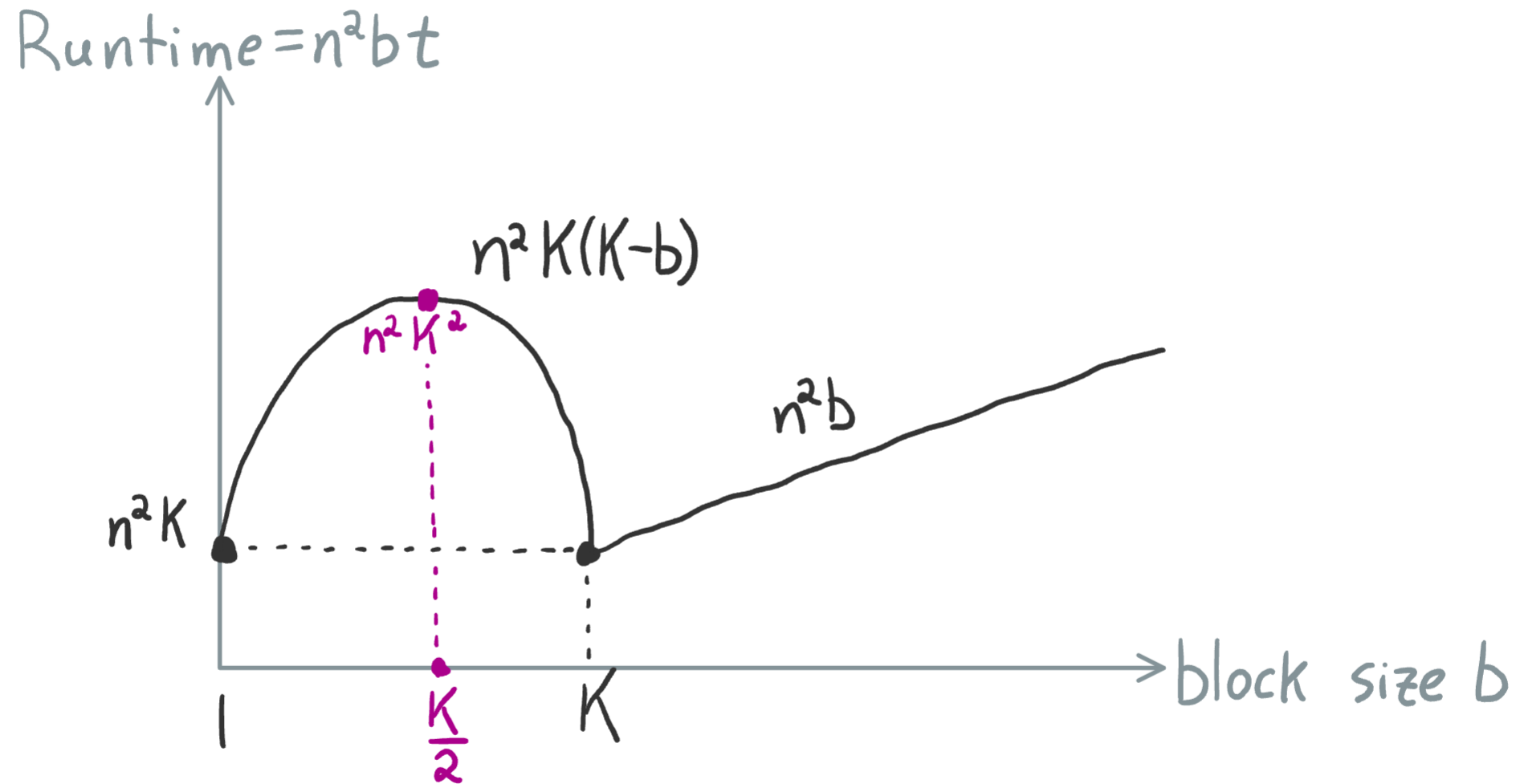
Small Block Convergence

[Meyer Musco Musco '24]

$$1 \leq b < K \implies t = \tilde{O}\left(\frac{K-b}{\sqrt{\epsilon}}\right) \text{ suffices}$$

$$\tilde{O}\left(n^2 b (K-b) \frac{1}{\sqrt{\epsilon}}\right) \text{ time}$$

The complexity landscape



$b = \frac{K}{2}$ is super expensive!?!

How should we pick b ?

2. Practitioner: Completely ignore K

Bottleneck is computing matrix-matrix products

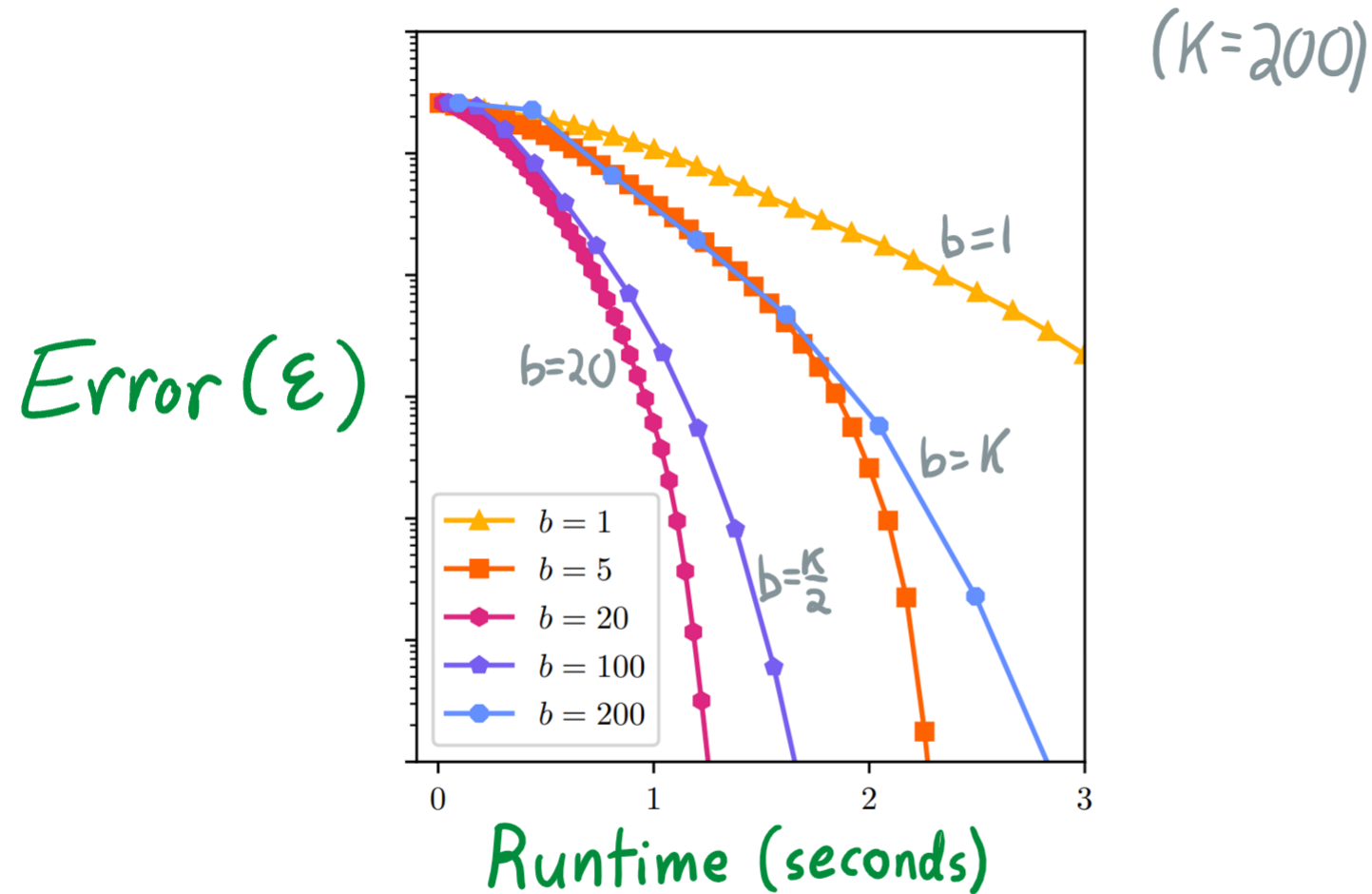
$$K = [B \quad AB \quad A^2B \quad \dots \quad A^{t-1}B \quad A^tB]$$

Product of $n \times n$ and $n \times b$ matrices

Unless your fast memory is saturated, you can increase b without almost any slow down!

Conclusion: use largest b that fits in fast memory!

Using this value of b works extremely well!



A theory/practice gap!

Should we pick block size b as a function of the target rank K in Block Krylov low-rank approximation?

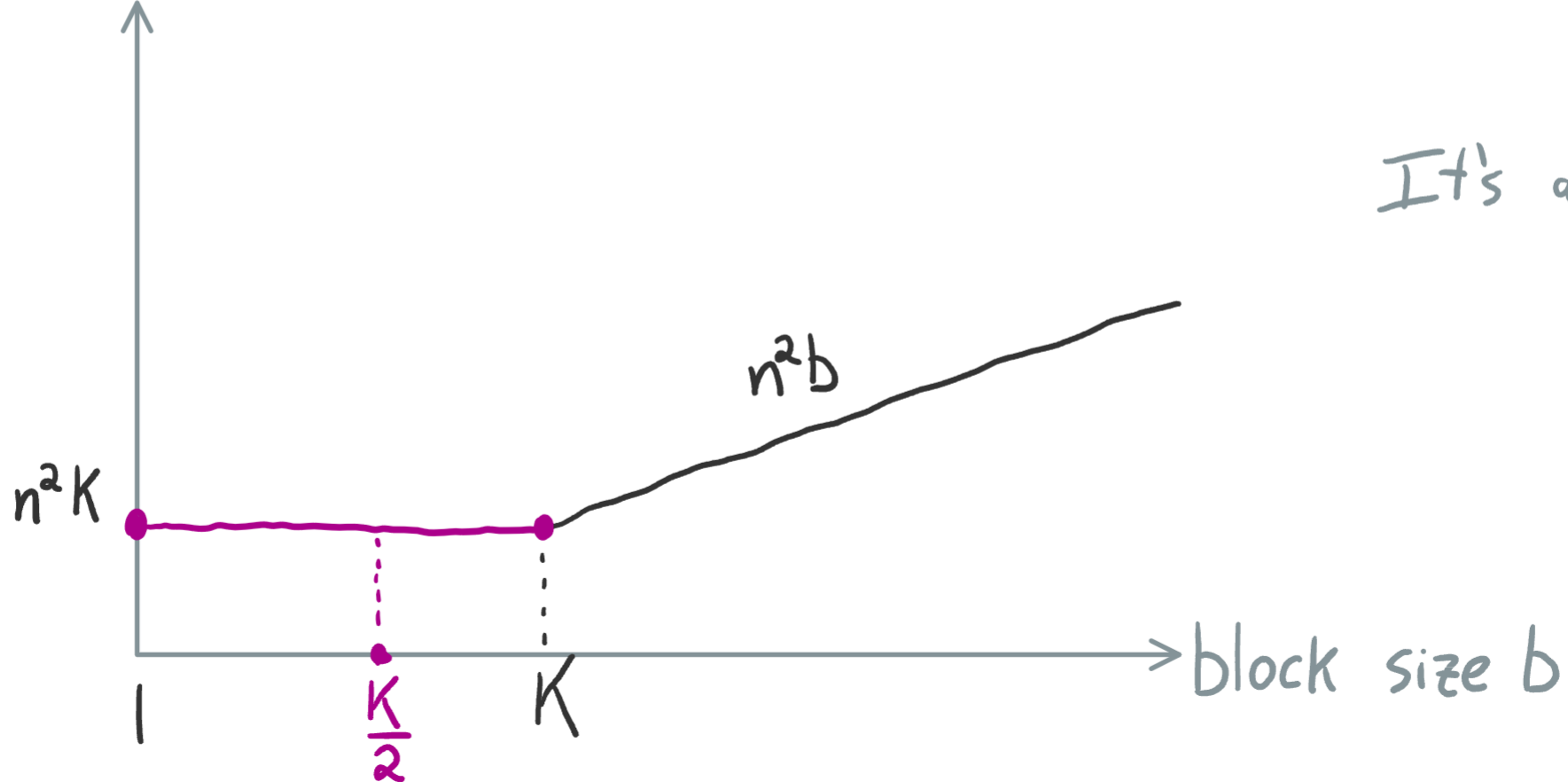
Caveat: Infinite Precision, Matrix-vector Complexity

Main Result

All Block Sizes Converge Fast

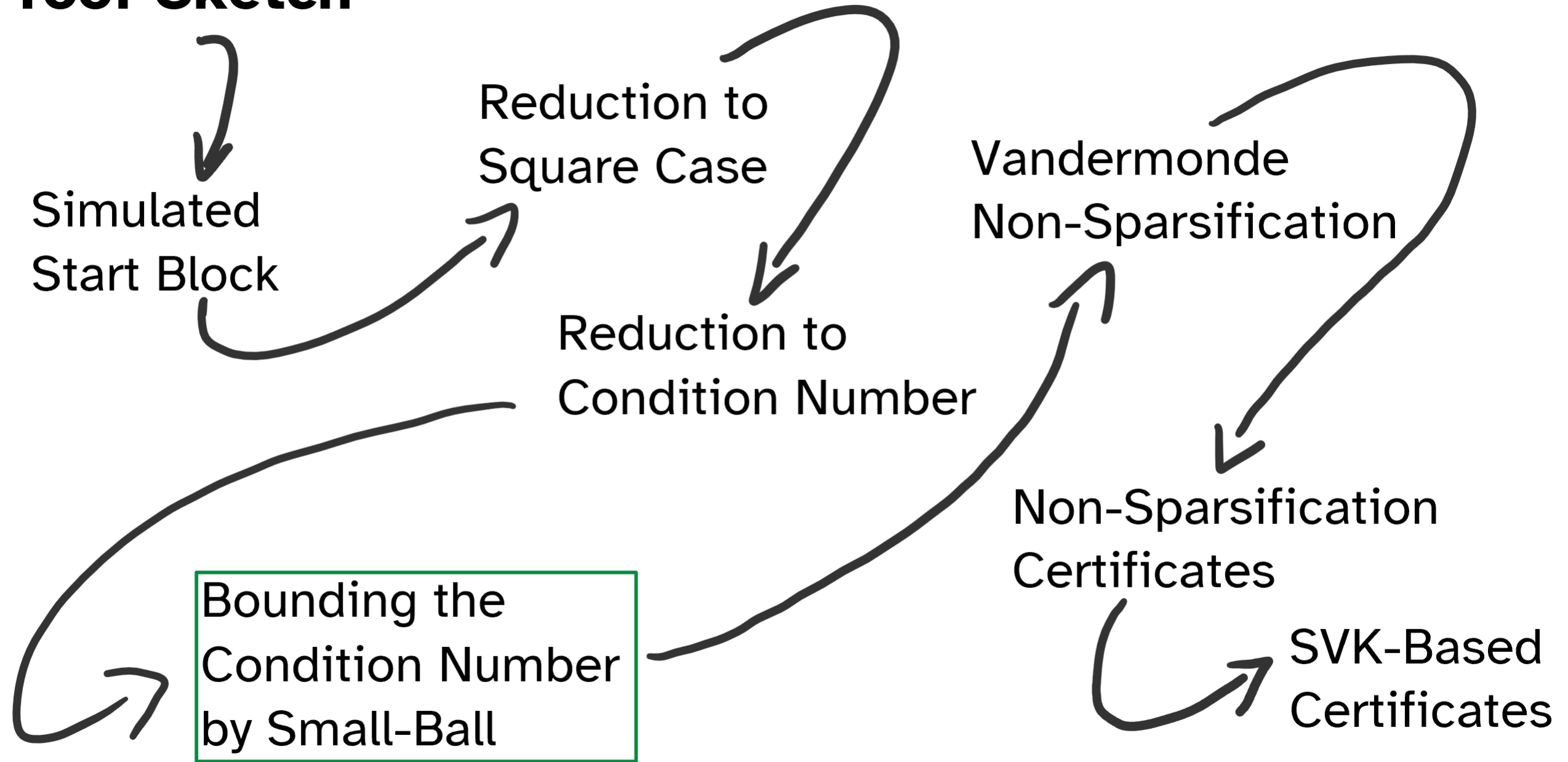
$$1 \leq b < K \implies t = \tilde{O}\left(\frac{K}{b} \cdot \frac{1}{\sqrt{\epsilon}}\right) \text{ suffices} \quad \tilde{O}(n^2 K \frac{1}{\sqrt{\epsilon}}) \text{ time}$$

Runtime = $n^2 b t$



It's all cheap!

Proof Sketch



Intermediate Result: Krylov Matrix Conditioning

Let $C \in \mathbb{R}^{K \times K}$ with eigenvalues $\lambda_1, \dots, \lambda_K$

$$\begin{array}{c} K \\ \square \\ K \end{array} C, \quad \underbrace{\lambda_i > 0}_{\text{PSD}}, \quad \underbrace{\text{cond}(C) \leq K}_{\text{well-conditioned}}, \quad \underbrace{|\lambda_i - \lambda_{i+1}| \geq \Delta \lambda_i}_{\text{bounded eigenvalue gaps}}$$

Suppose $K=bt$ exactly. Build Krylov matrix

$$K = [B \quad CB \quad C^2B \quad \dots \quad C^{t-1}B] \in \mathbb{R}^{K \times K}$$

$B \in \mathbb{R}^{K \times b}$
Gaussian ↗

Then,

$$\text{cond}(K) \leq \left(\frac{\Delta}{K}\right)^t \text{poly}(K) \quad \text{w.p. } \frac{2}{3}$$

[Peng Vempala 24] [Nie 22] had shown this for $b \geq \sqrt{K}$ only

In the paper: Grab bag of more implications

- **Beyond worst-case matrices**
- Smoothed Analysis
- Experiments
- A whole bunch of math

Any questions?