Model validation

Puteaux, Fall/Winter 2020-2021

1. Why is it important to choose validation in deep learning?

- Repeated training from cross-validation would take a long time, so it is common to use validation split rather than cross-validation.
- Deep learning is widely used in large datasets because the single validation score is based on a large amount of data and is reliable.

2. Code of model validation:

```
data = data_preparation(data)

predictors = data.drop(['shot_result'], axis=1).to_numpy()
n_cols = predictors.shape[1]
target = to_categorical(data.shot_result)
input_shape = (n_cols, )

def get_new_model(input_shape=input_shape):
    model = Sequential()
    model.add(Dense(100, activation='relu', input_shape=input_shape))
    model.add(Dense(100, activation='relu'))
    model.add(Dense(2, activation='softmax'))
    return (model)

model = get_new_model()
```

[2]: <tensorflow.python.keras.callbacks.History at 0x7fdfac48cc50>

3. Code of early stopping:

```
accuracy: 0.6195 - val_loss: 0.6525 - val_accuracy: 0.6137
Epoch 4/20
2802/2802 [============ ] - 8s 3ms/step - loss: 0.6503 -
accuracy: 0.6204 - val_loss: 0.6498 - val_accuracy: 0.6187
Epoch 5/20
accuracy: 0.6207 - val loss: 0.6501 - val accuracy: 0.6191
Epoch 6/20
2802/2802 [============= ] - 10s 4ms/step - loss: 0.6495 -
accuracy: 0.6205 - val_loss: 0.6496 - val_accuracy: 0.6186
Epoch 7/20
2802/2802 [============= ] - 7s 3ms/step - loss: 0.6493 -
accuracy: 0.6211 - val_loss: 0.6496 - val_accuracy: 0.6188
Epoch 8/20
accuracy: 0.6207 - val_loss: 0.6491 - val_accuracy: 0.6195
Epoch 9/20
2802/2802 [============ ] - 8s 3ms/step - loss: 0.6487 -
accuracy: 0.6208 - val_loss: 0.6498 - val_accuracy: 0.6205
Epoch 10/20
accuracy: 0.6217 - val_loss: 0.6498 - val_accuracy: 0.6196
```

[3]: <tensorflow.python.keras.callbacks.History at 0x7fdfaeeb5610>

4. What kind of experimentations could be included in deep learning?

- Experiment with different architectures.
- More layers.
- Fewer layers.
- Layers with more nodes.
- Layers with fewer nodes.
- Creating a great model requires experimentation.

5. Practice exercises for model validation:

► Package pre-loading:

```
[4]: import pandas as pd
from keras.layers import Dense
from keras.models import Sequential
from keras.utils import to_categorical
```

► Data pre-loading:

```
[5]: df = pd.read_csv('ref4. Titanic.csv')
```

```
df.replace(False, 0, inplace=True)
df.replace(True, 1, inplace=True)

predictors = df.drop(['survived'], axis=1).to_numpy()
n_cols = predictors.shape[1]
target = to_categorical(df.survived)
input_shape = (n_cols, )
```

▶ Evaluating model accuracy on validation dataset practice:

▶ Early stopping optimization optimizing practice:

```
[7]: # Import EarlyStopping
    from keras.callbacks import EarlyStopping

# Save the number of columns in predictors: n_cols
    n_cols = predictors.shape[1]
    input_shape = (n_cols, )

# Specify the model
    model = Sequential()
    model.add(Dense(100, activation='relu', input_shape=input_shape))
    model.add(Dense(100, activation='relu'))
    model.add(Dense(2, activation='softmax'))

# Compile the model
    model.compile(optimizer='adam',
```

[7]: <tensorflow.python.keras.callbacks.History at 0x7fdfb028d650>

► Package re-pre-loading:

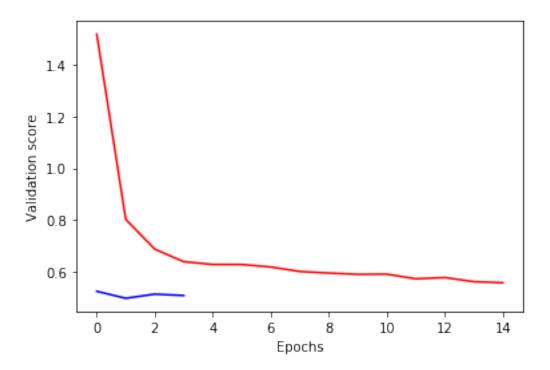
```
[8]: import matplotlib.pyplot as plt
```

► Code pre-loading:

▶ Experimenting with wider networks practice:

```
[10]: # Define early_stopping_monitor
early_stopping_monitor = EarlyStopping(patience=2)
# Create the new model: model_2
```

```
model_2 = Sequential()
# Add the first and second layers
model_2.add(Dense(100, activation='relu', input_shape=input_shape))
model_2.add(Dense(100, activation='relu'))
# Add the output layer
model_2.add(Dense(2, activation='softmax'))
# Compile model_2
model_2.compile(optimizer='adam',
                loss='categorical_crossentropy',
                metrics=['accuracy'])
# Fit model_1
model_1_training = model_1.fit(predictors,
                               target,
                               epochs=15,
                               validation_split=0.2,
                               callbacks=[early_stopping_monitor],
                               verbose=False)
# Fit model_2
model_2_training = model_2.fit(predictors,
                               target,
                               epochs=15,
                               validation_split=0.2,
                               callbacks=[early_stopping_monitor],
                               verbose=False)
# Create the plot
plt.plot(model_1_training.history['val_loss'], 'r',
         model_2_training.history['val_loss'], 'b')
plt.xlabel('Epochs')
plt.ylabel('Validation score')
plt.show()
```



► Code re-pre-loading:

▶ Network layers adding practice:

```
[12]: # The input shape to use in the first hidden layer
input_shape = (n_cols, )

# Create the new model: model_2
model_2 = Sequential()

# Add the first, second, and third hidden layers
model_2.add(Dense(50, activation='relu', input_shape=input_shape))
model_2.add(Dense(50, activation='relu'))
model_2.add(Dense(50, activation='relu'))

# Add the output layer
model_2.add(Dense(2, activation='softmax'))
```

```
# Compile model_2
model_2.compile(optimizer='adam',
                loss='categorical_crossentropy',
                metrics=['accuracy'])
# Fit model 1
model_1_training = model_1.fit(predictors,
                               target,
                               epochs=20,
                               validation_split=0.4,
                               callbacks=[early_stopping_monitor],
                               verbose=False)
# Fit model 2
model_2_training = model_2.fit(predictors,
                               target,
                               epochs=20,
                               validation_split=0.4,
                               callbacks=[early_stopping_monitor],
                               verbose=False)
# Create the plot
plt.plot(model_1_training.history['val_loss'], 'r',
         model_2_training.history['val_loss'], 'b')
plt.xlabel('Epochs')
plt.ylabel('Validation score')
plt.show()
```

