Discretization for Radial Concentrations is central difference forward time explicit Euler integration

radial discretization in a nutshell

The continuous partial differential equation we consider is

$$\frac{dc}{dt} = \frac{1}{r} \frac{\partial}{\partial r} \left(rD \frac{\partial}{\partial r} c(r, t) \right) - k_{\text{PDE}} c(r, t) p de(r) + F_0(t) r_0 \delta(r - r_0).$$

Denoting $c_i(t) = c(r_i, t)$ and $pde_i = pde(r_i)$, we used the following discretization

$$\frac{c_i(t+\Delta t)-c_i(t)}{\Delta t} = \frac{D}{r_i\Delta r}(c_{i+1/2}-c_{i-1/2}) + \frac{D}{\Delta r^2}(c_{i+1}-2c_i+c_{i-1}) - k_{\text{PDE}}pde_ic_i + F_0\delta_{0i}$$

Where we have taken $c_{-1}=c_{-1/2}=c_0$, and $c_{N+1}=c_{N+1/2}=c_N$, and $c_{i+1/2}=\frac{1}{2}(c_{i+1}+c_i)$, and $\delta_{ij}=1$ if i=j and $\delta_{ij}=0$ otherwise.

For each time step, we then explicitly computed $c(r_i, t + \Delta t)$ with a time step of $\Delta t = 0.005$ seconds and radial step $\Delta r = 1$ micron.

▼ more detailed description of radial discretization

- \bullet Let \bigoplus denote the concatenation function.
- Let $\mathbf{rmesh} = \bigoplus_{r=r_0=50 \mu m}^{r_{\max}=1000 \mu m} r \equiv \bigoplus_{i=0}^{N-1} r_i$ denote the 1D array of radial distances from the aggregate. Note that rmesh is an array of length N.
- Let c(r, t) denote the cAMP concentration at radial distance r at time t in nM.
- Let pde(r, t) denote the PDE concentration at radial distance r at time t in nM.
- Let $F_0(t) \in [0, 200]$ nM/s be the rate of change in cAMP concentration at the aggregate at time t.
- Let dt = 0.005s be the size of one time step and $dr = 1\mu m$ be the spatial resolution of **rmesh**.

Then, we may compute $c(r,t+dt) = c(r,t) + dt \cdot \frac{dc}{dt}\Big|_t$, where $\frac{dc}{dt}\Big|_t$ is returned by the function time_step .

time_step is effectively defined from the following steps:

step 1: compute the face terms

- **dface** $(t) = 0 \oplus \left(\bigoplus_{i=0}^{N-2} c(r_{i+1}, t) c(r_i, t)\right) \oplus 0$. Note **dface** has length N+1
- $\mathbf{cp}(t) = c(r_0, t) \oplus \left(\bigoplus_{i=0}^{N-1} c(r_i, t) \right) \oplus c(r_{\max}, t)$. Note \mathbf{cp} has length N+2
- $\mathbf{face}(t) = \frac{1}{2} \bigoplus_{i=0}^{N} \mathrm{cp}(r_{i+1},t) + \mathrm{cp}(r_i,t)$. Note face has length N+1

Let $cp(r_i, t)$, face (r_i, t) , and $dface(r_i, t)$ denote the i^{th} entry of cp(t), face(t), and dface(t), respectively.

step 2: compute the transient terms

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• \mathbf{term1}(t) = \frac{D}{dr} \bigoplus_{i=0}^{N-1} \frac{1}{r_i} \Big( \mathrm{face}(r_{i+1}, t) - \mathrm{face}(r_i, t) \Big)

• \mathbf{term2}(t) = \frac{D}{dr^2} \bigoplus_{i=0}^{N-1} \mathrm{dface}(r_{i+1}, t) - \mathrm{dface}(r_i, t)

• \mathbf{termDEG}(t) = -k_{PDE} \bigoplus_{i=0}^{N-1} c(r_i, t) pde(r_i, t)

• \mathbf{termBC}(t) = F_0 \oplus \bigoplus_{i=1}^{N-1} 0

\mathbf{step 3}: add the transient terms Then,

\frac{dc}{dc} \Big| = \mathbf{term1}(t) + \mathbf{term2}(t) + \mathbf{termDEG}(t) + \mathbf{termBC}(t)
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the numpy implementation fo the time step

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In [1]:
              import numpy as np
        executed in 272ms, finished 12:14:31 2020-07-15
In [2]:
          1 ▼ def time step(c, pde, rmesh, D, kPDE, dr, fluxLeft, fluxRight=0):
                   '''returns d[cAMP]/dt = the rate of change of the cAMP field c
          3
                  rmesh is the 1D radial mesh,
                  c = 1D array of cAMP concentrations
          4
          5
                  pde = 1D array of PDE concentrations
          6
                  D = diffusion coefficient of cAMP
          7
                  kPDE = decay constant of cAMP due to PDE
          8
                  dr = spatial resolution, for example 1 (microns)
                   fluxLeft is the rate cAMP is being added at the "left" boundary, closest to
          9
                   fluxRight is he rate cAMP is being added at the "right" boundary, furthest
         10
                   explicitely using only current state.'''
         11
         12
                   #step one: compute the face terms
         13
                  dface = np.hstack([ 0. , np.diff(c) , 0. ])
         14
                         = np.hstack([c[0], c, c[-1]])
         15
                   face = cp[1:]*0.5 + cp[:-1]*0.5
         16
         17
                   #step two: compute transient terms
         18
                   term1 = D*np.diff(face)/rmesh/dr
         19
                   term2 = D*np.diff(dface)/dr**2
         20
                   termDEG = -1*kPDE*c*pde
         21
                   #calculate boundary term
         22
                   termBC = np.hstack([ fluxLeft , 0*c[1:-1] , fluxRight ])
         23
         24
                   #step three: add transient terms
         25
                   dcdt = term1 + term2 + termBC + termDEG
         26
                   return dcdt
        executed in 9ms, finished 12:14:31 2020-07-15
In [ ]:
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