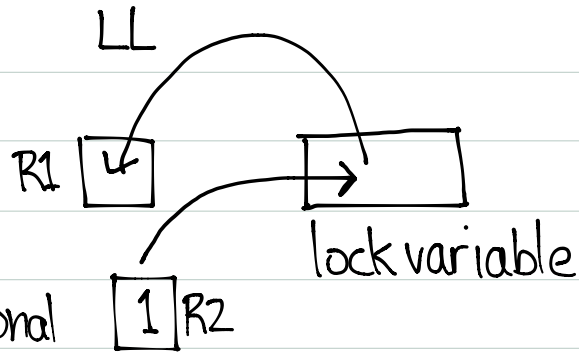


- No tested set for mips

- use

↳ LL → load link

↳ SC → store conditional



final value of register is
0: failure
1: success

Locks

- spinlocks vs locks

↳ use spinlocks to implement locks

↳ seem very similar

- when to use either

↳ spinlocks

- small, quick, critical sections

↳ locks

- larger more complicated

- other thread won't just stay spinning

Semaphore

- can solve mutual exclusion

- P and V are atomic

Semaphore P implementation

P();

WRONG

```

spinlock_acquire(&sem->sem_lock);
while if (sem->sem_count == 0) {
    /* block */
    wchan_lock(sem->sem_wchan);
    spinlock_release(&sem->sem_lock);
    wchan_sleep(sem->sem_wchan);
    spinlock_acquire(&sem->sem_lock);
}
sem->sem_count--;
spinlock_release(&sem->sem_lock);

```

cs350_submit -
cs350_runttests |& tee runtests.out
↳ takes 15 mins on unloaded servers

How LL SC works.

-SC R M

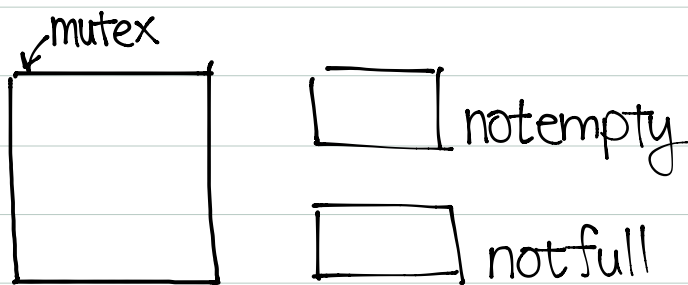
① WRITE contents of R into M if
no other update to M since LL
otherwise, do not change M

② Set value of R to 0 or 1 to indicate success
or failure of the store

Condition Variables

- kind of like wait channels

- signal - wakeone
- broadcast - wakeall
- need to be used with a lock
 - ↳ can only be used within the critical section that is protected by a lock.



- if a thread gets woken on notempty/notfull they may not have priority in the thread queue in the current simple implementation

Bounded Buffer Producer/Consumer with mutual exclusion

Producer

P(empty) // mutex can only be
P(mutex) 1 or 0

// add item

V(mutex)

V(full)

Consumer

P(full)

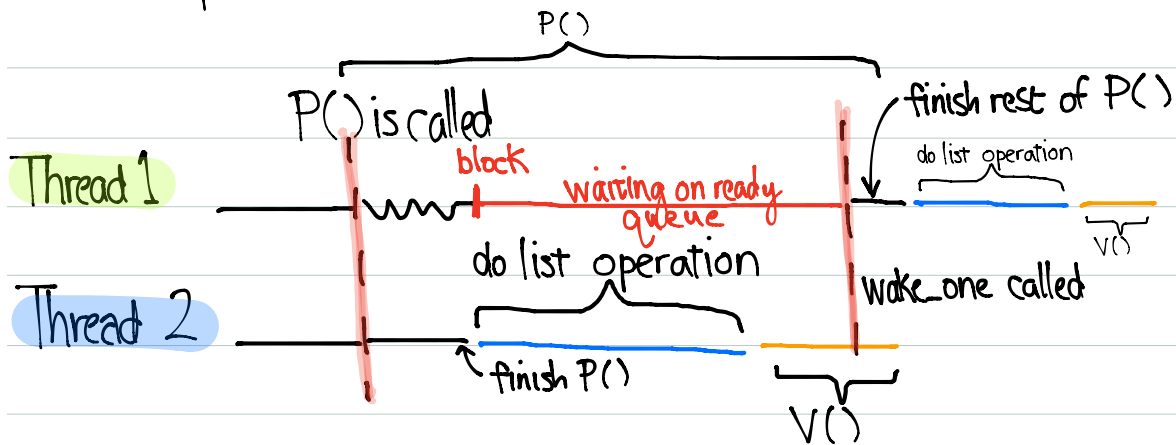
P(mutex)

// remove item

V(mutex)

V(empty)

How semaphores avoid conflict



Time: →

higher granularity → higher contention
→ lower overhead

Necessary condition for deadlock is "hold and wait"

Deadlock detection algorithm - run periodically to make sure system OK, kernel's job.