

# 2020-EE-'40-52'

EE24BTECH11023

- 1) Let  $a_r$ ,  $a_\phi$ , and  $a_z$  be unit vectors along  $r$ ,  $\theta$ , and  $z$  directions, respectively, in the cylindrical coordinate system. For the electric flux density given by  $\mathbf{D} = a_r 15 + a_\theta 2r - a_z 3rz$  Coulomb/m<sup>2</sup>, the total electric flux, in Coulomb, emanating from the volume enclosed by a solid cylinder of radius 3 m and height 5 m oriented along the  $z$ -axis with its base at the origin is:

- a)  $54 \pi$
- b)  $90 \pi$
- c)  $108 \pi$
- d)  $180 \pi$

- 2) A stable real linear time-invariant system with a single pole at  $p$ , has a transfer function

$$H(s) = \frac{s^2 + 100}{s - p}$$

with a dc gain of 5. The smallest positive frequency, in rad/s, at unity gain is closest to

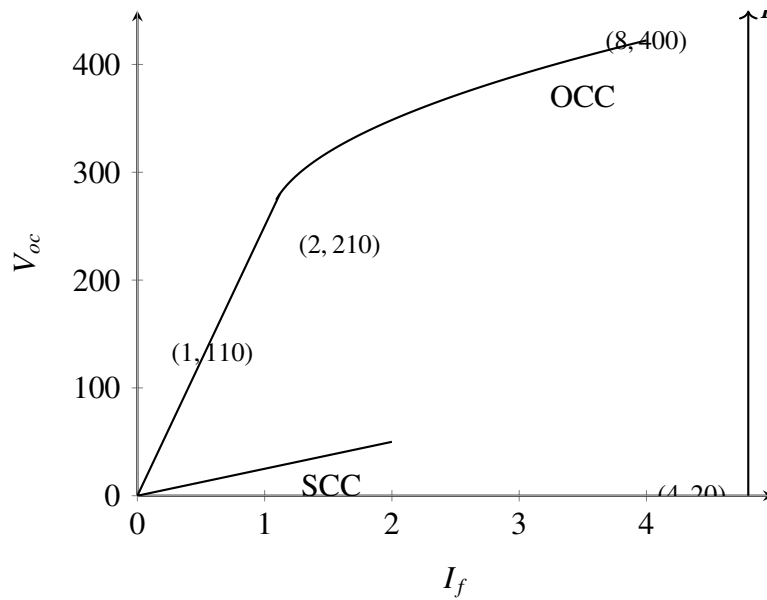
- a) 8.84
- b) 11.08
- c) 78.13
- d) 122.87

- 3) The number of purely real elements in a lower triangular representation of a given  $3 \times 3$  matrix, obtained through decomposition is \_\_\_\_\_.

$$\begin{bmatrix} 2 & 3 & 3 \\ 3 & 2 & 1 \\ 3 & 1 & 7 \end{bmatrix} = \begin{bmatrix} a_{11} & 0 & 0 \\ a_{12} & a_{22} & 0 \\ a_{13} & a_{23} & a_{33} \end{bmatrix} \begin{bmatrix} a_{11} & 0 & 0 \\ a_{12} & a_{22} & 0 \\ a_{13} & a_{23} & a_{33} \end{bmatrix}^T$$

- a) 5
- b) 6
- c) 8
- d) 9

- 4) The figure below shows the per-phase Open Circuit Characteristics (measured in V) and Short Circuit Characteristics (measured in A) of a 14 kVA, 400 V, 50 Hz, 4-pole, 3-phase, delta connected alternator, driven at 1500 rpm. The field current,  $I_f$  is measured in A. Readings taken are marked as respective  $(x, y)$  coordinates in the figure. Ratio of the unsaturated and saturated synchronous impedances ( $Z_{s(unsat)}/Z_{s(sat)}$ ) of the alternator is closest to:



- a) 2.100
- b) 2.025
- c) 2.000
- d) 1.000

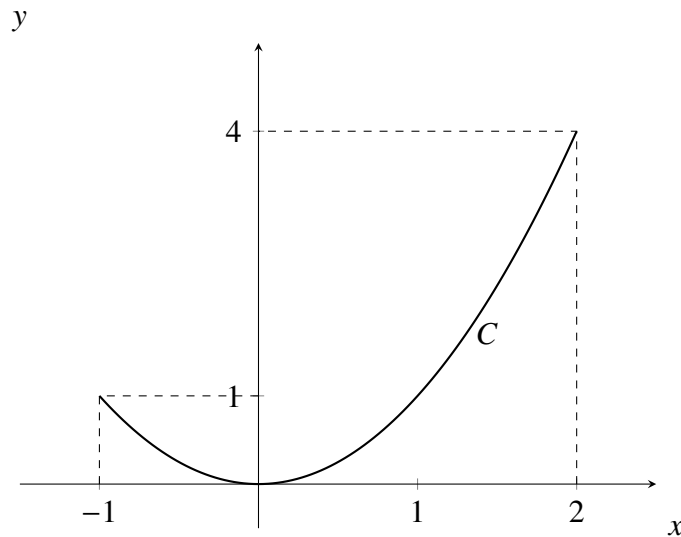
5) Let  $a_x$  and  $a_y$  be unit vectors along  $x$  and  $y$  directions, respectively. A vector function is given by:

$$\mathbf{F} = a_x y - a_y x$$

The line integral of the above function

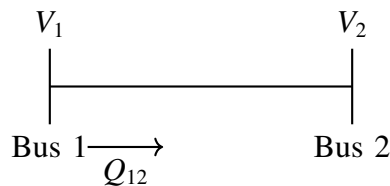
$$\int_C \mathbf{F} \cdot d\mathbf{l}$$

along the curve  $C$ , which follows the parabola  $y = x^2$  as shown below is \_\_\_\_\_ (rounded off to 2 decimal places).

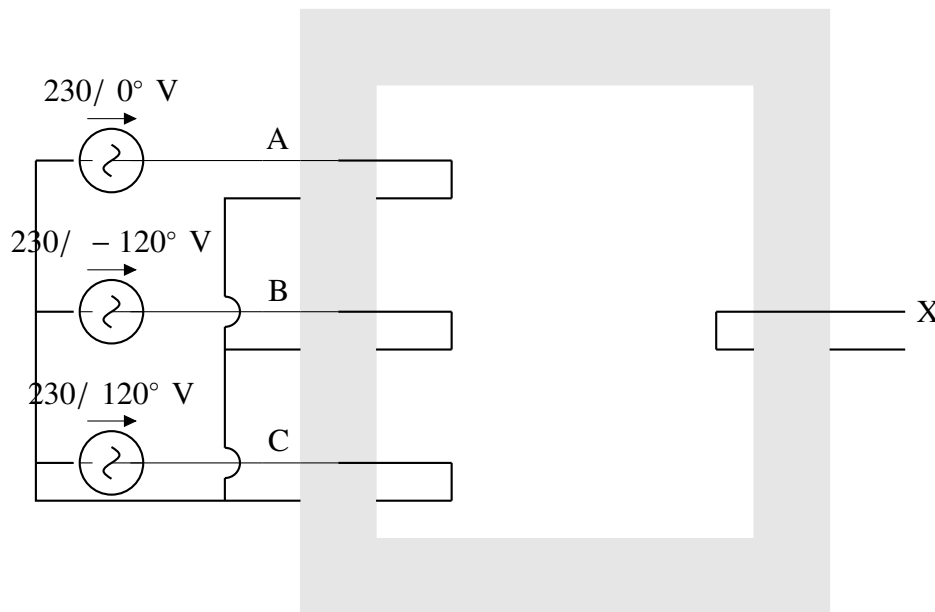


6) A resistor and a capacitor are connected in series to a 10 V dc supply through a switch. The switch is closed at  $t = 0$ , and the capacitor voltage is found to cross 0 V at  $t = 0.4\tau$ , where  $\tau$  is the circuit time constant. The absolute value of percentage change required in the initial capacitor voltage if the zero crossing has to happen at  $t = 0.2\tau$  is \_\_\_\_\_ (rounded off to 2 decimal places).

- 7) A cylindrical rotor synchronous generator with constant real power output and constant terminal voltage is supplying 100 A current to a 0.9 lagging power factor load. An ideal reactor is now connected in parallel with the load, as a result of which the total lagging reactive power requirement of the load is twice the previous value while the real power remains unchanged. The armature current is now \_\_\_\_\_ (rounded off to 2 decimal places).
- 8) Bus 1 with voltage magnitude  $V_1 = 1.1$  pu is sending reactive power  $Q_{12}$  towards bus 2 with voltage magnitude  $V_2 = 1$  pu through a lossless transmission line of reactance  $X$ . Keeping the voltage at bus 2 fixed at 1 pu, the magnitude of voltage at bus 1 is changed, so that the reactive power  $Q_{12}$  sent from bus 1 is increased by 20%. Real power flow through the line under both the conditions is zero. The new value of the voltage magnitude,  $V_1$ , in pu (rounded off to 2 decimal places), at bus 1 is \_\_\_\_\_.



- 9) Windings 'A', 'B', and 'C' have 20 turns each and are wound on the same iron core as shown, along with winding 'X' which has 2 turns. The figure shows the sense (clockwise/anti-clockwise) of each of the windings only and does not reflect the exact number of turns. If windings 'A', 'B', and 'C' are supplied with balanced 3-phase voltages at 50 Hz and there is no core saturation, the no-load RMS voltage (in V, rounded off to 2 decimal places) across winding 'X' is \_\_\_\_\_.



- 10) A cylindrical rotor synchronous generator has steady state synchronous reactance of 0.7 pu and subtransient reactance of 0.2 pu. It is operating at  $(1 + j0)$  pu terminal voltage with an internal emf of  $(1 + j0.7)$  pu. Following a three-phase solid short circuit fault at the terminal of the generator, the magnitude of the subtransient internal emf (rounded off to 2 decimal places) is \_\_\_\_\_ pu.
- 11) In the dc-dc converter circuit shown, switch  $Q$  is switched at a frequency of 10 kHz with a duty ratio of 0.6. All components of the circuit are ideal, and the initial current in the inductor is zero. Energy stored in the inductor in mJ (rounded off to 2 decimal places) at the end of 10 complete switching cycles is \_\_\_\_\_.

- 12) A single-phase, full-bridge, fully controlled thyristor rectifier feeds a load comprising a  $10\ \Omega$  resistance in series with a very large inductance. The rectifier is fed from an ideal 230 V, 50 Hz sinusoidal source through cables which have negligible internal resistance and a total inductance of 2.28 mH. If the thyristors are triggered at an angle  $\alpha = 45^\circ$ , the commutation overlap angle in degree (rounded off to 2 decimal places) is \_\_\_\_\_.
- 13) A non-ideal Si-based pn junction diode is tested by sweeping the bias applied across its terminals from -5 V to +5 V. The effective thermal voltage,  $V_T$ , for the diode is measured to be  $(29 \pm 2)$  mV. The resolution of the voltage source in the measurement range is 1 mV. The percentage uncertainty (rounded off to 2 decimal places) in the measured current at a bias voltage of 0.02 V is \_\_\_\_\_.