1D: 163432521
Q: Smart Receptionist Robot?
Sam
Robots Service are playing an
Increasingly nelevant note in society.
A smoot Receptions mobal can be negroved
both as a Socially interactive hobol.
working as a neceptionist is one possible employement.
employement.
Requirementi
Handware nequinment:
The second secon
1 Display. (VIII) Hard "disk"
(W) Arrami
@ Speaker
O Robobie Arrams, body.
Software requirement:
1 Windows Server
1) Lan Robotic Language.
M ACL Connector for oracle must instal.
IN ACL Connector for oracle must inser.

Solection & Wonwed zation Feature Dislance Monson Defection Body pose SVM. nession & Attention (6)p Saljeney Face

Specification; The smort nobet viritual embodiment used to in this work consists of an open source made of the physical In smart neceptions Robot. The Choice of a nobotoc aspect for both the physical and vintual robots can limit the presence of brases in the evaluation due to the receptionist appearance.

Hardware Components: The possibility To use viritual Robots for providing assistance to human user hasbeen extensively studied over the years, Historically two main freatures were bound to play a key note. in the The Robot interaction (encompassing Speech - and, gestwie - based Communicator facial expressions, gaze tacking etc. The main drawback of this solution is nepresented by the different Robol Systems,

Software components: The logical components that were assembled and for developed to Implement the Robotic reoptionist system: are in figure: 1. The control layer consists

of eight main modules, which we used to manage the smart rebots direction functionalitées. Modules a 1 Face Tracking. M Garce m chatbot (Invoice recognition O voice synthesis

Navigation OM Gestwee (VIII) Interaction logic.