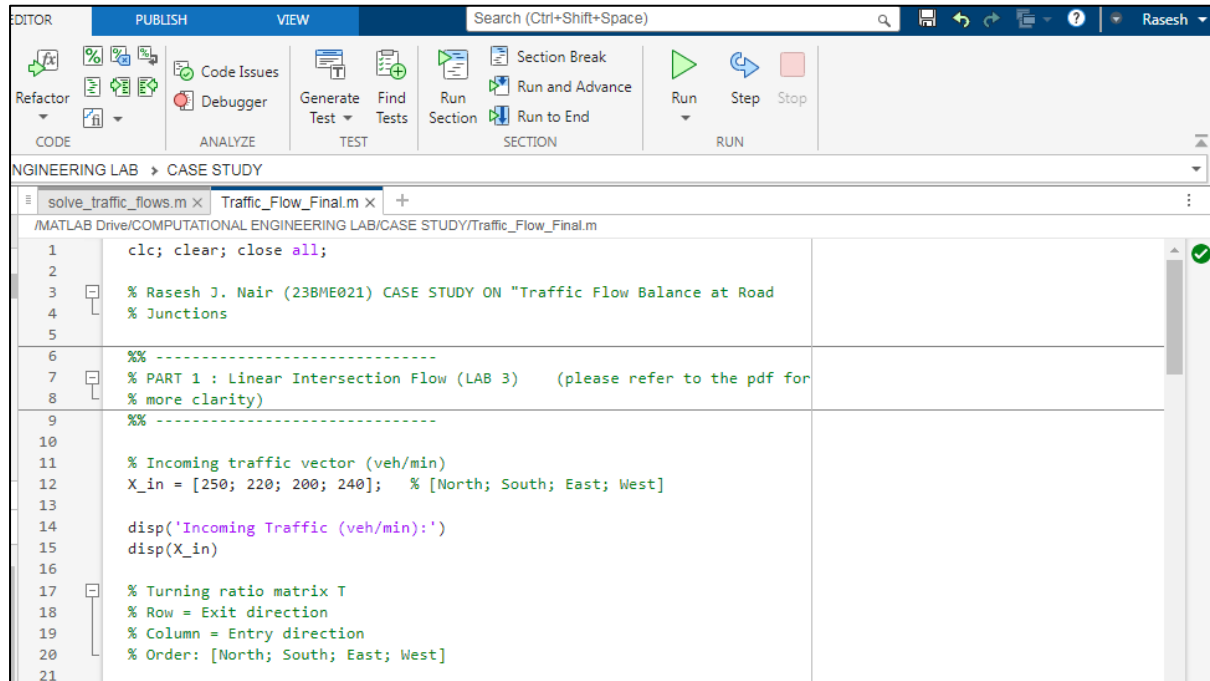


Aim: Traffic Flow Balance at Road Junctions – Using Conservation of Vehicles at intersections to form linear equations and compute traffic flows.

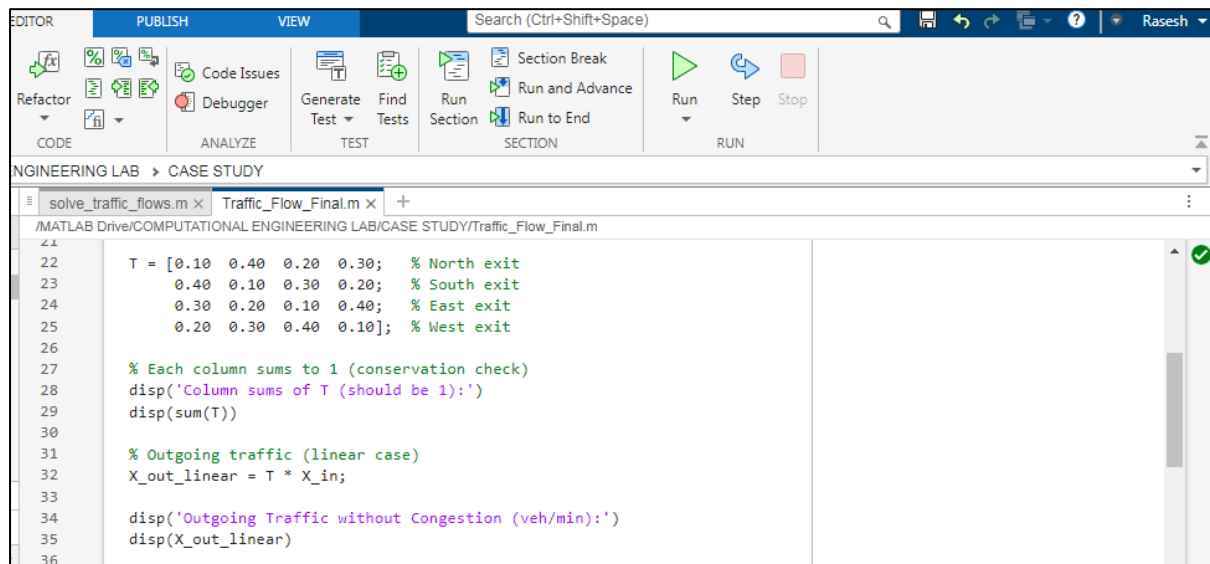


The screenshot shows the MATLAB Editor interface with the file 'Traffic_Flow_Final.m' open. The code includes comments for the author and the purpose of the script, followed by the definition of the incoming traffic vector X_{in} and the turning ratio matrix T .

```

1  clc; clear; close all;
2
3  % Rasesh J. Nair (23BME021) CASE STUDY ON "Traffic Flow Balance at Road
4  % Junctions
5
6  %% -----
7  % PART 1 : Linear Intersection Flow (LAB 3) (please refer to the pdf for
8  % more clarity)
9  %% -----
10
11 % Incoming traffic vector (veh/min)
12 X_in = [250; 220; 200; 240]; % [North; South; East; West]
13
14 disp('Incoming Traffic (veh/min):')
15 disp(X_in)
16
17 % Turning ratio matrix T
18 % Row = Exit direction
19 % Column = Entry direction
20 % Order: [North; South; East; West]
21

```



The screenshot shows the continuation of the MATLAB script. It defines the turning ratio matrix T and performs a conservation check by summing the columns of T . It then calculates the outgoing traffic vector X_{out_linear} for a linear case.

```

22 T = [0.10 0.40 0.20 0.30; % North exit
23      0.40 0.10 0.30 0.20; % South exit
24      0.30 0.20 0.10 0.40; % East exit
25      0.20 0.30 0.40 0.10]; % West exit
26
27 % Each column sums to 1 (conservation check)
28 disp('Column sums of T (should be 1):')
29 disp(sum(T))
30
31 % Outgoing traffic (linear case)
32 X_out_linear = T * X_in;
33
34 disp('Outgoing Traffic without Congestion (veh/min):')
35 disp(X_out_linear)
36

```

```

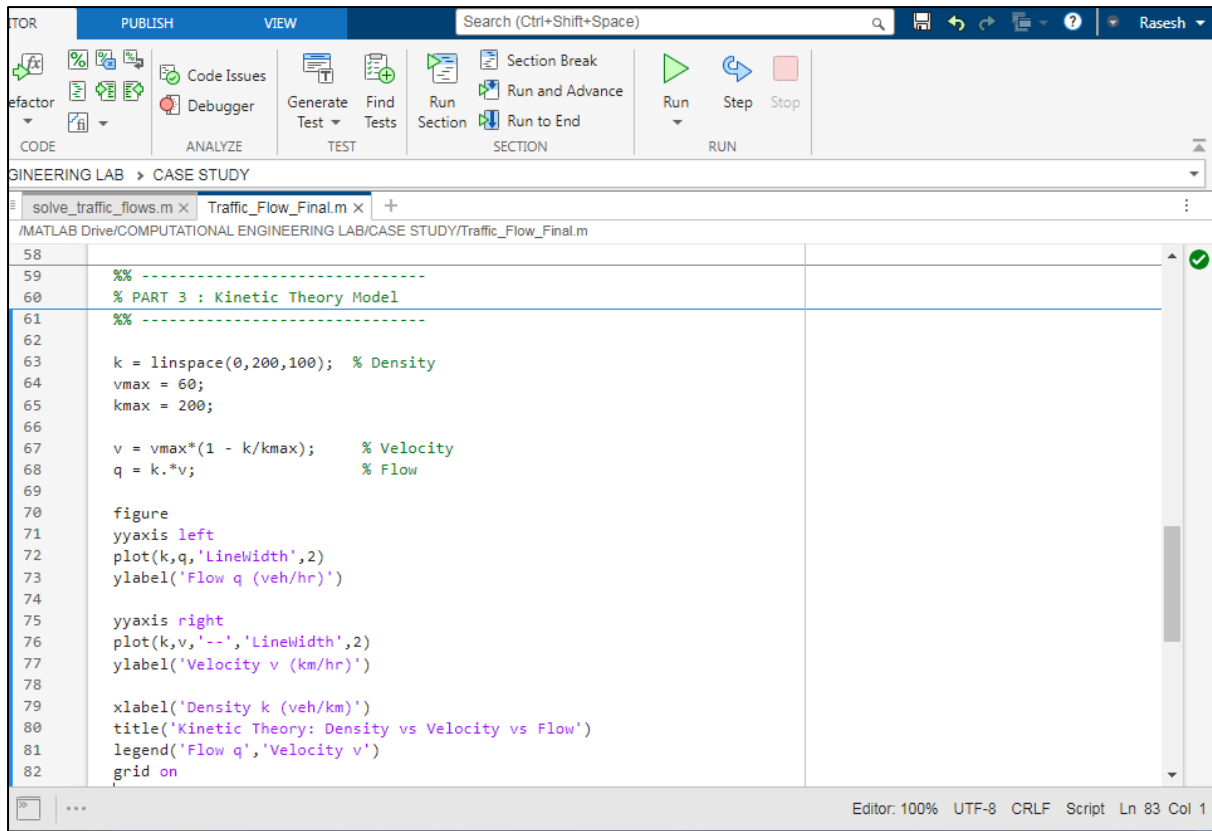
37
38     figure
39
40     bar([X_in X_out_linear])
41
42     xlabel('Road Number (1=N, 2=S, 3=E, 4=W)')
43     ylabel('Flow (veh/min)')
44     title('Incoming vs Outgoing Traffic at Junction (Matrix Model)')
45     legend('Incoming','Outgoing (Linear)')
46     grid on

```

```

36
37     %% -----
38     % PART 2 : Congestion Effect (Nonlinear) (LAB 5 concept)
39     %% -----
40
41     capacity = 400; % congestion parameter - vehicle/min
42
43     % Nonlinear congestion effect
44     X_out_cong = X_out_linear .* (1 - X_out_linear/capacity);
45
46     disp('Outgoing Traffic with Congestion (veh/min):')
47     disp(X_out_cong)
48
49     % Plot comparison
50     figure
51     bar([X_out_linear X_out_cong])
52     legend('Without Congestion','With Congestion')
53     xlabel('Road Number (1=N,2=S,3=E,4=W)')
54     ylabel('Flow (veh/min)')
55     title('Effect of Congestion at Junction (Matrix Model)')
56     grid on
57

```



```

58
59 %% -----
60 % PART 3 : Kinetic Theory Model
61 %% -----
62
63 k = linspace(0,200,100); % Density
64 vmax = 60;
65 kmax = 200;
66
67 v = vmax*(1 - k/kmax); % Velocity
68 q = k.*v; % Flow
69
70 figure
71 yyaxis left
72 plot(k,q,'LineWidth',2)
73 ylabel('Flow q (veh/hr)')
74
75 yyaxis right
76 plot(k,v,'--','LineWidth',2)
77 ylabel('Velocity v (km/hr)')
78
79 xlabel('Density k (veh/km)')
80 title('Kinetic Theory: Density vs Velocity vs Flow')
81 legend('Flow q','Velocity v')
82 grid on

```

Command Window

Incoming Traffic (veh/min):

```

250
220
200
240

```

Column sums of T (should be 1):

```

1    1    1    1

```

Outgoing Traffic without Congestion (veh/min):

```

225
230
235
220

```

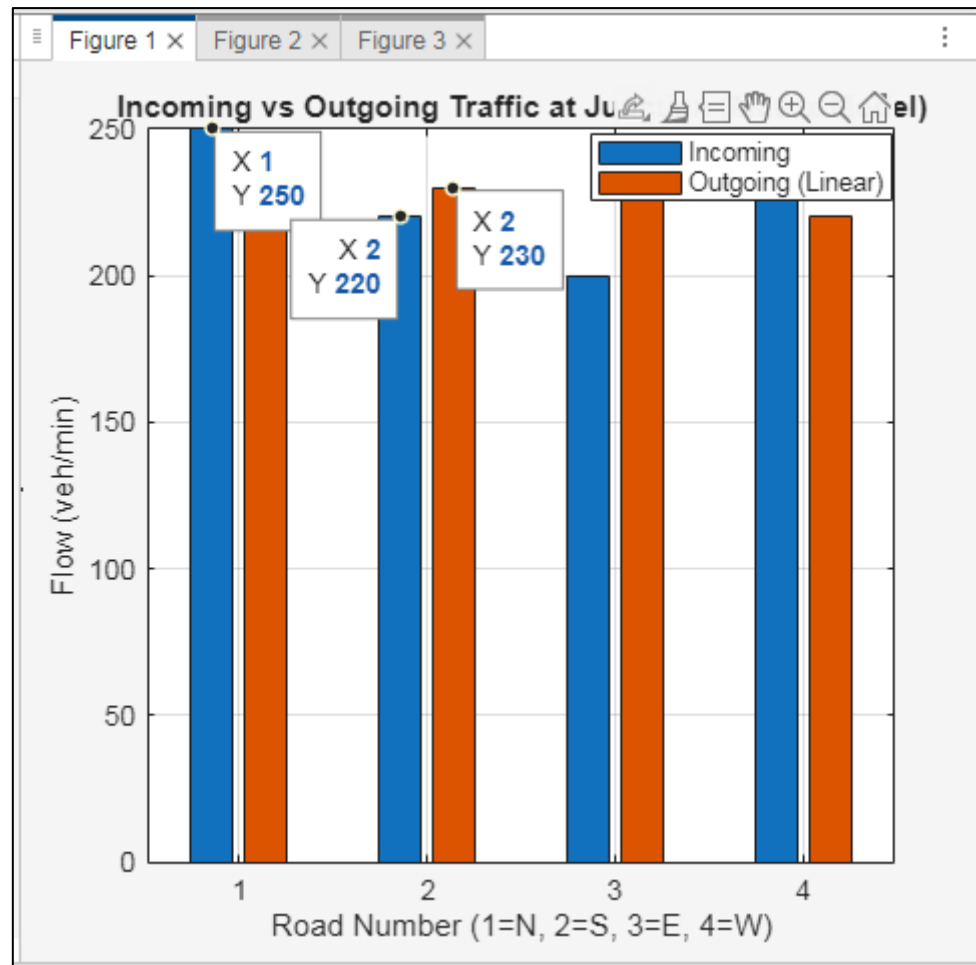
Outgoing Traffic with Congestion (veh/min):

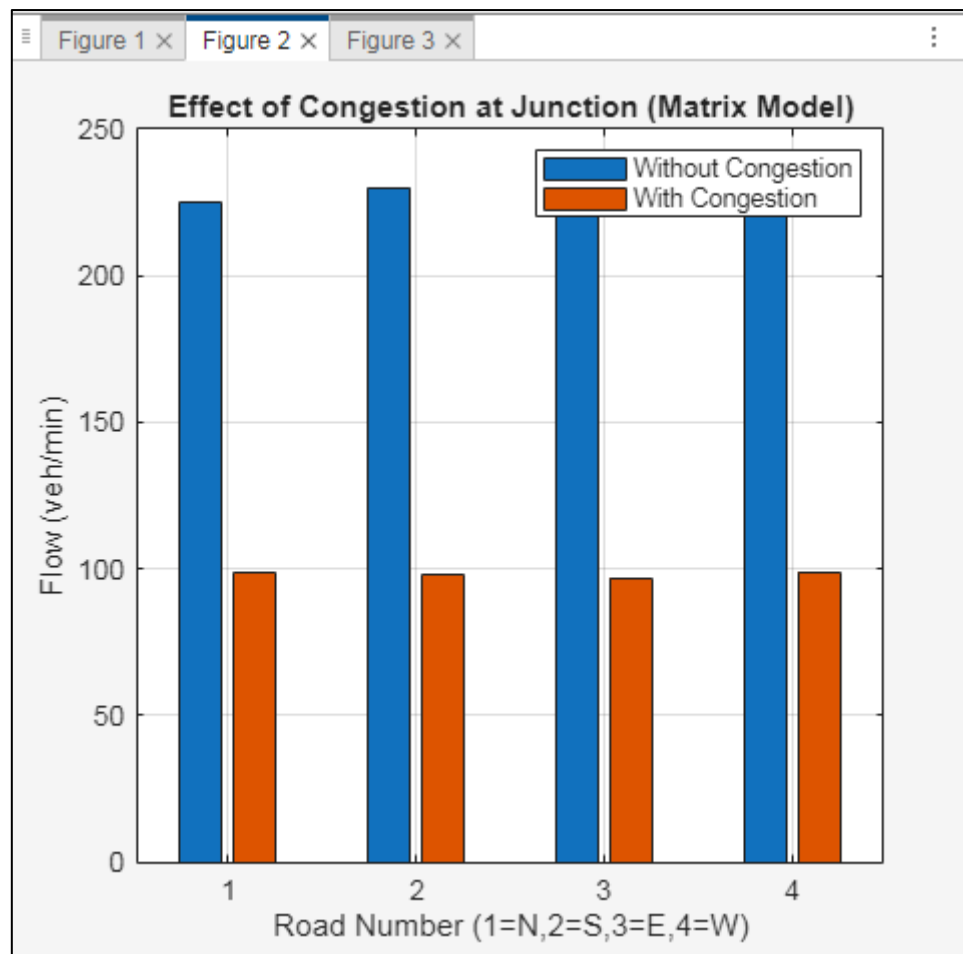
```

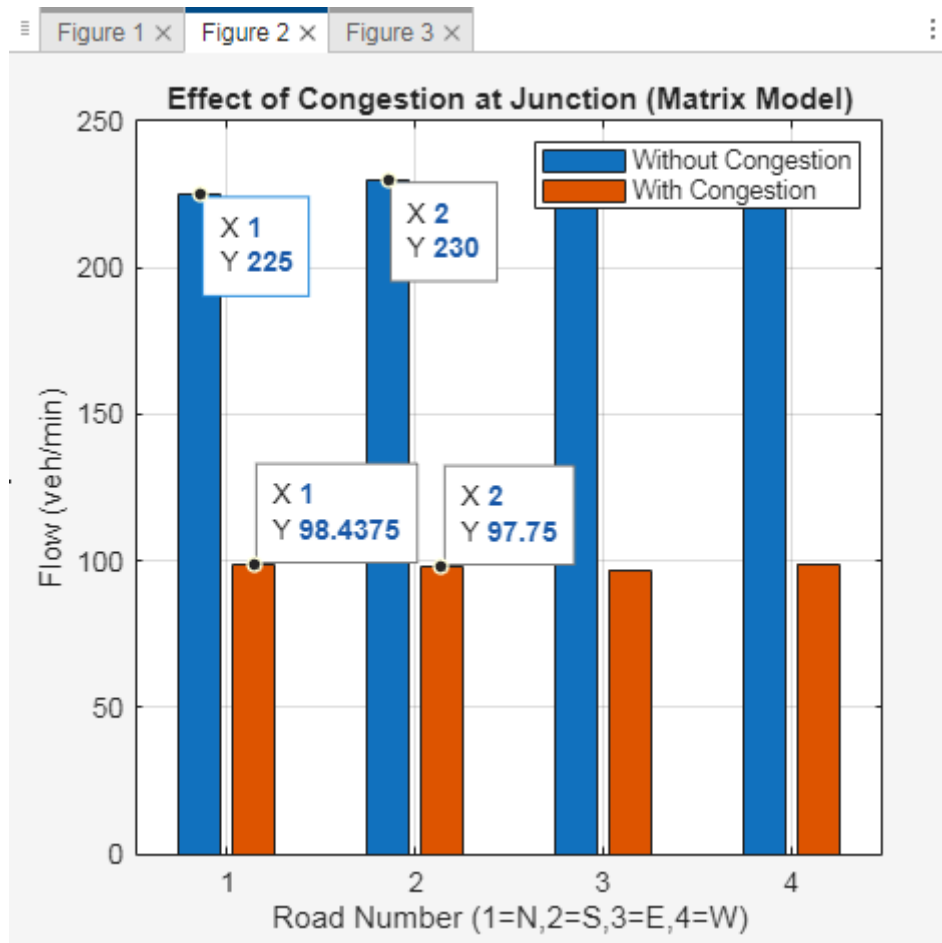
98.4375
97.7500
96.9375
99.0000

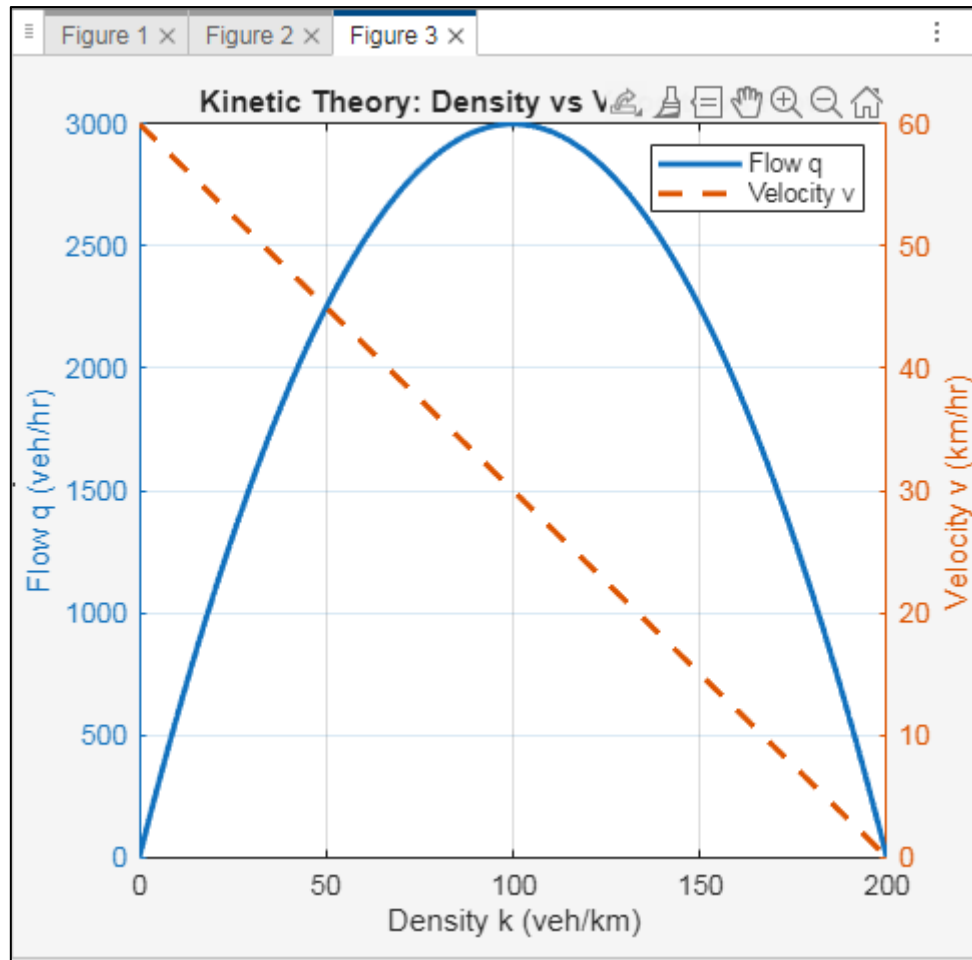
```

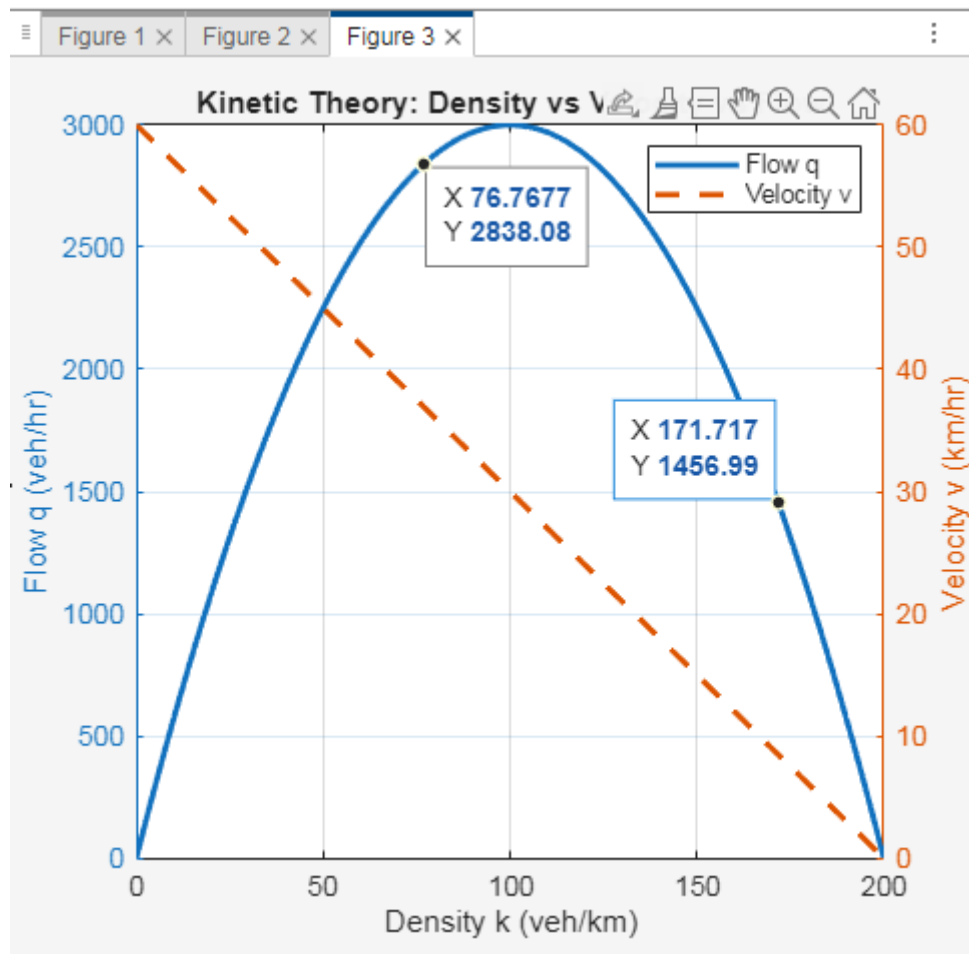
```
>>
```











CEL LAB (Case Study)

No. of vehicles (entering) = No. of vehicles (leaving)
4 Roads \rightarrow

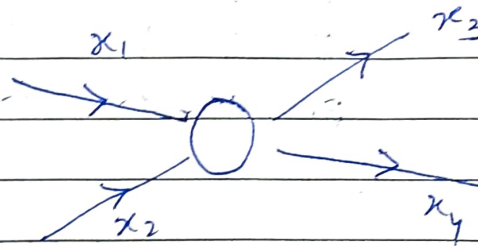
x_1, x_2 : Incoming traffic flows

x_3, x_4 : outgoing traffic flows

Conservatⁿ Law:

$$x_1 + x_2 = x_3 + x_4$$

$$x_1 + x_2 - x_3 - x_4 = 0$$

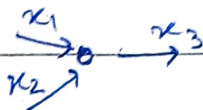


* Multiple Roads Junctⁿs

\rightarrow multiple eqⁿ

$x_1, x_2, x_3, x_4, x_5 \rightarrow$ Cars per hour on that road

@ Junctⁿ 1

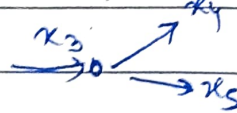


$$x_1 + x_2 = x_3$$

$$x_1 + x_2 - x_3 = 0$$

①

@ Junctⁿ 2

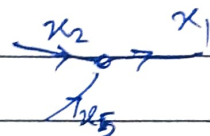


$$x_3 = x_4 + x_5$$

$$x_3 - x_4 - x_5 = 0$$

②

@ Junctⁿ 4



$$x_2 + x_5 = x_1$$

$$x_2 + x_5 - x_1 = 0$$

③

$$x_1 + x_2 - x_3 = 0$$

(Junctⁿ 1)

$$x_3 - x_4 - x_5 = 0$$

(Junctⁿ 2)

$$x_2 + x_5 - x_1 = 0$$

(Junctⁿ 3)

Putting in Matrix form

$$A \cdot x = b$$

Coeff. \downarrow \downarrow \downarrow
 of \downarrow unknown \downarrow zero vector
 some \downarrow Traffic \downarrow (because of
 flow \downarrow conservatⁿ)

$$A = \begin{matrix} & x_1 & x_2 & x_3 & x_4 & x_5 \\ \begin{bmatrix} 1 & 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & -1 \\ 0 & 1 & 0 & 0 & 1 \\ -1 & & & & \end{bmatrix} \end{matrix}$$

$$b = [0 \ 0 \ 0]$$

$$x = A/b$$

Kinetic
theory

4-Road Junction

(North, South, East, West)

Let:

 x_1 = flow from North to Junction (vehicle/min) x_2 = " " South " / " x_3 = " " East " / " x_4 = " " West " / "

At the Junction:

10% vehicle take U-Turn

20% turn Right

30% turn left

40% go straight

~~Out~~ Outgoing flow:

East exit = 180 vehicles

West " = ~~160~~ 16

North " = 150

South " = 170

* Conservation of vehicle

Total inflow = Total Outflow

e.g:

1) Vehicles leaving to East come from:1.) Straight from West (40% of x_4)2.) Left from North (30% of x_1)3.) Right " South (20% of x_2)4.) U-Turn " East (10% of x_3)

$$0.4x_4 + 0.3x_1 + 0.2x_2 + 0.1x_3 = 180$$

2) West exit

$$0.4x_3 + 0.3x_2 + 0.2x_1 + 0.1x_4 = 160$$

3) North exit

$$0.4x_2 + 0.3x_4 + 0.2x_3 + 0.1x_1 = 150$$

4) South exit

$$0.4x_1 + 0.3x_3 + 0.2x_4 + 0.1x_2 = 170$$

★ Matrix

$$A X = B$$

$$A = \begin{bmatrix} 0.3 & 0.2 & 0.1 & 0.4 \\ 0.2 & 0.3 & 0.4 & 0.1 \\ 0.1 & 0.4 & 0.2 & 0.3 \\ 0.4 & 0.1 & 0.3 & 0.2 \end{bmatrix}$$

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \quad B = \begin{bmatrix} 180 \\ 160 \\ 150 \\ 170 \end{bmatrix}$$

$$X = A \backslash B$$

Non-linear

↓
Congestion effect

$$\hookrightarrow F = x(1 - \alpha x)$$

↓
 $\alpha = 0.0005$

$$0.3x_1(1 - 0.0005x_1) + \dots$$

2) Kinetic theory

Flow = Density \times Velocity

$$q = kv$$

Assuming vel. \downarrow ses with density

$$v = v_{\max} \left(1 - \frac{k}{k_{\max}} \right)$$

then,

$$q = k v_{\max} \left(1 - \frac{k}{k_{\max}} \right)$$