MECHTRON/SFWR ENG 3DX4 Tutorial Quiz 1 Wednesday AM: Laplace Transforms review

1. Inverse Laplace Transforms (10 marks)

Laplace transform tables are on the back!

a) (5 marks) Assume that you are given a system $G_1(s) = \frac{Y(s)}{R(s)} = \frac{s+5}{(s+1)(s+2)^2}$. What is the steady state value of y(t) (i.e. $\lim_{t\to\infty} y(t)$), in response to a 5 unit step input (i.e. r(t) = 5u(t))?

$$(S+1)(S+2)^2=0 \rightarrow S+1=0$$
 3 $S+2=0 \rightarrow S=-1$, $S=-7$

Lo since both roots are non-positive, we can use final-value theorem

$$\lim_{t\to\infty} y(t) = \lim_{s\to 0} \left[\frac{s+s}{(s+1)(s+z)^2} \right] \cdot r(t)$$

$$y(\infty) = \frac{5}{4} \cdot 5 \quad \Rightarrow \quad y(\infty) = \frac{25}{4}$$

b) (5 marks) What is the time domain output, y(t) for the system $G_1(s)$, in response to a 5 unit step input (i.e. r(t) = 5u(t))?

$$\frac{(2+1)(2+2)_{5}}{2+2} = \frac{2+1}{4} + \frac{2+5}{13} + \frac{(2+5)_{5}}{6}$$

$$S + S = A(S+2)^2 + B(S+1)(S+2) + ((S+1)$$

$$\frac{5+5}{(5+1)(5+2)^2} = \frac{4}{5+1} - \frac{4}{5+2} - \frac{3}{(5+2)^2}$$

$$y(t) = \int_{-1}^{1} \left\{ \frac{4}{5+1} - \frac{4}{5+2} - \frac{3}{(5+2)^2} \right\} \cdot 5 \rightarrow y(t) = \left[\int_{-1}^{1} \left\{ \frac{4}{5+1} \right\} - \int_{-1}^{1} \left\{ \frac{4}{5+2} \right\} - \int_{-1}^{2} \left\{ \frac{3}{(5+2)^2} \right\} \right] \cdot 5$$

$$y(t) = \left[4e^{-t} - 4e^{-2t} - 3t e^{-2t} \right] \cdot 5 \rightarrow y(t) = 20e^{-t} - 20e^{-2t} - 15t e^{-2t}$$

tem no.	f(t)	F(s)
1.	$\delta(t)$	1
2.	u(t)	$\frac{1}{s}$
3.	tu(t)	$\frac{1}{s^2}$
4.	$t^n u(t)$	$\frac{n!}{s^{n+1}}$
5.	$e^{-at}u(t)$	$\frac{1}{s+a}$
6.	$\sin \omega t u(t)$	$\frac{\omega}{s^2+\omega^2}$
7.	$\cos \omega t u(t)$	$\frac{s}{s^2+\omega^2}$

ltem no.	Theorem		Name
1.	$\mathcal{L}[f(t)] = F(s)$	$= \int_{0-}^{\infty} f(t)e^{-st}dt$	Definition
2.	$\mathcal{L}[kf(t)]$	= kF(s)	Linearity theorem
3.	$\mathcal{L}[f_1(t) + f_2(t)]$	$= F_1(s) + F_2(s)$	Linearity theorem
4.	$\mathcal{L}[e^{-at}f(t)]$	= F(s+a)	Frequency shift theorem
5.	$\mathcal{L}[f(t-T)]$	$= e^{-sT}F(s)$	Time shift theorem
6.	$\mathcal{L}[f(at)]$	$=\frac{1}{a}F\left(\frac{s}{a}\right)$	Scaling theorem
7.	$\mathscr{L}\left[\frac{df}{dt}\right]$	= sF(s) - f(0-)	Differentiation theorem
8.	$\mathcal{L}\left[\frac{d^2f}{dt^2}\right]$	$= s^2 F(s) - s f(0-) - \dot{f}(0-)$	Differentiation theorem
9.	$\mathscr{L}\left[\frac{d^nf}{dt^n}\right]$	$= s^{n}F(s) - \sum_{k=1}^{n} s^{n-k}f^{k-1}(0-)$	Differentiation theorem
10.	$\mathscr{L}\left[\int_{0-}^{t} f(\tau) d\tau\right]$	$=\frac{F(s)}{s}$	Integration theorem
11.	$f(\infty)$	$= \lim_{s \to 0} sF(s)$	Final value theorem ¹
12.	<i>f</i> (0+)	$= \lim_{s \to \infty} sF(s)$	Initial value theorem ²

For this theorem to yield correct finite results, all roots of the denominator of F(s) must have negative real parts and no more than one can be at the origin. For this theorem to be valid, f(t) must be continuous or have a step discontinuity at t=0 (i.e., no impulses or their derivatives at t=0).