Lecture #32

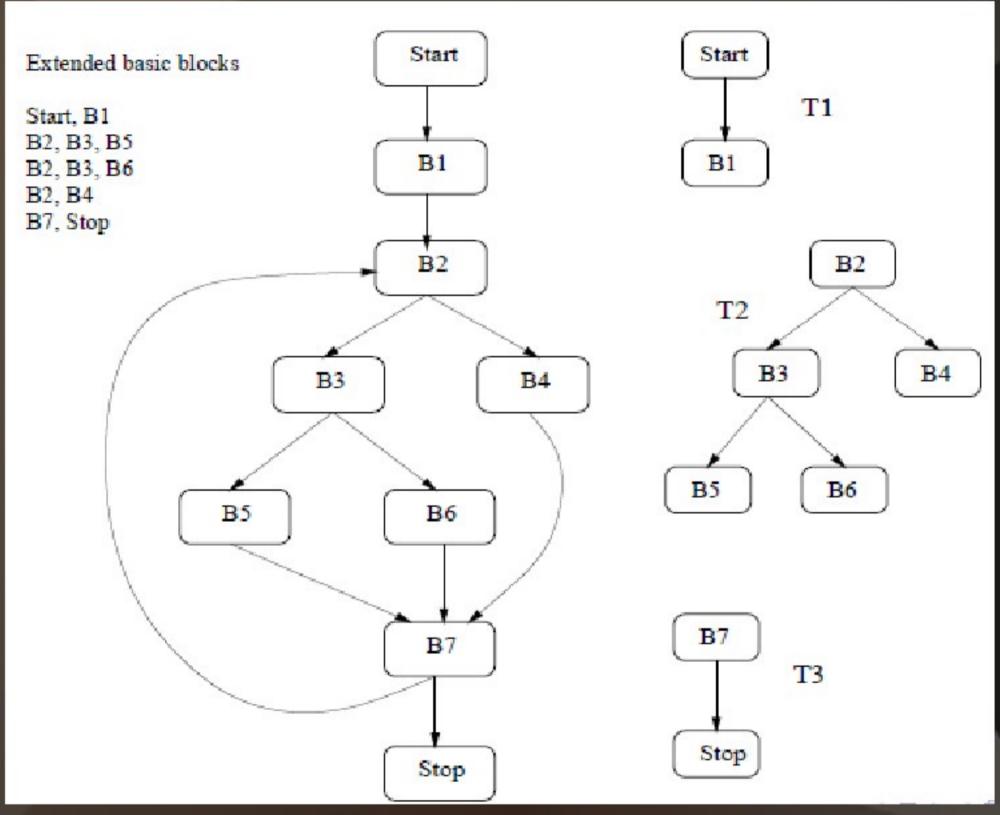
Code Optimization

CSE346: Compilers, IIT Guwahati

Extended Basic Blocks

- A sequence of basic blocks $B_1, B_2, ... B_k$, such that B_i is the unique predecessor of $B_{i+1} (1 \le i < k)$, and B_1 is either the start block or has no unique predecessor
- Extended basic blocks with shared blocks can be represented as a tree
- Shared blocks in extended basic blocks require scoped versions of tables
- The new entries must be purged and changed entries must be replaced by old entries
- Preorder traversal of extended basic block trees is used

Extended Basic Blocks



Extended Basic Blocks

```
function visit-ebb-tree(e) // e is a node in the tree
begin
  // From now on, the new names will be entered with a new scope into the tables.
  // When searching the tables, we always search beginning with the current scope
  // and move to enclosing scopes. This is similar to the processing involved with
  // symbol tables for lexically scoped languages
  value-number(e.B);
  // Process the block e.B using the basic block version of the algorithm
  if (e.left \neq null) then visit-ebb-tree(e.left);
  if (e.right \neq null) then visit-ebb-tree(e.right);
  remove entries for the new scope from all the tables
  and undo the changes in the tables of enclosing scopes;
end
begin // main calling loop
  for each tree t do visit-ebb-tree(t);
  //t is a tree representing an extended basic block
end
```

Peephole Optimization

- A machine dependent optimization technique
- Peephole optimizations are replacement rules of the form:

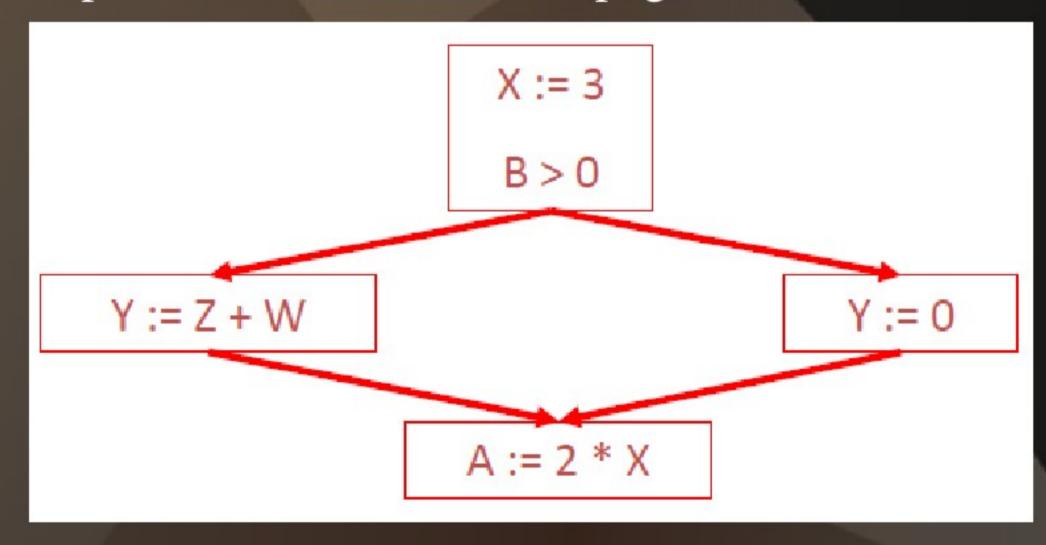
$$i_1, ..., i_n \rightarrow j_1, ..., j_m$$

where the RHS is the improved version of the LHS

- Example:
 - move a \$b, move a \$b a \rightarrow move a \$b
 - Works if move \$b \$a is not the target of a jump
- Another example
 - addiu \$a \$a i, addiu \$a \$a j → addiu \$a \$a i+j

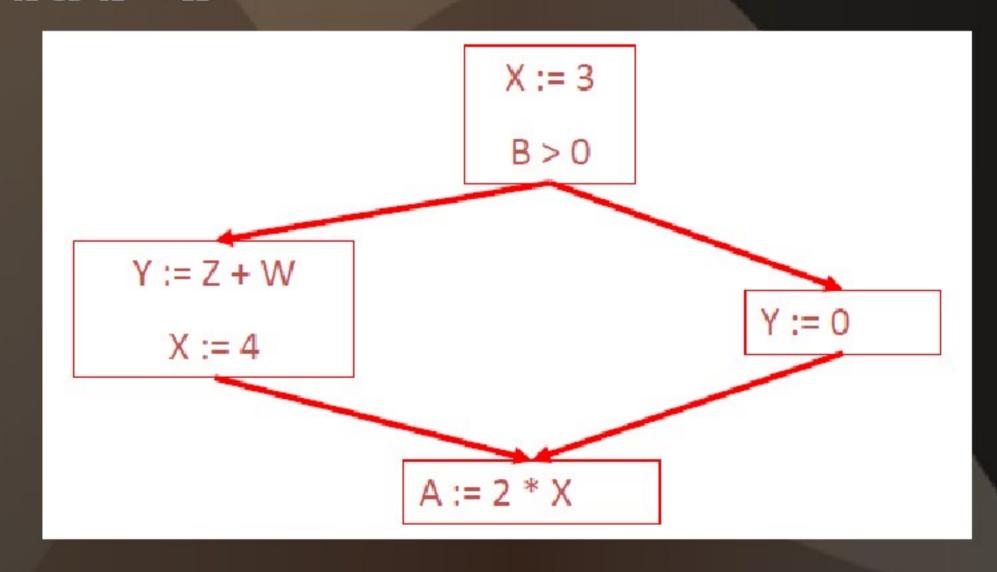
Dataflow Analysis

- Simple optimizations over a basic block may be extended over the entire CFG
- Example: Global Constant Propagation



Dataflow Analysis

- To replace a use of x by a constant k we must know:
 - On every path to the use of \mathbf{x} , the last assignment to \mathbf{x} is $\mathbf{x} = \mathbf{k}$

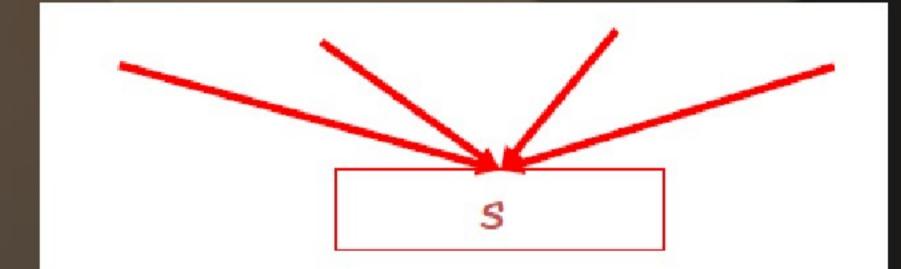


Global Optimization

- The correctness condition is not trivial to check
 - Paths include paths around loops and through branches of conditionals
- Generally global optimization depends on knowing a property X at a particular point in program execution
 - Proving X at any point requires knowledge of the entire program
- It is OK to be conservative. If the optimization requires X to be true, then want to know either
 - X is definitely true
 - Don't know if **X** is true
 - It is always safe to say "don't know"

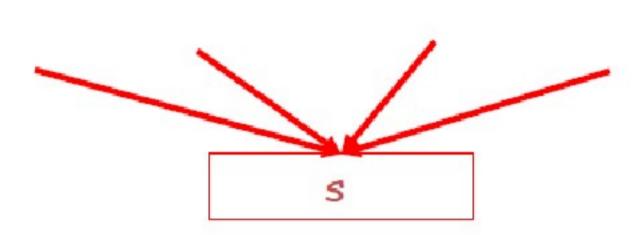
- We must know whether:
 - On every path to the use of x, the last assignment to x is x = k
- We associate one of the following values with x at every program point:
 - \(\preceq\) (Bottom): This statement never executes
 - C : x equals to constant C
 - T (Top) : x is not a constant
- For each statement s, the value of x immediately before and after x is calculated
 - C(s, x, in): Value of x before s
 - C(s, x, out): Value of x after s

• Rule #1



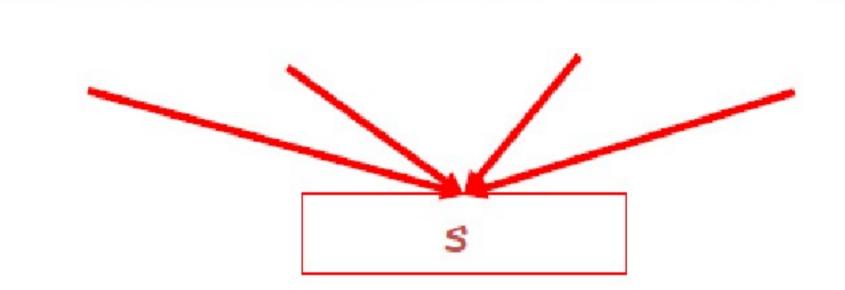
if $C(p_i, x, out) = T$ for any i, then C(s, x, in) = T

• Rule #2

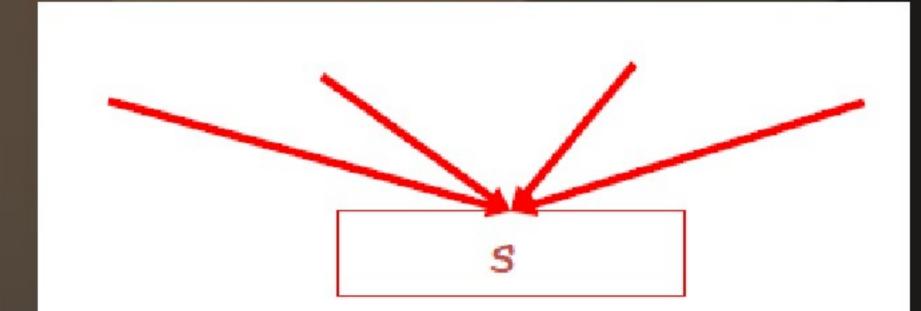


if $C(p_i, x, out) = c & C(p_j, x, out) = d & d <> c$ then C(s, x, in) = T

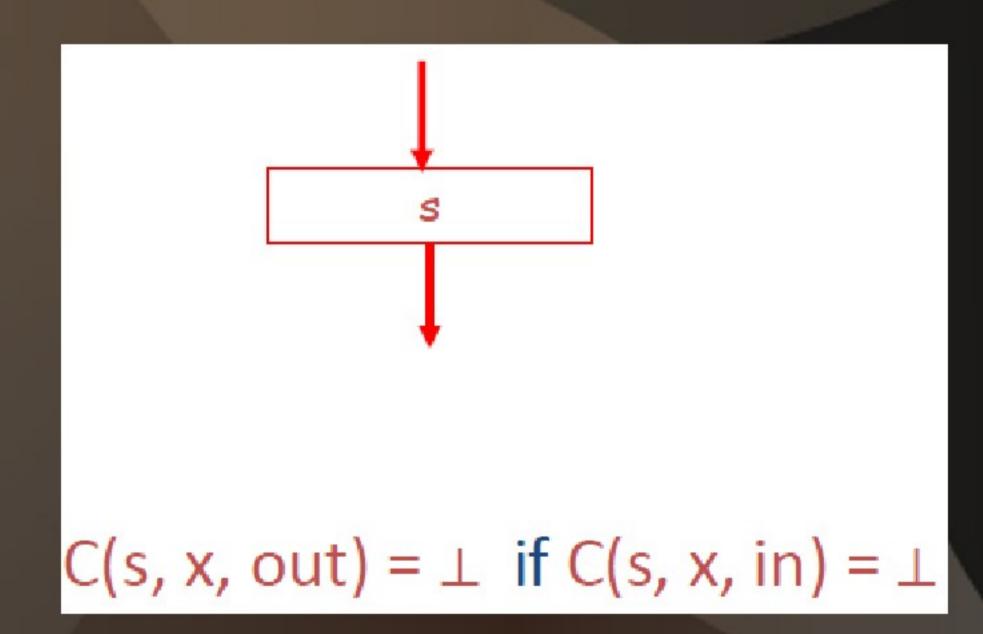
• Rule #3



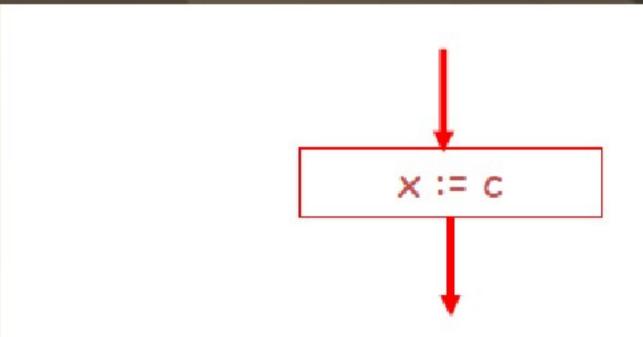
if $C(p_i, x, out) = c$ or \bot for all i, then C(s, x, in) = c



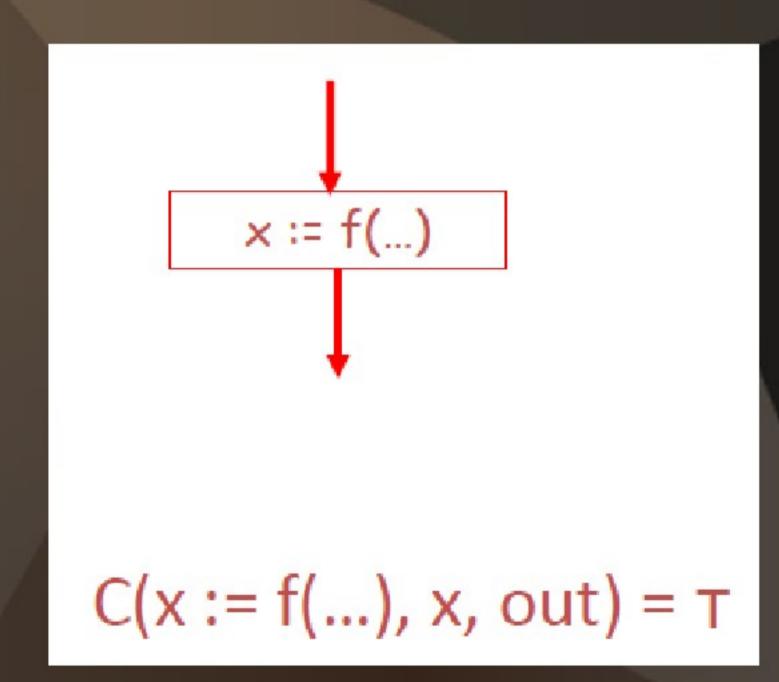
if
$$C(p_i, x, out) = \bot$$
 for all i,
then $C(s, x, in) = \bot$

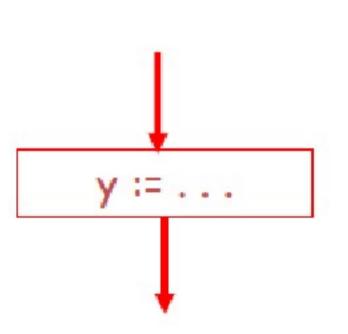


• Rule #6



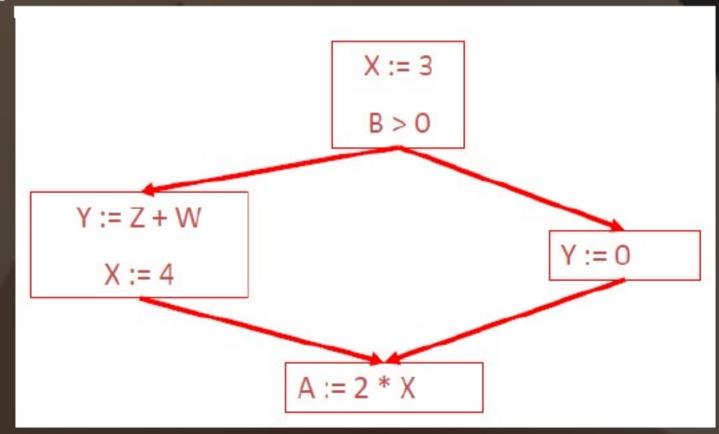
C(x := c, x, out) = c if c is a constant





$$C(y := ..., x, out) = C(y := ..., x, in) if x <> y$$

- For every entry s to the program, set C(s, x, in) = T
- Set $C(s, x, in) = C(s, x, out) = \bot$ everywhere else
- Repeat until all points satisfy 1-8:
 - Pick s not satisfying 1-8 and update using the appropriate rule



Analysis of Loops

 How can global constant propagation for the following CFG be performed?

