

Lecture #30

Code Optimization

Code Optimization

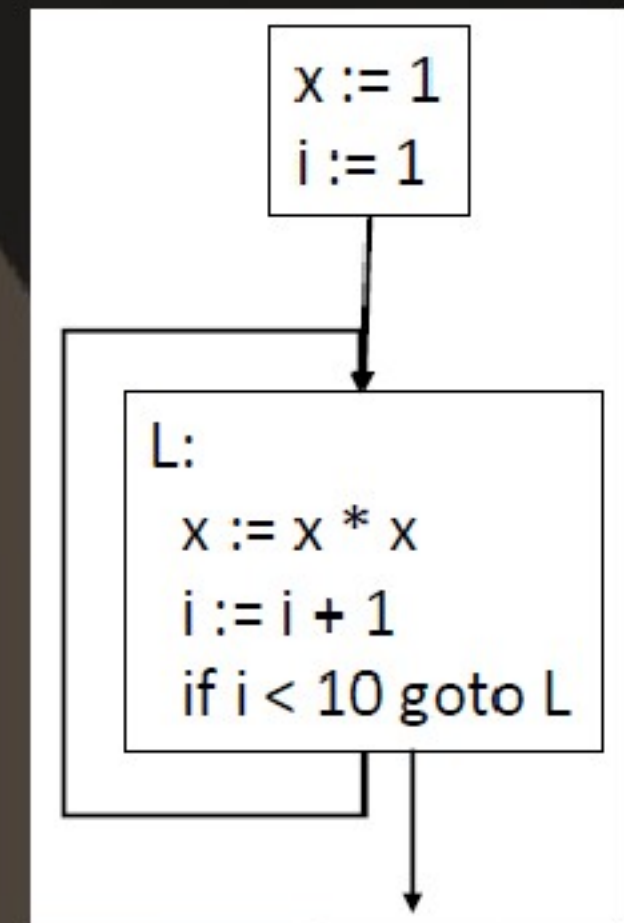
- Most complexity in modern compilers is in the optimizer
 - Also by far the largest phase
- Optimizations can be performed on
 - AST / DAG
 - Machine independent optimization
 - Assembly code
 - Target dependent optimization
 - On an intermediate language

Basic Blocks

- A basic block is a maximal sequence of instructions with:
 - no labels (except at the first instruction), and
 - no jumps (except in the last instruction)
- Idea:
 - Cannot jump into a basic block (except at beginning)
 - Cannot jump out of a basic block (except at end)
 - A basic block is a single-entry, single-exit, straight-line code segment
- *The property of sequential control flow can be useful for many optimizations.*

Control Flow Graphs

- Control-Flow Graph (CFG)
 - Models the way that the code transfers control between blocks in the procedure.
 - *Node*: a single basic block
 - *Edge*: transfer of control between basic blocks.
 - All *return* nodes are terminal



Code Optimization

- Optimization seeks to improve a program's resource utilization
 - Execution time (most often)
 - Code size
 - Network messages sent
 - Memory Usages
 - Disk Accesses
 - Power
- Optimization should not alter what the program computes
 - *The answer before and after optimization must remain same*

Code Optimization

- There are three granularities of optimizations
 - Local optimizations
 - Apply to a basic block in isolation
 - Global optimizations
 - Apply to a control-flow graph (method body) in isolation
 - Inter-procedural optimizations
 - Apply across method boundaries
- *Most compilers do local and global optimizations but not the third*
- Often a conscious decision is made not to implement the fanciest optimization known
 - Goal: Maximum benefit for minimum cost

Code Optimization

- There are three granularities of optimizations
 - Local optimizations
 - Apply to a basic block in isolation
 - Global optimizations
 - Apply to a control-flow graph (method body) in isolation
 - Inter-procedural optimizations
 - Apply across method boundaries
- *Most compilers do local and global optimizations but not the third*
- Often a conscious decision is made not to implement the fanciest optimization known
 - Goal: Maximum benefit for minimum cost

Local Optimization

- Constant Folding
 - Evaluation at compile-time of expressions whose operands are known to be constant
 - Example

$a = 10 * 5 + 6 - b;$



```
t0 = 10 ;  
t1 = 5 ;  
t2 = t0 * t1 ;  
t3 = 6 ;  
t4 = t2 + t3 ;  
t5 = t4 - b ;  
a = t5 ;
```



```
t0 = 56 ;  
t1 = t0 - b ;  
a = t1 ;
```


Local Optimization

- Constant Propagation

- If a variable is assigned a constant value, then subsequent uses of that variable can be replaced by the constant as long as no intervening assignment has changed the value of the variable.

- Example:

```
t0 = 12 ;  
t1 = arr + t0 ;  
t2 = *(t1) ;
```

```
li $t0, 12  
lw $t1, 8($fp)  
add $t2, $t1, $t0  
lw $t3, 0($t2)
```



Constant propagation +
rearrangement cuts no. of
regs. and insns. from 4 to 2

```
t0 = *(arr + 12) ;
```

```
lw $t0, -8($fp)  
lw $t1, 12($t0)
```

Local Optimization

- Algebraic simplification and Reassociation
 - Simplifications use algebraic properties or particular operator-operand combinations to simplify expressions.
 - Reassociation refers to using properties such as associativity, commutativity and distributivity to rearrange an expression to enable other optimizations

Local Optimization

- Algebraic simplification and Reassociation

- Simplification Examples:

$x+0 = x$ $0+x = x$ $x*1 = x$ $1*x = x$ $0/x = 0$ $x-0 = x$
 $b \ \&\& \ \text{true} = b$ $b \ \&\& \ \text{false} = \text{false}$
 $b \ \|\ \text{true} = \text{true}$ $b \ \|\ \text{false} = b$

- Example: Re-arrangement + constant folding

$b = 5 + a + 10 ;$



$t0 = 5 ;$
 $t1 = t0 + a ;$
 $t2 = t1 + 10 ;$
 $b = t2 ;$



$t0 = 15 ;$
 $t1 = a + t0 ;$
 $b = t1 ;$

Local Optimization

- Operator Strength Reduction
 - Replaces an operator by a "less expensive" one
 - Often performed as part of *loop-induction variable elimination*
 - Example:

```
while (i < 100)
{
    arr[i] = 0;
    i = i + 1;
}
```



```
t1 = i;
L0:
If t1>100 Goto L1 ;
t2 = 4 * t1 ;
t3 = arr + t2 ;
*(t3) = 0 ;
t1 = t1 + 1 ;
Jump L0
L1:
```



```
t1 = arr ;
L0: If i > 100 Goto L1 ;
* t1 = 0;
t1 = t1 + 4;
i = i + 1 ;
L1:
```


Local Optimization

- Copy Propagation
 - Similar to constant propagation, but generalized to non-constant values
 - For $a = b$, we can replace later occurrences of a with b (assuming there are no changes to either variable in-between)
 - Example

```
t2 = t1 ;  
t3 = t2 * t1 ;  
t4 = t3 ;  
t5 = t3 * t2 ;  
c = t5 + t4 ;
```



```
t3 = t1 * t1 ;  
t5 = t3 * t1 ;  
c = t5 + t3 ;
```