

# Sadman Kazi

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## SKILLS

### PROGRAMMING

#### PROFICIENT WITH:

Java • C • C++ • Python

#### FAMILIAR WITH:

Javascript • C# • GLSL

#### APIs & SDKs:

OpenGL • Android • SDL • GTK+

### OTHER

#### TOOLS:

Visual Studio • Vim • Git • Unix Shell

#### GAME ENGINES:

Unity3d • Unreal • Godot

## EDUCATION

### UNIVERSITY OF WATERLOO

#### CANDIDATE FOR BACHELOR OF SOFTWARE ENGINEERING (CO-OP)

2014 - 2019 (Expected) | Waterloo, ON

##### Relevant Courses:

- Programming Fundamentals
- Introduction to Data Abstraction and Implementation
- Sequential Programming
- Digital Computers

### MARC GARNEAU CI

2011 - 2014 | Toronto, ON

#### Activities:

Founder and President of

- Physics Club (2013-2014)
- Guitar Club (2013-2014)

Vice President of

- Table Tennis Club (2012-2014)

## AWARDS

### 2015

Second Place Mobility Challenge

Fourth Place Microassembly Challenge

IEEE Micro/Nano Robotics & Automation Technical Committee

People's Choice Award

UWaterloo EngHack Winter 2015

### 2014

President's Scholarship of Distinction

University of Waterloo

First

Math Olympiad, MIST Toronto

Calculus and Vectors Award

Data Management Award

Marc Garneau CI

## TECHNICAL EXPERIENCE

### D{ LAB

#### SOFTWARE PRODUCT PROTOTYPING | C • C++ • PYTHON

May 2015 – August 2015 | Kitchener, ON

Worked with an engineering team to develop a real-time communication architecture prototype for large-scale sensor networks from the ground up.

- Worked in a team of two to deploy a mesh network communication system
- Designed and implemented the offline software architecture
- Optimized the platform to ensure that data is pushed to the cloud in real time
- Developed an interface for an OLED screen and input registry

### UNIVERSITY OF WATERLOO NANO-ROBOTICS GROUP

#### CONTROLS TEAM MEMBER | PYTHON • GLADE • OPENCV • C#

September 2014 – Present | Waterloo, ON

Part of a small team responsible for controlling the robot through software.

- Implemented the controlling of actuators and magnetic field activation which is used to control a micro robot with gamepad input
- Competed at ICRA 2015 in Seattle as a member of the debugging team
- Currently porting the project to use multiple threads

## NOTABLE PROJECTS

### 3D GAME ENGINE | C++ • GLSL • OPENGGL • SDL

April 2015 - Present | Personal Side Project

An open source WIP 3d game engine.

- Currently functional: shader compilation, mesh rendering, game loop for the core engine, keyboard and mouse input handling, and camera control

### MYO GUITAR | JAVA • ANDROID SDK

March 2015 | Developed at EngHack Winter 2015

An Android air guitar app that uses the screen as the frets and a Myo armed hand for strumming.

- Created the algorithms to detect and play the pressed notes dynamically
- Implemented noise filters to mute specific strings when playing specific chords

### CITY KIT | JAVASCRIPT • GOOGLE MAPS API • HTML • CSS

November 2014 | Developed at the 24 hour Start-up hackathon

An online service that pulls data from Yelp database using JSON

- Created the module that serviced ads using the Google Maps API and the geolocation code

### MYO PAD | C++ • MYO SDK

October 2014 | Developed at EngHack Fall 2014

A program using the Myo armband that exports drawings/writing on a surface to graphical interface on a computer.

- Created the module that received data from the armband using the Myo SDK
- Developed the main interface that took that data to draw, erase and move the cursor on the screen.

### ECLIPSE | UNITY3D • C#

July 2014 - August 2014 | Personal side project

An open source 3d game for android made using the Unity3d engine.

- Developed everything independently, including but not limited to scripting, modelling, lighting, and texturing