Computer Vision and Image Processing (EC 336)

Lecture 2: Introduction and Fundamentals

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Outline

- Few interesting images from past
- Light sources
- Examples of different types of images
- Spatial and intensity resolution
- Basic relationships between pixels

Few Interesting images

FIGURE 1.1 A digital picture produced in 1921 from a coded tape by a telegraph printer with special type faces. (McFarlane.†)

Sent by submarine cable between London and New York, the transportation time was reduced to less than three hours from more than a week

Few Interesting images

FIGURE 1.4 The first picture of the moon by a U.S. spacecraft. *Ranger 7* took this image on July 31, 1964 at 9 : 09 A.M. EDT, about 17 minutes before impacting the lunar surface. (Courtesy of NASA.)

Sources for Images

- Electromagnetic (EM) energy spectrum
- Acoustic
- Ultrasonic
- Electronic
- Synthetic images produced by computer

Electromagnetic (EM) energy spectrum

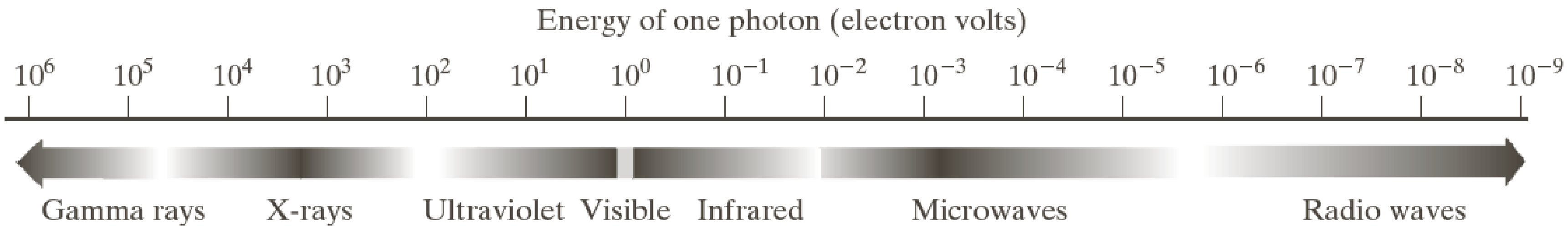
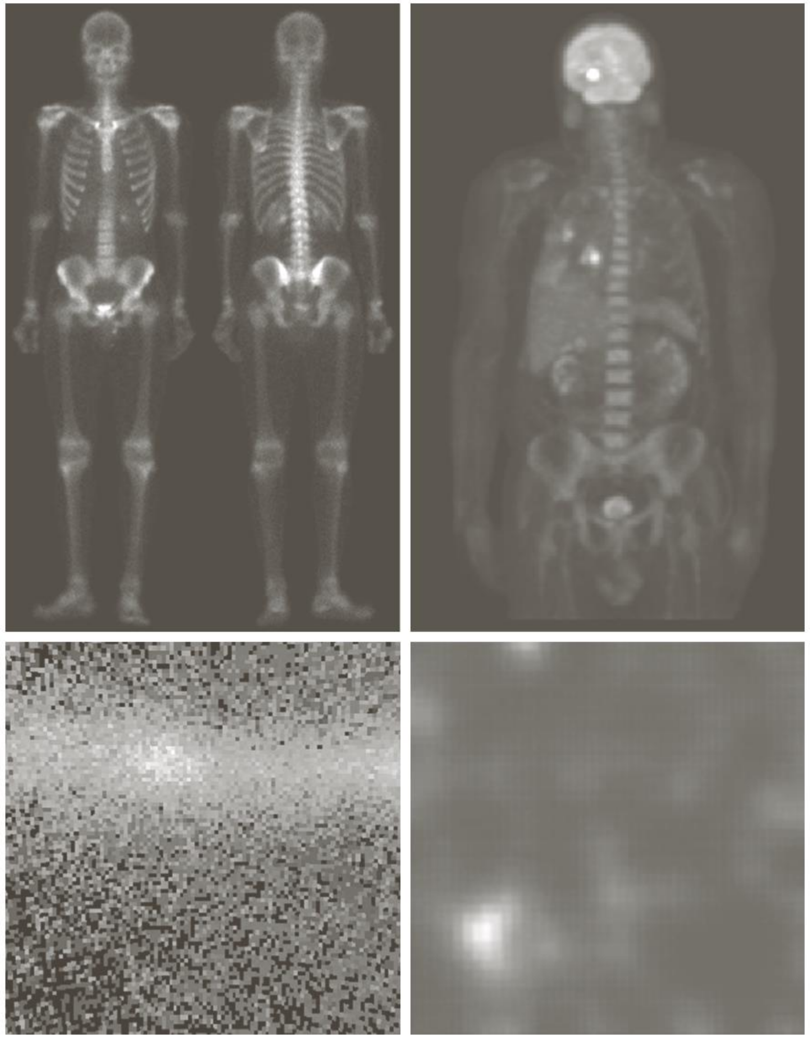


FIGURE 1.5 The electromagnetic spectrum arranged according to energy per photon.

Major uses

- **Gamma-ray imaging**: nuclear medicine and astronomical observations
- **X-rays**: medical diagnostics, industry, and astronomy, etc.
- **Ultraviolet**: lithography, industrial inspection, microscopy, lasers, biological imaging,and astronomical observations
- **Visible and infrared bands**: light microscopy, astronomy, remote sensing, industry, and law enforcement
- **Microwave band**: radar
- **Radio band**: medicine (such as MRI) and astronomy

Examples: Gama-Ray Imaging



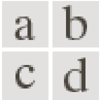
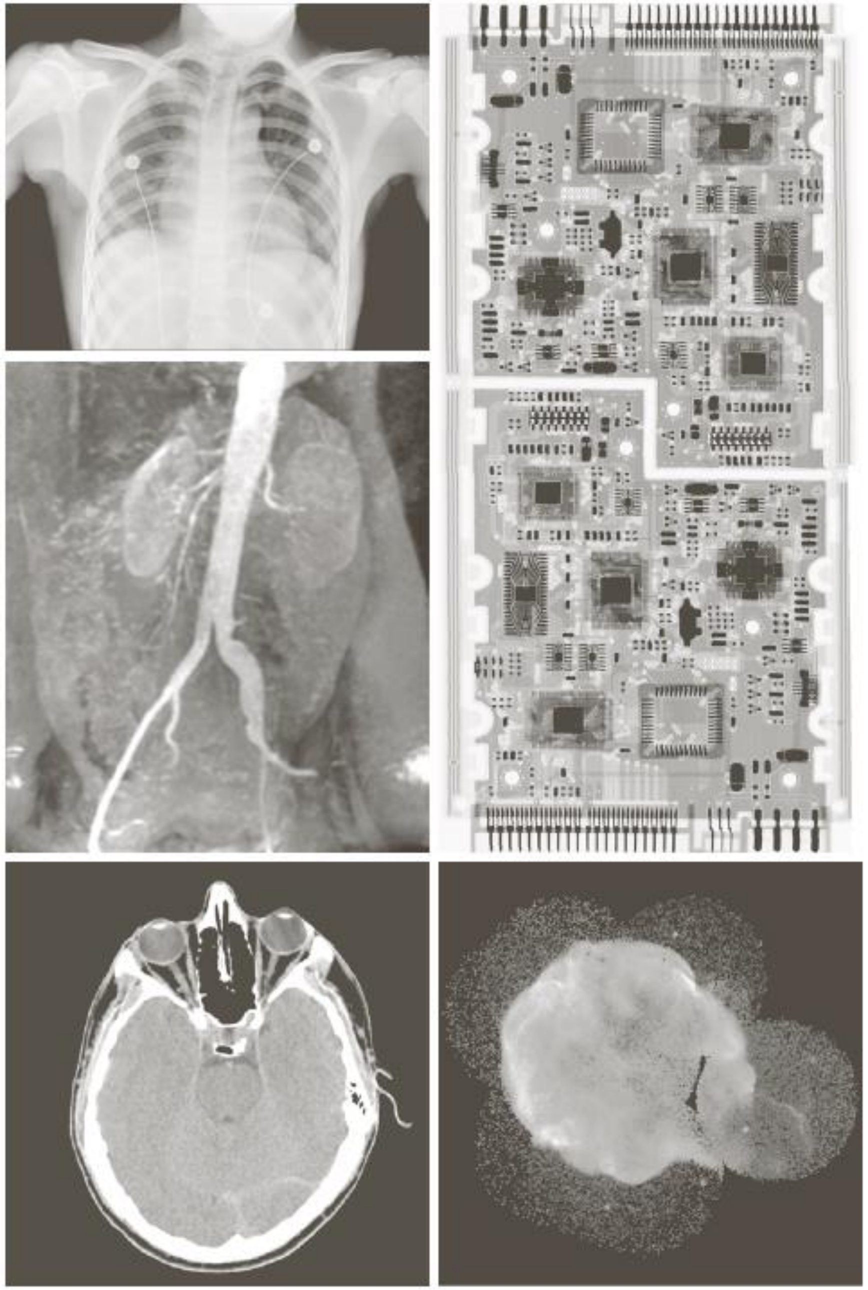


FIGURE 1.6 Examples of gamma-ray imaging. (a) Bone scan. (b) PET image. (c) Cygnus Loop. (d) Gamma radiation (bright spot) from a reactor valve. (Images courtesy of (a) G.E. Medical Systems, (b) Dr. Michael E. Casey, CTI PET Systems, (c) NASA, (d) Professors Zhong He and David K. Wehe, University of Michigan.)

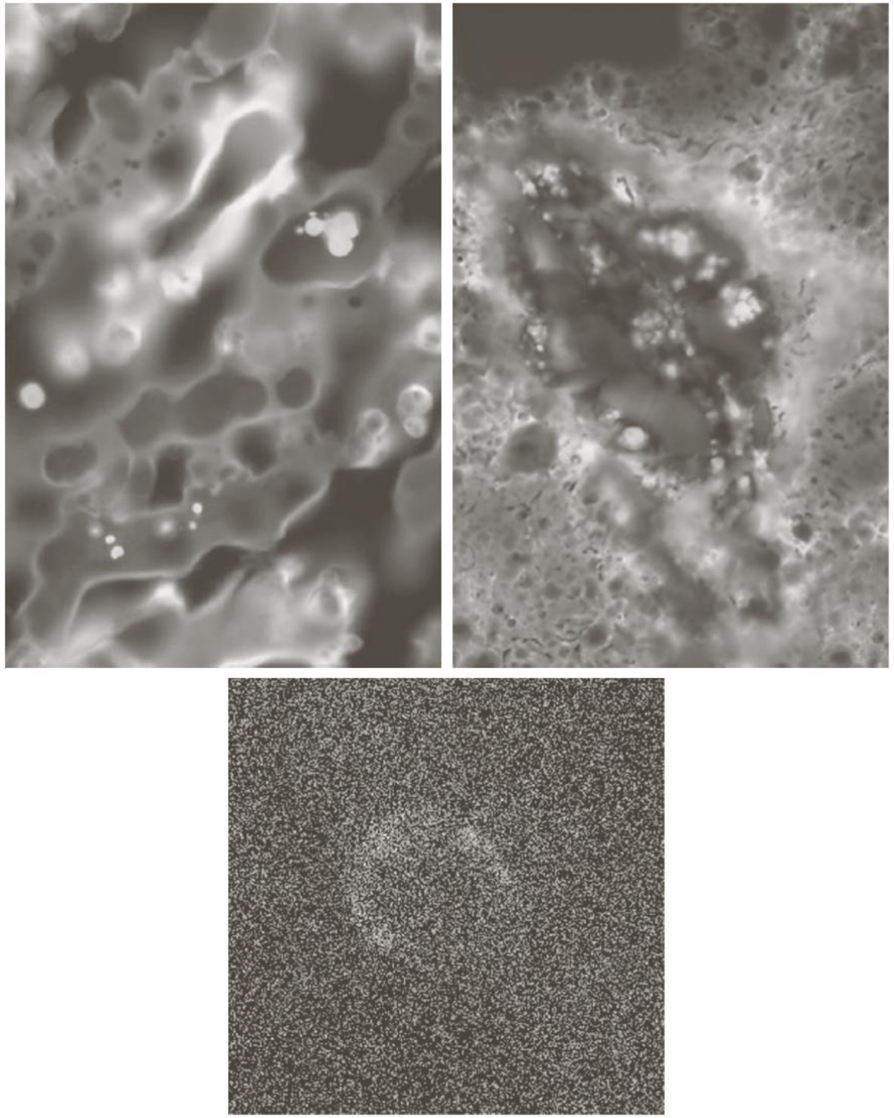
Examples: X-Ray Imaging



a d
b
c e

FIGURE 1.7 Examples of X-ray imaging. (a) Chest X-ray. (b) Aortic angiogram. (c) Head CT. (d) Circuit boards. (e) Cygnus Loop. (Images courtesy of (a) and (c) Dr. David R. Pickens, Dept. of Radiology & Radiological Sciences, Vanderbilt University Medical Center; (b) Dr. Thomas R. Gest, Division of Anatomical Sciences, University of Michigan Medical School; (d) Mr. Joseph E. Pascente, Lixi, Inc.; and (e) NASA.)

Examples: Ultraviolet Imaging



a b
c

FIGURE 1.8 Examples of ultraviolet imaging. (a) Normal corn. (b) Smut corn. (c) Cygnus Loop. (Images courtesy of (a) and (b) Dr. Michael W. Davidson, Florida State University, (c) NASA.)

Examples: Light Microscopy Imaging

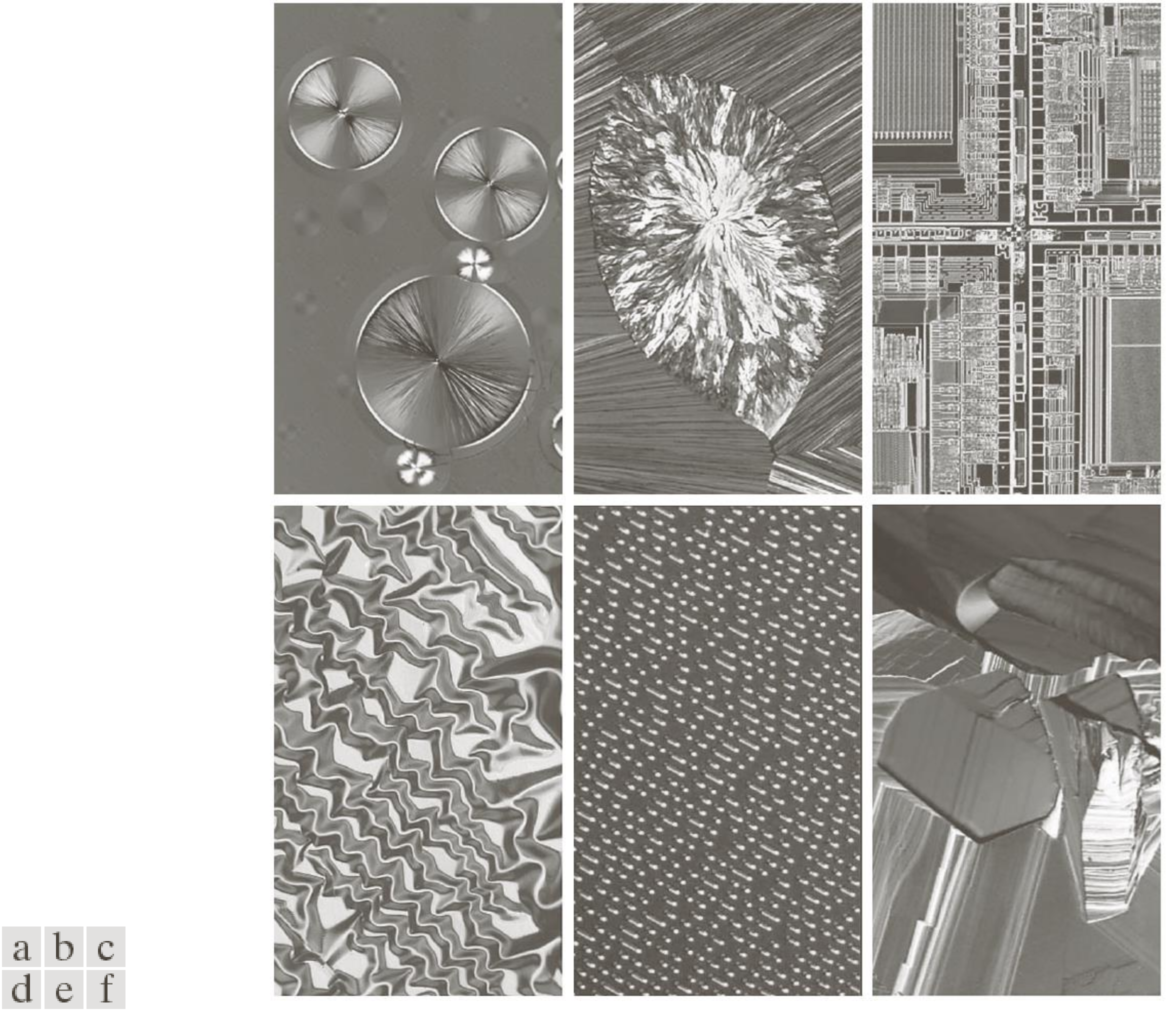


FIGURE 1.9 Examples of light microscopy images. (a) Taxol (anticancer agent), magnified 250×. (b) Cholesterol—40×. (c) Microprocessor—60×. (d) Nickel oxide thin film—600×. (e) Surface of audio CD—1750×. (f) Organic superconductor—450×. (Images courtesy of Dr. Michael W. Davidson, Florida State University.)

Examples: Visual and Infrared Imaging

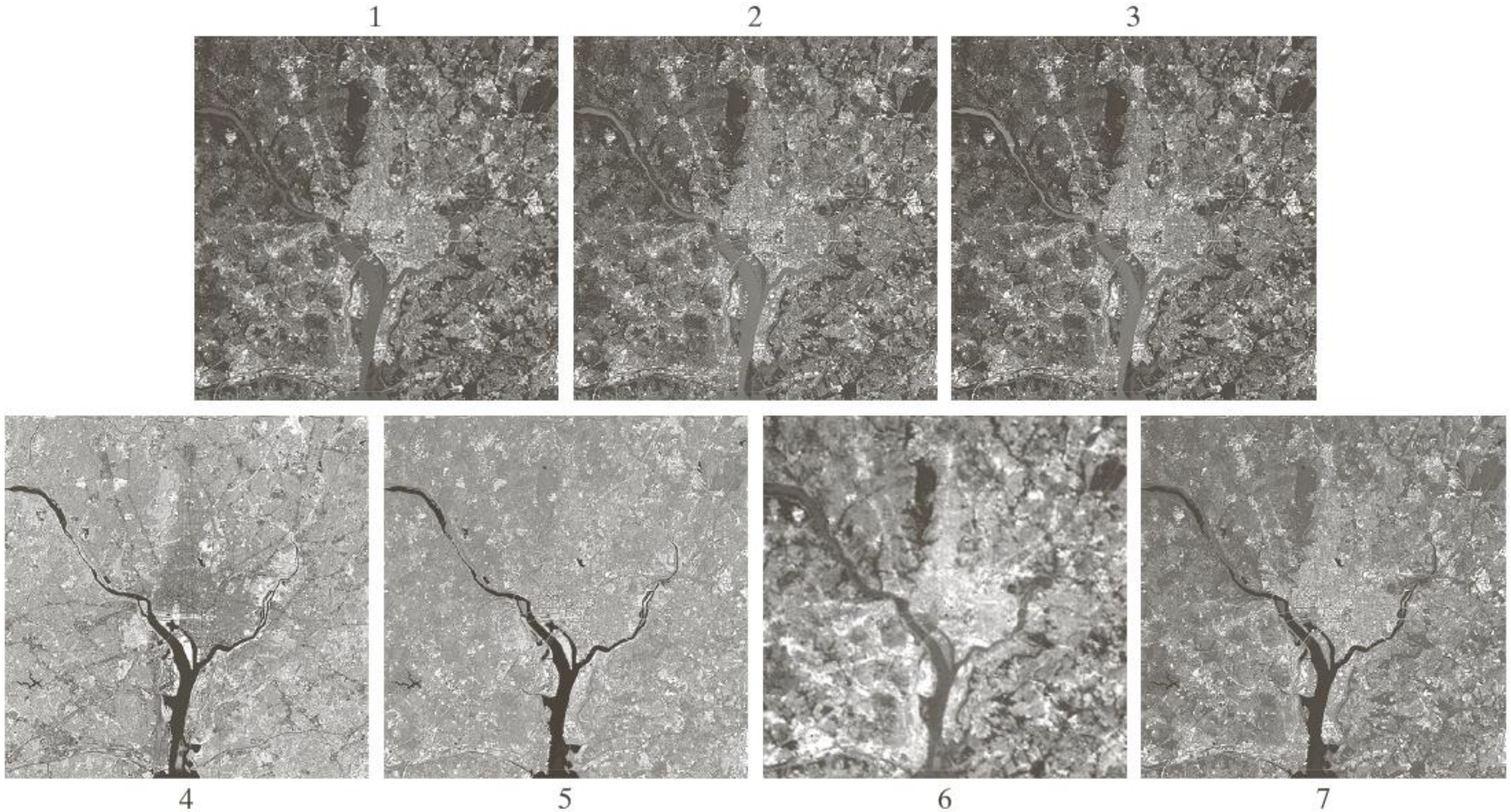


FIGURE 1.10 LANDSAT satellite images of the Washington, D.C. area. The numbers refer to the thematic bands in Table 1.1. (Images courtesy of NASA.)

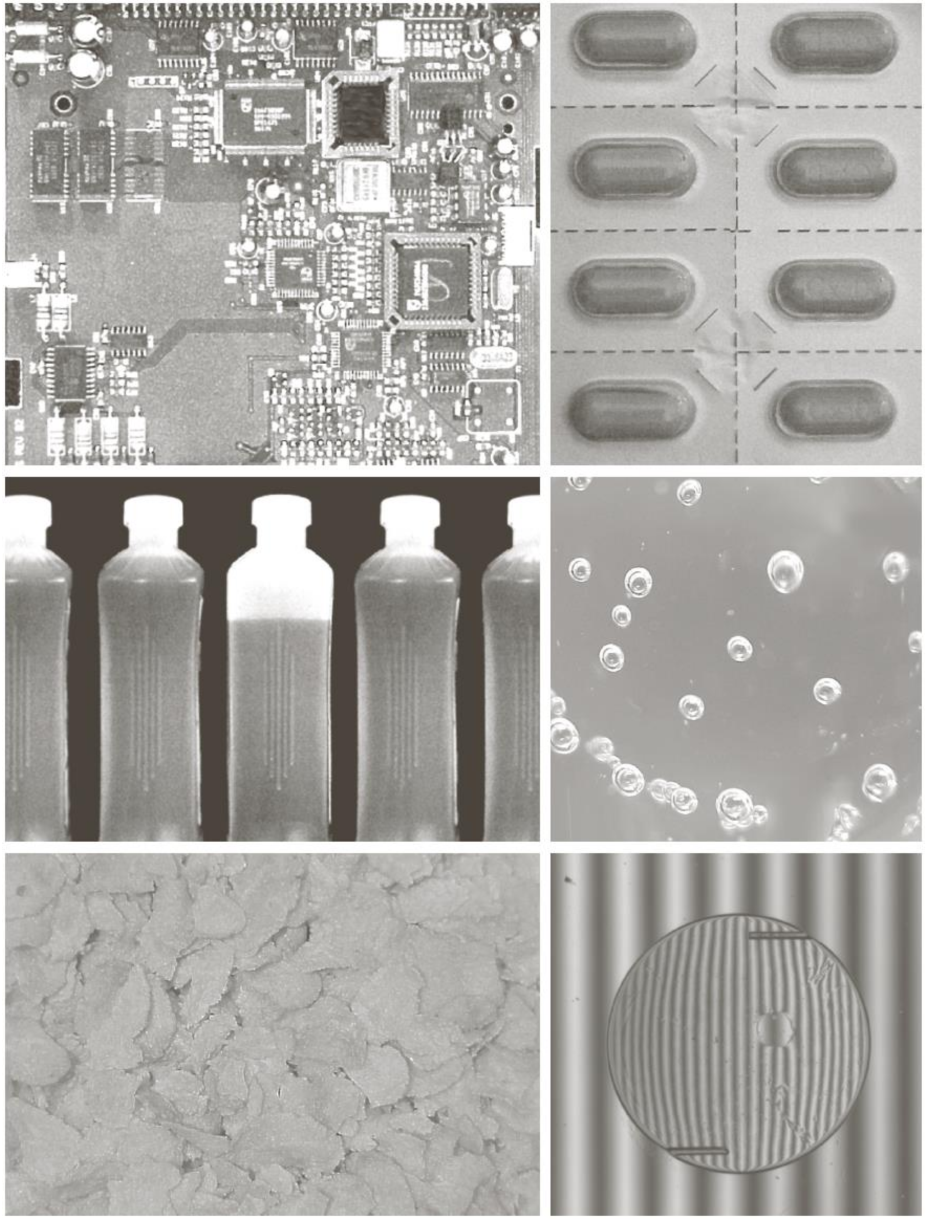
Examples: Visual and Infrared Imaging

TABLE 1.1 Thematic bands in NASA's LANDSAT satellite.

Band No.	Name	Wavelength (μm)	Characteristics and Uses
1	Visible blue	0.45–0.52	Maximum water penetration
2	Visible green	0.52–0.60	Good for measuring plant vigor
3	Visible red	0.63–0.69	Vegetation discrimination
4	Near infrared	0.76–0.90	Biomass and shoreline mapping
5	Middle infrared	1.55–1.75	Moisture content of soil and vegetation
6	Thermal infrared	10.4–12.5	Soil moisture; thermal mapping
7	Middle infrared	2.08–2.35	Mineral mapping

Examples: Infrared Satellite Imaging

Examples: Automated Visual Inspection



a	b
c	d
e	f

FIGURE 1.14 Some examples of manufactured goods often checked using digital image processing. (a) A circuit board controller. (b) Packaged pills. (c) Bottles. (d) Air bubbles in a clear-plastic product. (e) Cereal. (f) Image of intraocular implant. (Fig. (f) courtesy of Mr. Pete Sites, Perceptics Corporation.)

Examples: Automated Visual Inspection

a b
c
d

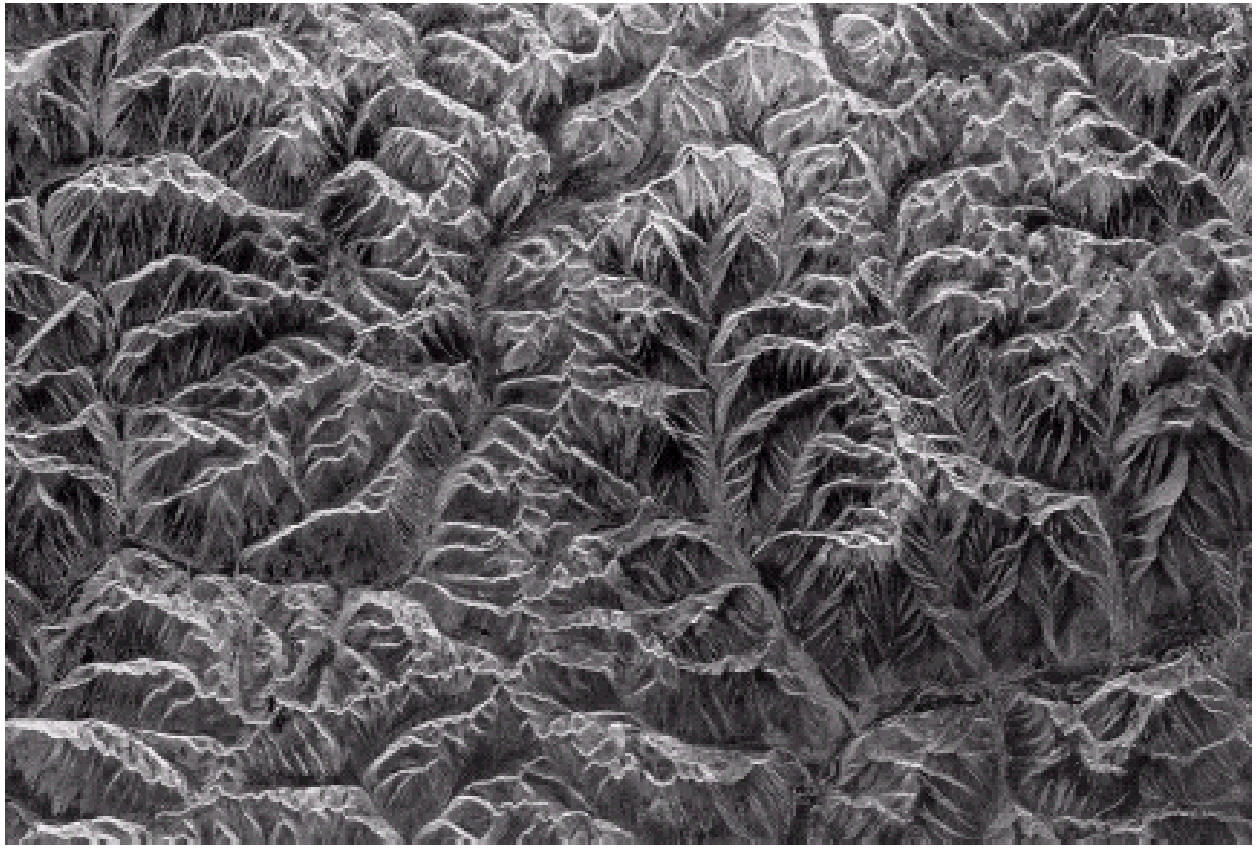
FIGURE 1.15 Some additional examples of imaging in the visual spectrum. (a) Thumb print. (b) Paper currency. (c) and (d) Automated license plate reading. (Figure (a) courtesy of the National Institute of Standards and Technology. Figures (c) and (d) courtesy of Dr. Juan Herrera, Perceptics Corporation.)

Results of automated reading of the plate content by the system

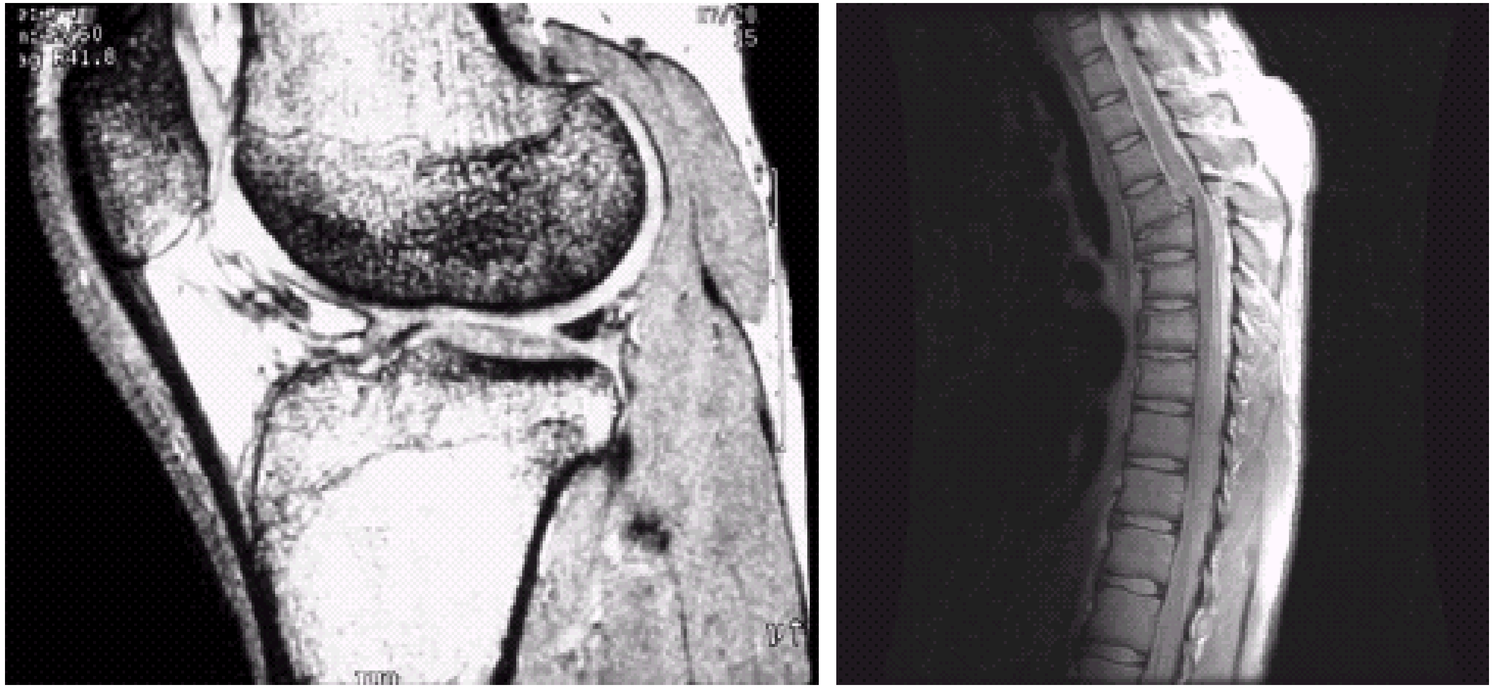
The area in which the imaging system detected the plate

Example of Radar Image

FIGURE 1.16
Spaceborne radar image of mountains in southeast Tibet. (Courtesy of NASA.)



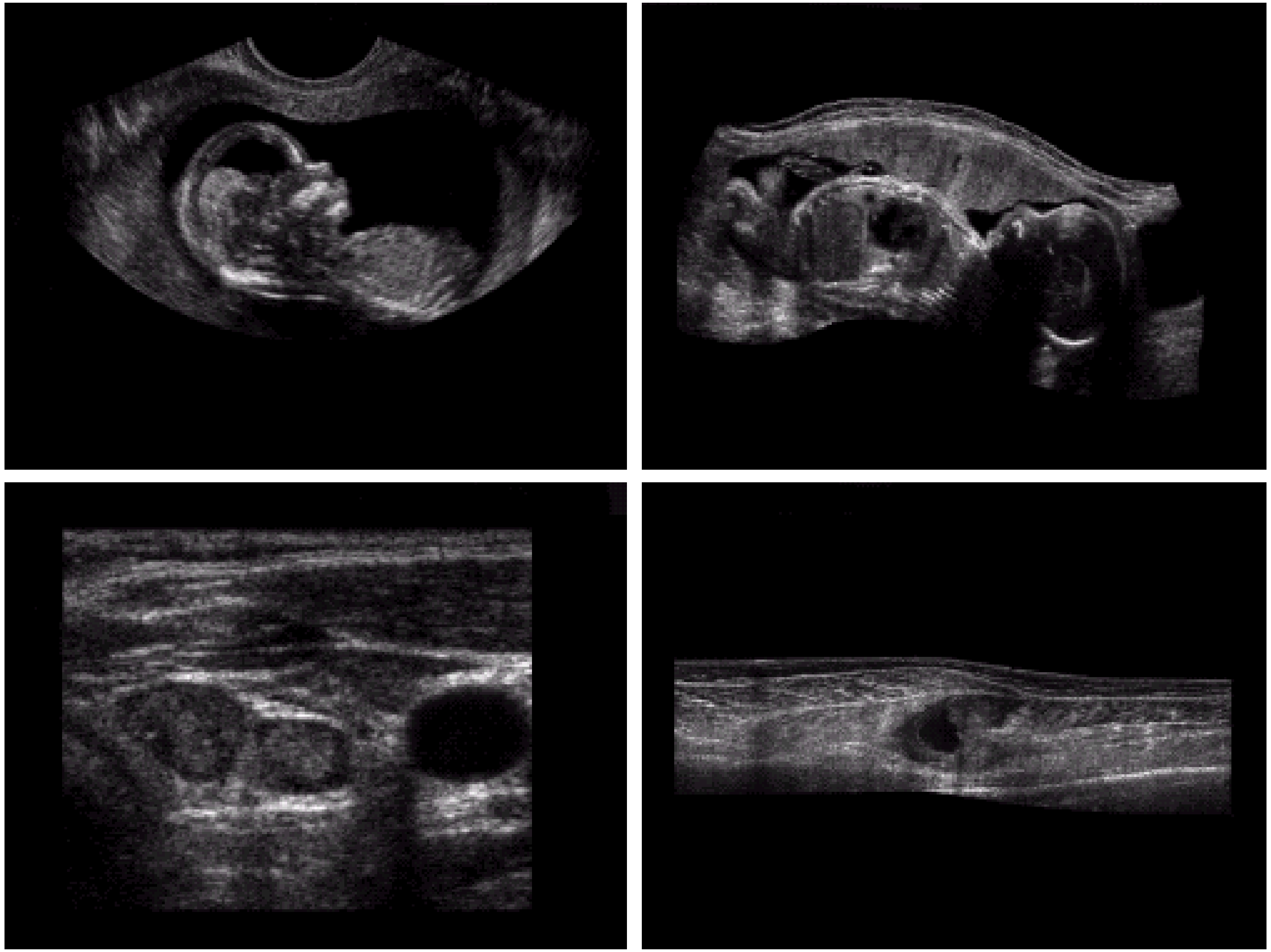
Examples: MRI (Radio Band)



a b

FIGURE 1.17 MRI images of a human (a) knee, and (b) spine. (Image (a) courtesy of Dr. Thomas R. Gest, Division of Anatomical Sciences, University of Michigan Medical School, and (b) Dr. David R. Pickens, Department of Radiology and Radiological Sciences, Vanderbilt University Medical Center.)

Examples: Ultrasound Imaging



a b
c d

FIGURE 1.20 Examples of ultrasound imaging. (a) Baby. (2) Another view of baby. (c) Thyroids. (d) Muscle layers showing lesion. (Courtesy of Siemens Medical Systems, Inc., Ultrasound Group.)

Spatial and Intensity Resolution

- Spatial resolution

  — A measure of the smallest discernible detail in an image

  — stated with *line pairs per unit distance, dots (pixels) per unit distance, dots per inch (dpi)*

- Intensity resolution

  — The smallest discernible change in intensity level

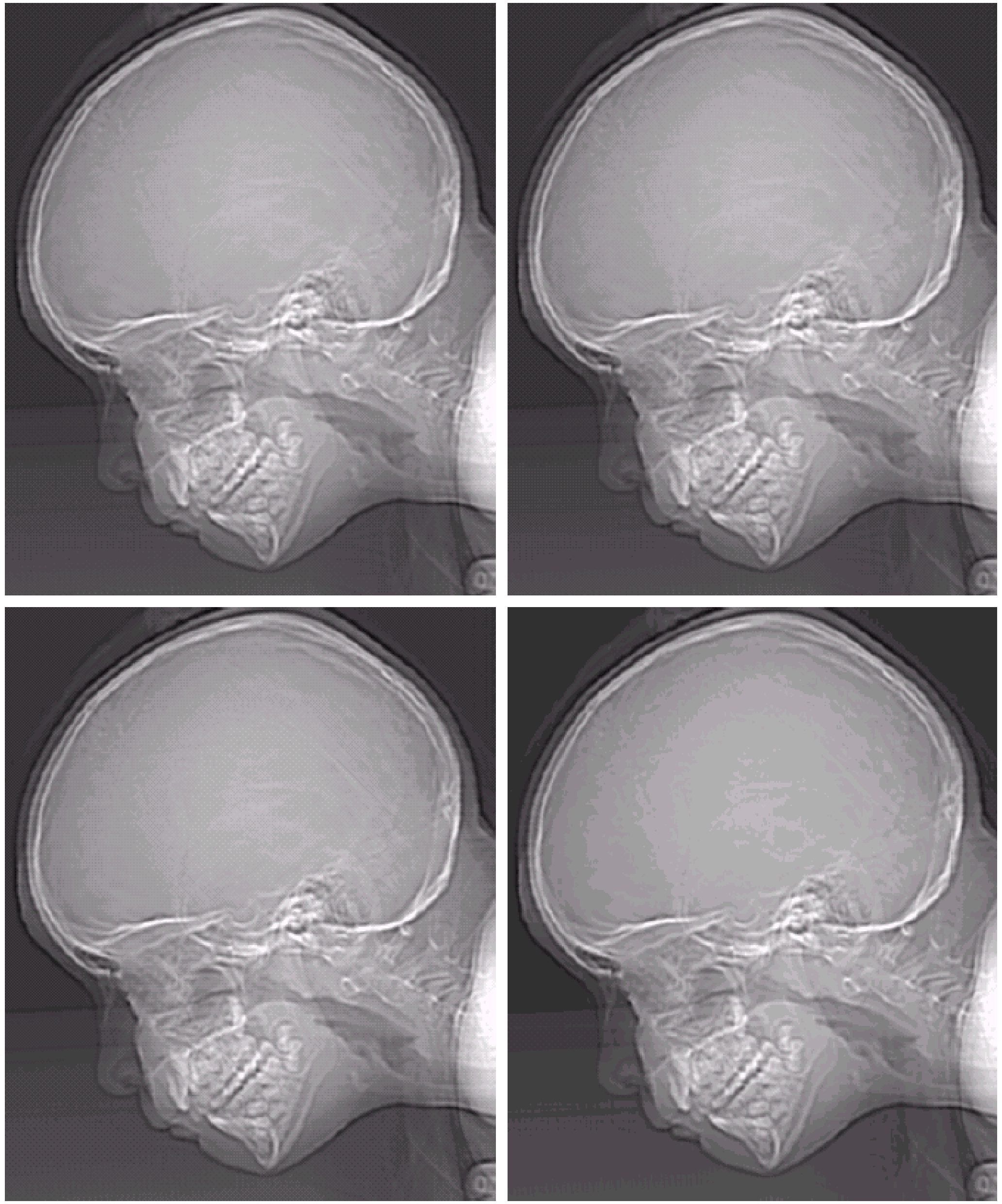
  — stated with *8 bits, 12 bits, 16 bits, etc.*

Effects of Reducing Spatial Resolution

a	b
c	d

FIGURE 2.20 Typical effects of reducing spatial resolution. Images shown at: (a) 1250 dpi, (b) 300 dpi, (c) 150 dpi, and (d) 72 dpi. The thin black borders were added for clarity. They are not part of the data.

Effects of Reducing Intensity Resolution

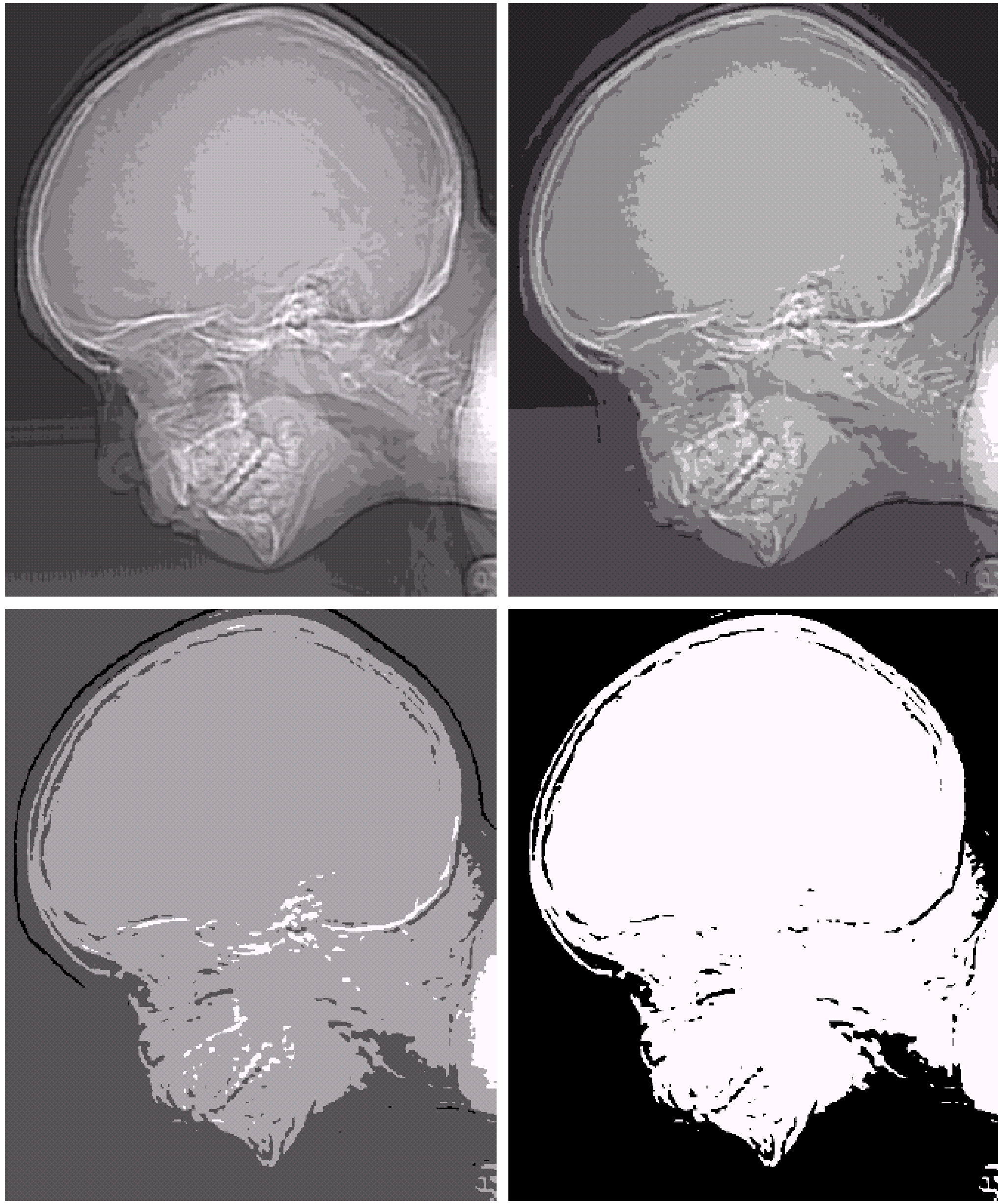


a b
c d

FIGURE 2.21 (a) 452 × 374, 256-level image. (b)–(d) Image displayed in 128, 64, and 32 gray levels, while keeping the spatial resolution constant.

e f
g h

FIGURE 2.21 *(Continued)* (e)–(h) Image displayed in 16, 8, 4, and 2 gray levels. (Original courtesy of Dr. David R. Pickens, Department of Radiology & Radiological Sciences, Vanderbilt University Medical Center.)



Basic Relationships Between Pixels

- Neighborhood
- Adjacency
- Connectivity
- Paths
- Regions and boundaries

Basic Relationships Between Pixels (Neighborhood)

- **Neighbors** of a pixel *p* at coordinates *(x,y)*

➢ **4-neighbors of *p***, denoted by $\boldsymbol{N_4(p)}$:
(x-1, y), (x+1, y), (x,y-1), and *(x, y+1).*

➢ **4 diagonal neighbors of p**, denoted by $\boldsymbol{N_D(p)}$:
(x-1, y-1), (x+1, y+1), (x+1,y-1), and *(x-1, y+1).*

➢ **8 neighbors of p**, denoted $\boldsymbol{N_8(p)}$

$N_8(p) = N_4(p) \cup N_D(p)$

Basic Relationships Between Pixels (Adjacency)

- **Adjacency**
  Let V be the set of intensity values

- **4-adjacency**: Two pixels p and q with values from V are 4-adjacent if q is in the set $N_4(p)$.

- **8-adjacency**: Two pixels p and q with values from V are 8-adjacent if q is in the set $N_8(p)$.
- **m-adjacency**: Two pixels p and q with values from V are m-adjacent if

  (i) q is in the set $N_4(p)$, or

  (ii) q is in the set $N_D(p)$ and the set $N_4(p) \cap N_4(p)$ has no pixels whose values are from V.

Basic Relationships Between Pixels (Path)

- **Path**

➢ A (digital) path (or curve) from pixel p with coordinates (x_0, y_0) to pixel q with coordinates (x_n, y_n) is a sequence of distinct pixels with coordinates

$$(x_0, y_0), (x_1, y_1), \ldots, (x_n, y_n)$$

Where (x_i, y_i) and (x_{i-1}, y_{i-1}) are adjacent for $1 \le i \le n$.

➢ Here *n* is the *length* of the path.

➢ If $(x_0, y_0) = (x_n, y_n)$, the path is ***closed*** path.

➢ We can define 4-, 8-, and m-paths based on the type of adjacency used.

Examples: Adjacency and Path

V = {1, 2}

0	1	1		0	1	1		0	1	1
0	2	0		0	2	0		0	2	0
0	0	1		0	0	1		0	0	1

Examples: Adjacency and Path

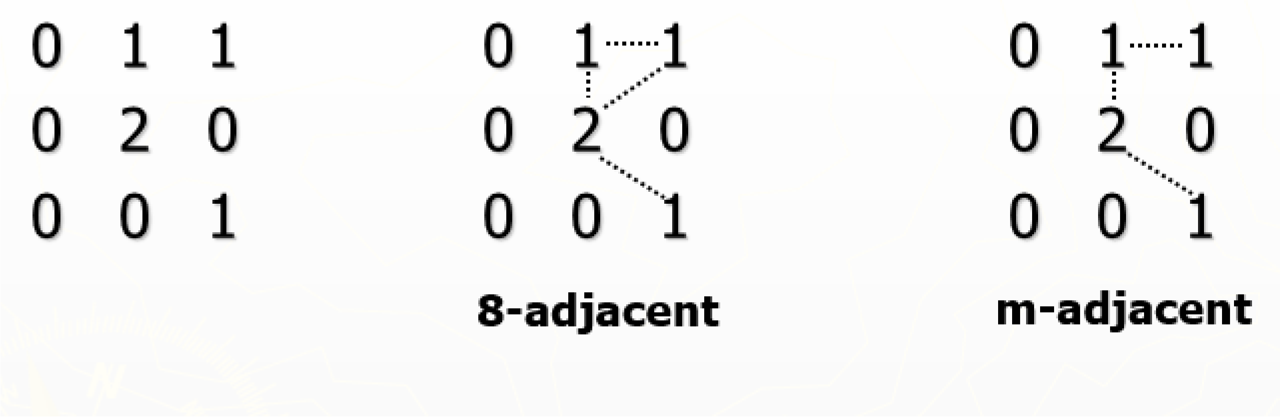
V = {1, 2}

$$\begin{matrix} 0 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{matrix} \qquad \begin{matrix} 0 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{matrix} \qquad \begin{matrix} 0 & 1 & 1 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{matrix}$$

8-adjacent

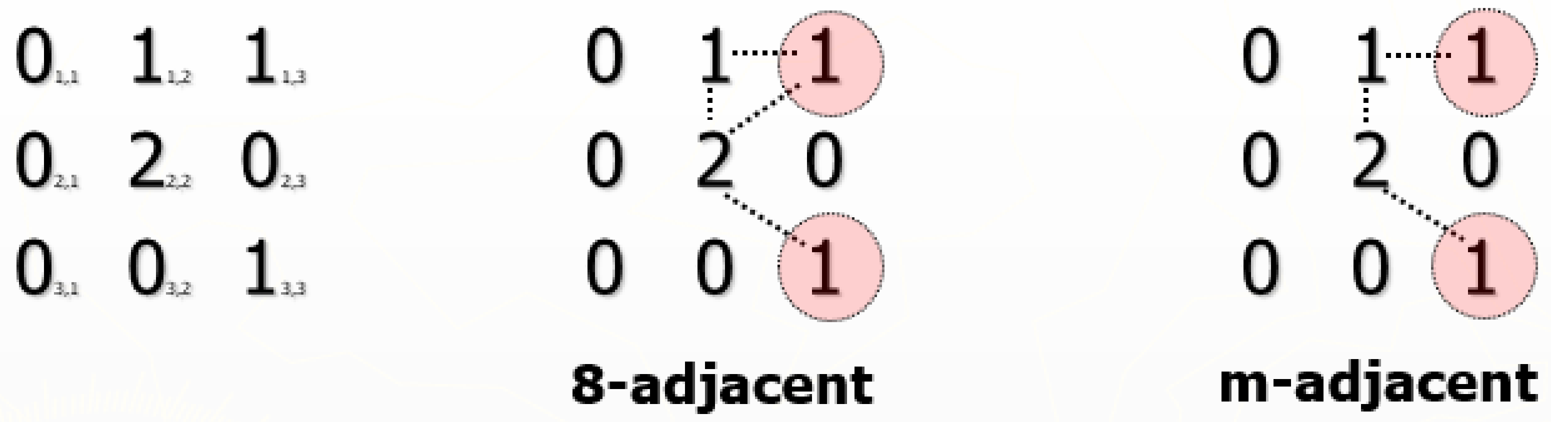
Examples: Adjacency and Path

V = {1, 2}



Examples: Adjacency and Path

V = {1, 2}



The 8-path from (1,3) to (3,3):
(i) (1,3), (1,2), (2,2), (3,3)
(ii) (1,3), (2,2), (3,3)

The m-path from (1,3) to (3,3):
(1,3), (1,2), (2,2), (3,3)

Basic Relationships Between Pixels (Connectivity)

- **Connected in S**

  Let S represent a subset of pixels in an image. Two pixels p with coordinates (x_0, y_0) and q with coordinates (x_n, y_n) are said to be **connected in S** if there exists a path

  $(x_0, y_0), (x_1, y_1), \ldots, (x_n, y_n)$

  Where $\forall i, 0 \le i \le n, (x_i, y_i) \in S$

Basic Relationships Between Pixels (Connectivity)

Let S represent a subset of pixels in an image

- For every pixel *p* in S, the set of pixels in S that are connected to *p* is called a ***connected component*** of S.

- If S has only one connected component, then S is called ***Connected Set*.**

- We call R a **region** of the image if R is a connected set

- Two regions, R_i and R_j are said to be ***adjacent*** if their union forms a connected set.
- Regions that are not to be adjacent are said to be ***disjoint.***

Basic Relationships Between Pixels (Boundary and Regions)

- **Boundary (or border)**

➢ The ***boundary*** of the region R is the set of pixels in the region that have one or more neighbors that are not in R.

➢ If R happens to be an entire image, then its boundary is defined as the set of pixels in the first and last rows and columns of the image.

- **Foreground and background**

➢ An image contains K disjoint regions, R_k, $k = 1, 2, \dots, K$. Let R_u denote the union of all the K regions, and let $(R_u)^c$ denote its complement.

All the points in R_u is called **foreground**;

All the points in $(R_u)^c$ is called **background**.

Thank you !