

Dual Propagation

Accelerating Contrastive Hebbian Learning with Dyadic Neurons

Rasmus Høier, D. Staudt, Christopher Zach

Chalmers University of Technology



Motivation

Contrastive hebbian learning (CHL) [1] and equilibrium propagation (EP) [2]

- Biological plausibility
- Neuromorphic computing

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A dyadic objective

$$\begin{split} \mathcal{L}_{\alpha}(\theta) &:= \min_{z^{+}} \max_{z^{-}} \alpha \ell(z_{L}^{+}) + (1 - \alpha) \ell(z_{L}^{-}) \\ &+ \sum_{k=1}^{L} \frac{1}{\beta_{k}} \Big(G_{k}(z_{k}^{+}) - G_{k}(z_{k}^{-}) + (z_{k}^{-} - z_{k}^{+})^{\top} W_{k-1}(\alpha z_{k-1}^{+} + (1 - \alpha) z_{k-1}^{-}) \Big) \end{split}$$

- Linear units: $G_k = ||\cdot||^2/2$
- ReLU units: $G_k = ||\cdot||^2/2 + i_{\geq 0}(\cdot)$
- $\alpha \in [0,1]$

Choice of α

- $\alpha = 1$ and $\alpha = 0$:
 - LPOM-like [3, 4] pure minimization objectives
 - · First order gradient estimate
 - · Slow iterative inference
- $\alpha = 1/2$:
 - · Fast layer-wise closed form inference
 - Second order gradient estimate

$$\begin{split} \mathcal{L}_{\frac{1}{2}}(\theta) &= \min_{z^{+}} \max_{z^{-}} \frac{1}{2} \ell(z_{L}^{+}) + \frac{1}{2} \ell(z_{L}^{-}) \\ &+ \sum_{k=1}^{L} \frac{1}{\beta_{k}} \Big(G_{k}(z_{k}^{+}) - G_{k}(z_{k}^{-}) + \frac{1}{2} (z_{k}^{-} - z_{k}^{+})^{\top} W_{k-1}(z_{k-1}^{+} + z_{k-1}^{-}) \Big) \end{split}$$

Connection to CHL and EP

Defining energy functions E_k as in CHL allows reformulating $\mathcal{L}_{\frac{1}{2}}.$

$$\cdot \ E_k(z_k, z_{k-1}) := G_k(z_k) - z_k^T W_{k-1} z_{k-1}$$

$$\cdot \ \overline{Z}_k := \frac{1}{2}(Z_k^+ + Z_k^-)$$

$$\mathcal{L}_{\frac{1}{2}}(\theta) = \min_{z^{+}} \max_{z^{-}} \ell(z_{L}^{+}) + \ell(z_{L}^{-}) + \sum_{k=1}^{L} \frac{1}{\beta_{k}} (E(z_{k}^{+}, \bar{z}_{k-1}) - E(z_{k}^{-}, \bar{z}_{k-1}))$$

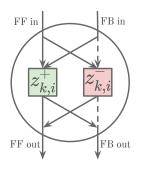
Similar to CHL and EP objectives but z_k^+ and z_k^- are inferred simultaneously and "tethered" via \bar{z}_{k-1} .

Inference

$$z_{k}^{\pm} \leftarrow f_{k} \left(\frac{1}{2} W_{k-1} (z_{k-1}^{+} + z_{k-1}^{-}) \pm \frac{\beta_{k}}{2\beta_{k+1}} W_{k}^{\top} (z_{k+1}^{+} - z_{k+1}^{-}) \right)$$

- · Neurons within layers are not coupled
- Fully optimize $\mathcal{L}_{\frac{1}{2}}$ with respect to a z_k^+ and z_k^- in a single block-coordinate descent step!

Dvadic neurons



$$z_{k}^{\pm} \leftarrow f_{k} \left(\underbrace{\frac{1}{2} W_{k-1} (z_{k-1}^{+} + z_{k-1}^{-})}_{\text{FF in}} \pm \underbrace{\frac{\beta_{k}}{2\beta_{k+1}} W_{k}^{\top} (z_{k+1}^{+} - z_{k+1}^{-})}_{\text{FB in}} \right)$$

$$\text{FF out} = \frac{1}{2} (z_{k,i}^{+} + z_{k,i}^{-})$$

$$\text{FB out} = \frac{1}{2} (z_{k,i}^{+} - z_{k,i}^{-})$$

Biologically plausible?

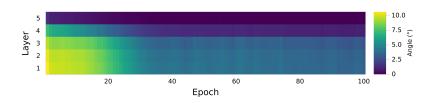
- Error signals depend on both FF and FB inputs.
- · Similar issue in [5] resolved via inter-neurons.

Learning

- Fully local contrastive Hebbian gradient
- · Second order gradient estimate
- Discounting not needed ($\beta_k = 1 \forall k \text{ employed in experiments}$)

$$\tfrac{\partial}{\partial W_{k-1}}\mathcal{L}_{\frac{1}{2}} = \tfrac{1}{2\beta_k} \left(Z_k^- - Z_k^+ \right) \left(Z_{k-1} + Z_{k-1} \right)^\top.$$

· Excellent gradient alignment between BP and DP



Experiments: MLP (MNIST)

- DP: cost-efficient (forwards + backwards)
- MS-DP: Multiple steps of inference and weight updates per datapoint
- L-DP: "Lazily" let old states persist providing potentially harmful feedback.
- P-DP: parallel neuron updates
- · R-DP-100: Random update sequence

Method	BP	DP	MS-DP	L-DP	P-DP	R-DP-100
Test	98.45	98.43	98.40	98.42	98.47	98.48
acc (%)	±0.04	±0.03	±0.02	± 0.07	±0.04	±0.11

Experiments: VGG16

Method		BP	DP	KP-DP [†]	EP* [6]	DTP* [7]
CIFAR10	Top-1	92.26 ± 0.23	92.30 ± 0.11	91.84 ± 0.11	88.6 ± 0.2	89.38 ± 0.20
CIFAR100	Top-1	69.63 ± 0.24	69.57 ± 0.51	70.40 ± 0.25	61.6 ± 0.1	_
	Top-5	88.13 ± 0.22	88.36 ± 0.13	88.57 ± 0.15	86.0 ± 0.1	_
ImageNet32x32	Top-1	41.28 ± 0.19	41.48 ± 0.19	_	36.5 ± 0.3	36.81
	Top-5	64.89 ± 0.11	64.90 ± 0.13	_	60.8 ± 0.4	60.54

- (†) Dual propagation with Kolen-Pollack learning of feedback weights.
- (*) High computational costs limit EP (Laborieux 2022) and DTP (Ernoult 2022) to 5-7 layer VGG-like networks.

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Conclusion

- Unlike previous CHL methods DP computes errors across compartments rather than across time.
- The dyadic neuron model enables closed-form inference rules and a second order gradient estimate.
- Many viable update schemes including random and parallel updates.
- The efficient DP implementation matches back-propagation both in terms of accuracy and runtime.

Future work: Continuous inference and learning in a streaming setting.

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