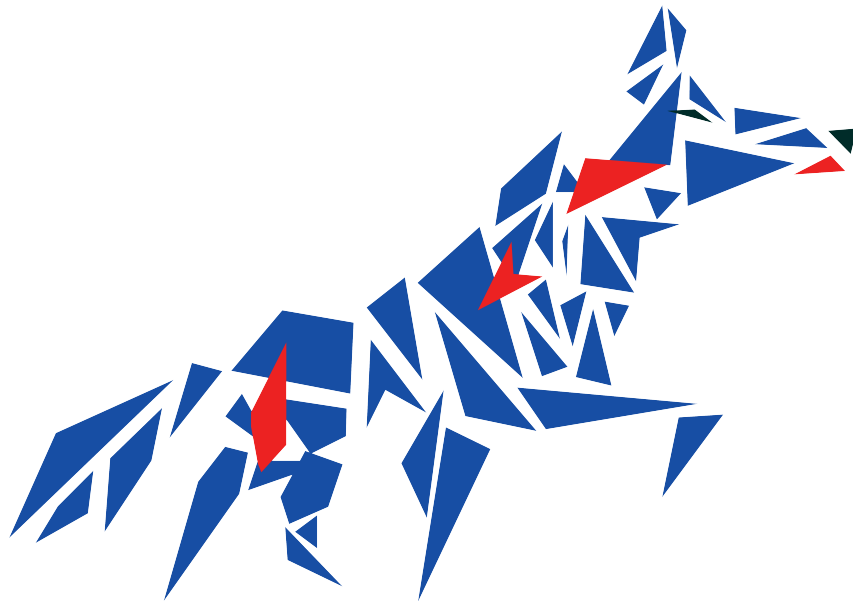


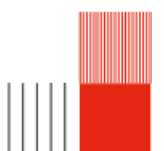
Analysis of MAC Protocols in Wireless Sensor Networks (WSN)

Clément Gauché



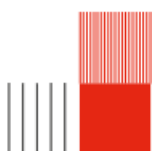
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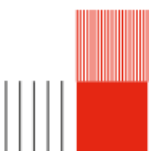
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Abstract

Medium Access Control (MAC) protocols are essential in Wireless Sensor Networks (WSNs) for managing how nodes access the communication channel. This paper provides an in-depth analysis of several MAC protocols designed for WSNs. The protocols are compared based on their channel access mechanisms, clock synchronization, localization capabilities, security features, and support for node mobility.



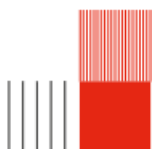
Introduction

Wireless sensor networks have emerged as one of the most transformational technologies for monitoring and managing various environments, from industrial processes to ecological systems. These are networks of spatially distributed sensor nodes that may collaborate on collecting, processing, and transmitting information to central points for analysis. The MAC protocol is an important ingredient for efficient and reliable operation of WSNs, allowing nodes to access and share the communication medium.

Designing MAC protocols in WSNs poses an exceptional challenge compared to traditional networks. Indeed, sensor nodes are usually small and resource-constrained nodes with very limited energy supply, processing power, and limited storage capacity. In general, WSNs are deployed in the field for monitoring applications. Hence, protocols should be versatile to adapt to changing environmental conditions, topology, traffic patterns, and application requirements. Most of the key design aspects include energy efficiency, latency control, scalability, and robustness under continuously changing conditions.

This document, in the context of the course on Wireless Sensors Networks at INSA Toulouse, covers the wide variety of MAC protocols developed for WSNs. It analyzes in detail their characteristics, including channel access mechanisms, clock synchronization techniques, localization capabilities, security features, and mobility support. This work is intended to help choose or develop appropriate MAC protocols by studying the strengths and limitations of various protocols.

The paper is organized as follows: after the basic concepts of multiple access protocols are introduced, a deep analysis of prominent MAC protocols for WSNs is provided, including Sensor-MAC (S-MAC), Timeout-MAC (T-MAC), Berkeley-MAC (B-MAC), Zebra-MAC (Z-MAC), and Geographic Adaptive Fidelity (GAF). Finally, a comparison of these protocols outlines their trade-offs and their suitability for specific applications, and concludes by giving indications on the choice of MAC protocol when developing its own network of nodes.



1. Multiple Access Protocols

When we think of MAC protocols, we first think of the link layer of Ethernet or Wi-Fi LANs (IEEE 802.11). However, they are not the only ones: there are specific MAC protocols for wireless networks (WSNs). These protocols manage shared access to the communication channel when several devices attempt to transmit simultaneously. You will see below that several types of MAC have been developed for WSNs and that they can be classified into different channel access categories. [1]

1.1. Definition of Multiple Access Protocols

Multiple access protocols are communication systems that share a common transmission medium between several users. These protocols address the problem of "conflict resolution among users desiring channel access" [2] by governing the way devices access the communication channel, thus guaranteeing efficient, conflict-free data transmission. In wireless sensor networks (WSNs), where energy efficiency and data reliability are key, multiple access protocols play an essential role in minimising collisions, maximising throughput and conserving energy.

In several research papers, the main characteristics of multiple access protocols are as follows:

1. Channel Allocation: The manner in which the shared communication medium is divided among users. It may be done in time, for example, time slots in TDMA, by frequency bands as in FDMA, or even by codes as in CDMA..

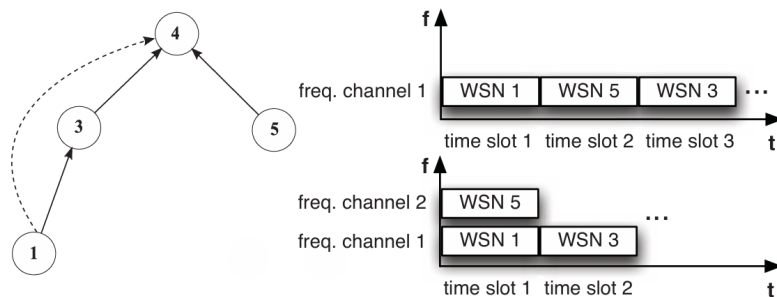
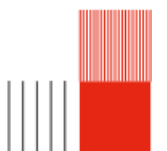


Figure 1.1: Top channel allocation based on time slot and bottom allocation is based on both time slots and frequency channels [3]



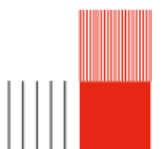
2. Collision Avoidance: Mechanisms to minimize or prevent simultaneous transmissions that can lead to data loss. Protocols like CSMA/CA employ carrier sensing and backoff strategies to address this.
3. Energy Efficiency: Energy is the scarcest resource in WSNs, thus, protocols are designed to minimize active communication time and idle listening to save energy.
4. Scalability: The ability of the protocol to accommodate a growing number of devices without significant degradation in performance or efficiency.
5. Fairness: Ensuring all users have equitable access to the communication medium, avoiding the exclusion of certain devices.
6. Synchronization: Some protocols require clock synchronization to coordinate transmissions, especially in TDMA systems.
7. Adaptability: The ability to adapt to changing network conditions, like varying traffic loads or node mobility.

Multiple access protocols can be categorized into contention-based protocols (e.g., CSMA) and scheduled protocols (e.g., TDMA), depending on whether they dynamically or preemptively allocate channel resources.

1.2. Overview of general Multiple Access Protocol

General multiple access protocols form the basis for more specialized MAC protocols in WSNs. These include:

- Code Division Multiple Access (CDMA): CDMA assigns unique codes to each node, enabling simultaneous transmission over the same frequency band. It is energy-intensive but resilient to interference.[4]
- Frequency Division Multiple Access (FDMA): FDMA allocates distinct frequency bands to each node, ensuring collision-free communication but at the cost of bandwidth underutilization in low-traffic scenarios.[5]
- Time Division Multiple Access (TDMA): TDMA divides time into slots, assigning each slot to a specific node. This approach eliminates collisions and improves energy efficiency but requires precise synchronization.[6]
- Multiple Access with Collision Avoidance (MACA): MACA enhances contention-based access by introducing control packets like RTS (Request to Send) and CTS (Clear to Send) to reduce collisions.[7]
- Carrier Sense Multiple Access with Collision Avoidance (CSMA/CA): Widely used in WSNs, CSMA/CA senses the channel before transmission and employs backoff mechanisms to minimize collisions during contention. It is best known for its use in WiFi.[8]



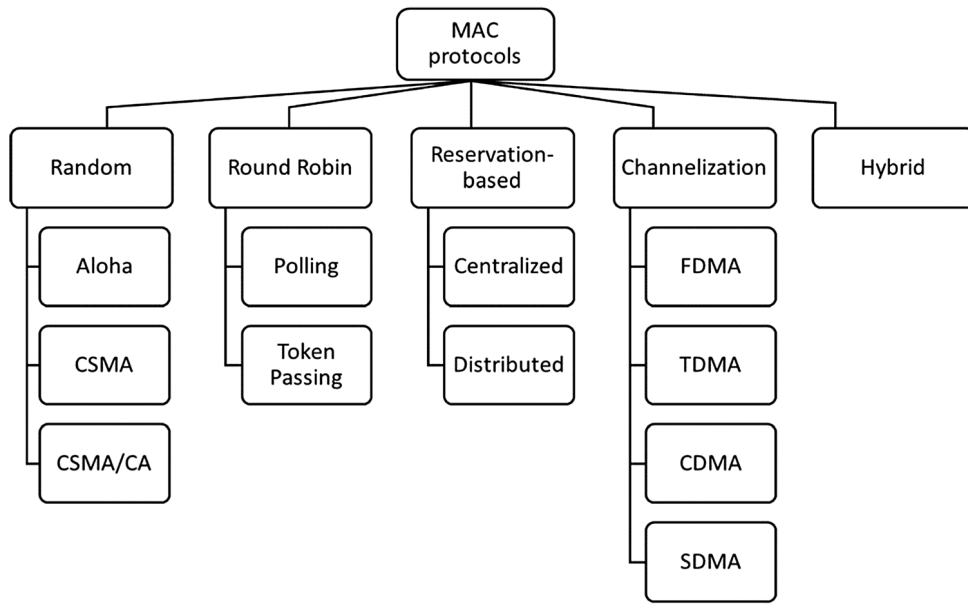
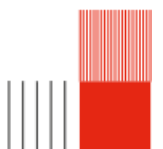


Figure 1.2: General classification of MAC protocols
(based on their type of channel access) [9]

These protocols establish the core mechanisms for accessing shared communication channels and are adapted in WSNs to address challenges like energy constraints, scalability, and environmental variability.



2. MAC Protocols in WSN

MAC protocols in wireless sensor networks (WSNs) are essential for managing media access, ensuring energy efficiency and maintaining communication reliability. This section analyses the main aspects of various protocols, including their channel access mechanisms, the presence and accuracy of clock synchronization and whether or not they incorporate localization capabilities. This evaluation also takes into account the presence of security mechanisms and the ability to support node mobility, which is crucial for dynamic network scenarios. Finally, the protocols are ranked and compared in an attempt to highlight their strengths, weaknesses and suitability for specific WSN applications, allowing an understanding of their performance under different conditions.

2.1. Sensor-MAC (S-MAC)

The S-MAC protocol was announced in 2002 by Wei Ye, John Heidemann and Deborah Estrin at the University of Southern California. It was designed with the aim of reducing energy consumption in sensor networks by introducing the principle of static coordinated sleep.

Channel Access Type

S-MAC employs a [contention-based](#) channel access using Carrier Sense Multiple Access with Collision Avoidance (CSMA/CA). Nodes sense the channel and transmit if it is idle.

Clock Synchronization

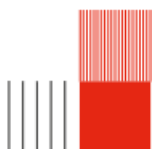
S-MAC includes basic clock synchronization where nodes periodically exchange synchronization packets. The precision is coarse, aimed at ensuring that nodes wake up and sleep at approximately the same time.

Localization Capability

S-MAC does not inherently support localization. Any localization functionality must be added via higher network layers.

Security Mechanisms

S-MAC lacks built-in security features. External security layers, such as encryption or authentication, need to be incorporated.



Mobility Support

S-MAC is designed for static networks, and it does not handle node mobility efficiently. Movement may disrupt the synchronization process and the rigid sleep schedules.

Energy Consumption

The only way to reduce the power consumption of the S-MAC protocol is to increase the latency by using the increasing the sleep delay.

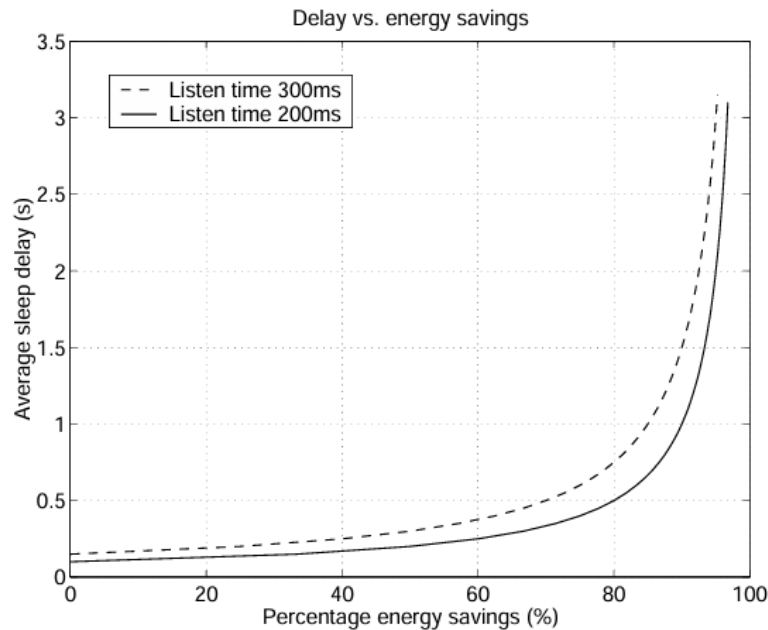


Figure 2.1: Energy savings vs. average sleep delay for the listen time of 30ms [10]

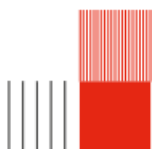
However, the S-MAC has four major sources of energy waste. These are the collision, the overhearing, the control packet overhead and the idle listening. Therefore, S-MAC tries to reduce the wastage by putting the sensor nodes into a periodic sleep mode with a low and fixed duty cycle. [11]

2.2. Timeout-MAC (T-MAC)

Introduced in 2004 by Tijs van Dam and Koen Langendoen of the Technical University of Delft, it is a further development of the S-MAC, designed to optimize energy consumption in varying traffic situations.

Channel Access Type

Similar to S-MAC, T-MAC uses contention-based access via CSMA/CA. It improves upon S-MAC by dynamically adjusting the active/sleep periods depending on network traffic, offering adaptive duty cycles.



Clock Synchronization

T-MAC includes synchronization mechanisms akin to S-MAC, but is still relatively coarse, focused on aligning active periods. Unlike S-MAC, which has a fixed active period, T-MAC dynamically adjusts the duty cycle using a timeout mechanism. Nodes remain active until a specified timeout (TA) passes without detecting activity, after which they transition to sleep mode to save energy.

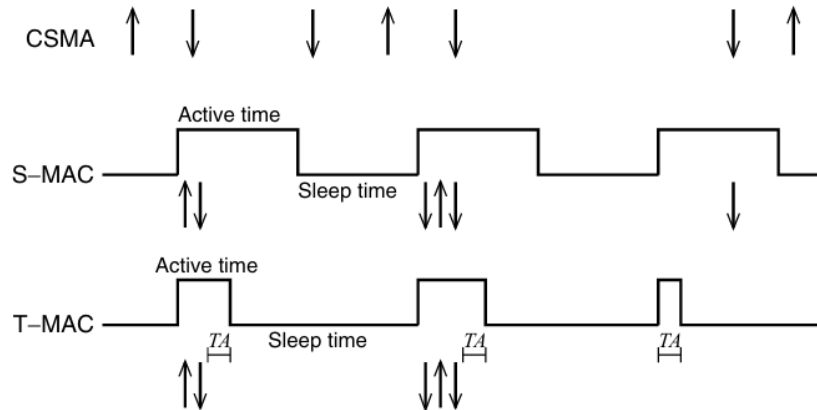


Figure 2.2: The S-MAC and T-MAC duty cycles; the arrows indicate transmitted and received messages(TA denotes the activity time-out period.) [12]

Localization Capability

Like S-MAC, T-MAC does not include localization features.

Security Mechanisms

No built-in security is provided in T-MAC, requiring external solutions for secure communication.

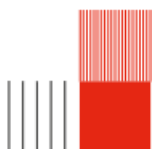
Mobility Support

T-MAC does not handle mobility well and is also intended for static networks.

Energy Consumption

T-MAC significantly reduces energy consumption by minimizing idle listening, a primary cause of energy waste in WSNs. In a typical WSN with low traffic, nodes spend a majority of their time in a low-power sleep mode. For example:

- For low traffic, T-MAC has a duty cycle of roughly 2.5%, using very little power [12].
- At zero traffic, T-MAC uses about 0.16 mA-considerably better than other protocols such as CSMA with Low-Power Listening (LPL), which uses 0.42 mA under the same circumstances [12].



However, as traffic load increases, T-MAC adapts by extending the active period, which raises energy consumption. This trade-off ensures that T-MAC maintains performance without sacrificing reliability, though its aggressive power-down policy may occasionally cause latency or dropped packets under high contention.

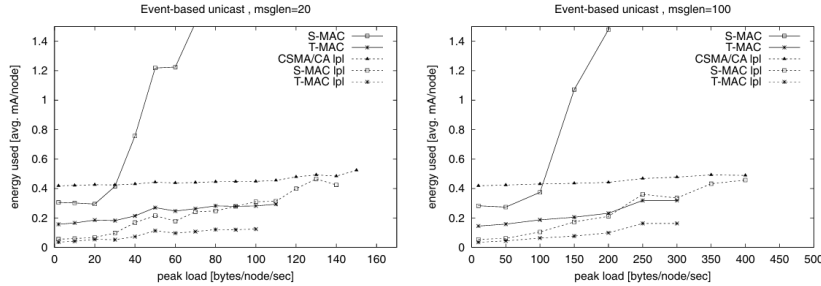


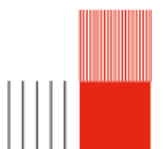
Figure 2.3: Event-based unicast performance for small messages (left) and large messages (right) [12]

2.3. Berkeley MAC (B-MAC)

Berkeley MAC (B-MAC) was developed in 2004 by Joseph Polastre, Robert Szewczyk, and David Culler at the University of California, Berkeley. It is a versatile, robust, and energy-efficient MAC protocol that quickly became a cornerstone in Wireless Sensor Networks (WSNs) research due to its flexibility and adaptability across various applications.

Channel Access Type

B-MAC operates using a contention-based protocol with Low-Power Listening (LPL), where nodes periodically sample the channel to detect activity. This approach significantly reduces idle listening and conserves energy. However, network performance can be further enhanced by dynamically adjusting the LPL duty cycle based on traffic patterns. For instance, during periods of high data generation, the receiving node can increase its active listening periods to reduce latency, thereby maintaining a balance between energy efficiency and responsiveness.



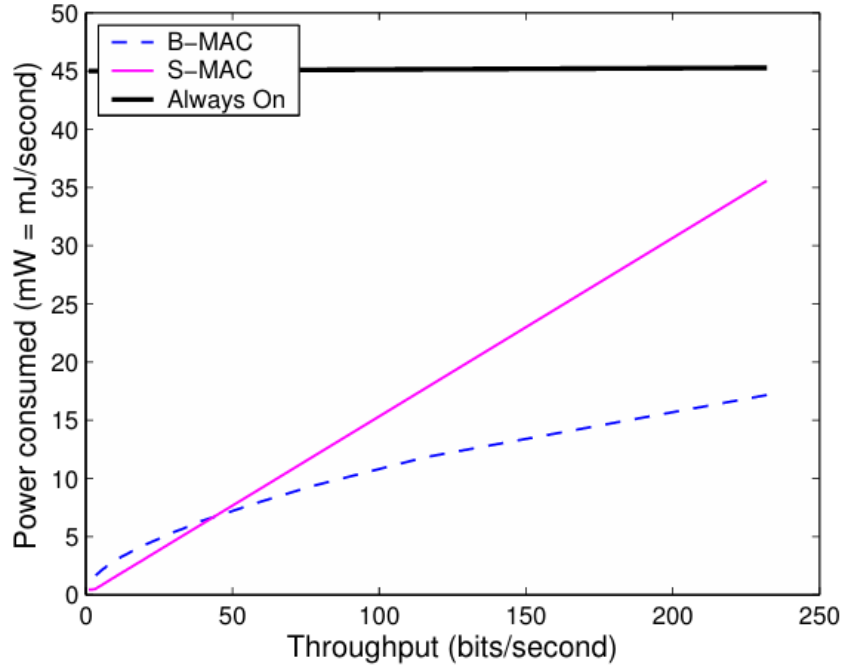


Figure 2.4: Average energy consumption of a node for an average bit rate (based on a network of 10 nodes) and a comparison of S-MAC and B-MAC [13]

Additionally, the use of RTS/CTS (Request to Send/Clear to Send) mechanisms can enhance collision avoidance in B-MAC. While not originally included in its design, RTS/CTS could mitigate issues like the hidden node problem, particularly in dense or high-traffic networks. However, the added control packet overhead must be weighed against the benefits, as it could increase latency and energy consumption.

Clock Synchronization

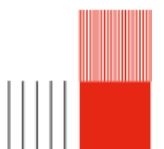
B-MAC operates asynchronously, with no need for clock synchronization. Each node independently wakes up to sample the channel, hence it is lightweight and flexible, especially in networks where global synchronization is either unnecessary or impractical.

Localization Capability

B-MAC does not inherently support localization features. If required, localization mechanisms, such as GPS or other higher-layer techniques, must be integrated into the network stack.

Security Mechanisms

B-MAC does not include built-in security measures. Features such as encryption, authentication, or intrusion detection must be implemented in higher layers to ensure secure communication. This modular approach allows B-MAC to remain lightweight but places the burden of security on other parts of the system.



Mobility Support

Although B-MAC is primarily designed for static networks, its asynchronous nature enables it to tolerate slow-moving nodes. This makes it marginally suitable for networks with limited mobility, such as environmental monitoring or low-speed mobile platforms. For high-mobility scenarios, however, additional mechanisms, such as dynamic handoff or mobility-aware scheduling, would need to be implemented.

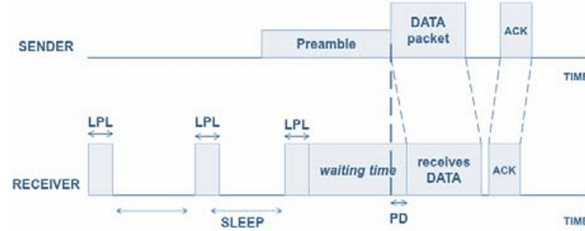


Figure 2.5: The timeline and events during a successful B-MAC transmission [14]

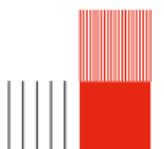
Energy Consumption

2.4. ESR-MAC (Energy-Efficient and Scalable Real-Time MAC)

The ESR-MAC protocol was proposed in 2008 by Yu-Chia Chang and Jang-Ping Sheu from National Tsing Hua University, Taiwan. It was developed to reduce the collision problem of the current S-MAC and T-MAC protocols, and to improve the throughput while ensuring energy efficiency and scalability. This protocol presents a slot reservation scheme that will lessen the effect from both contention and collision. ESR-MAC can decrease the transmission delay and improve throughput without reducing the energy efficiency. [11]

Channel Access Type

ESR-MAC employs a hybrid approach combining TDMA for scheduled communication and CSMA for contention-based access. This hybrid mechanism ensures scalability and supports real-time communication by dynamically adjusting the schedule based on network load.



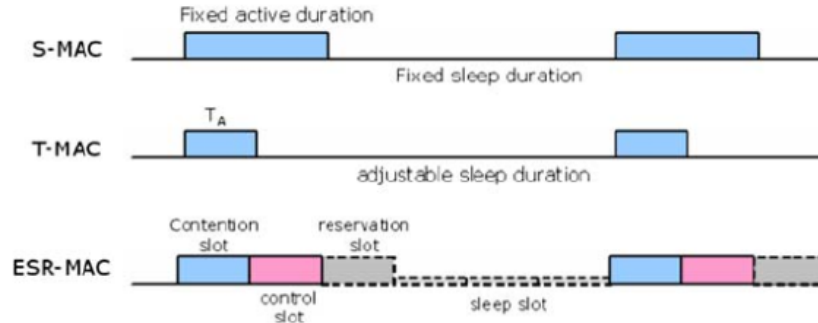


Figure 2.6: Framework of S-MAC, T-MAC and ESR-MAC protocols [11]

Clock Synchronization

ESR-MAC relies on global clock synchronization to align TDMA time slots, achieved through periodic synchronization messages. The precision is high, suitable for time-sensitive applications.

Localization Capability

ESR-MAC does not include localization capabilities, but its synchronization framework can support localisation-based enhancements if integrated with an external localization system.

Security Mechanisms

ESR-MAC has some inbuilt security mechanisms, like encrypted synchronization packets and secure channel reservations, to avoid unauthorized access and eavesdropping during TDMA scheduling.

Mobility Support

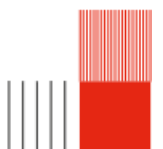
ESR-MAC partially supports node mobility by dynamically reallocating time slots and reconfiguring the TDMA schedule when nodes join or leave the network. However, rapid or frequent mobility may require significant overhead for resynchronization.

2.5. Zebra MAC (Z-MAC)

Z-MAC was proposed in 2005 by Injong Rhee and colleagues at North Carolina State University. It combines CSMA and TDMA to adapt to varying traffic conditions, balancing energy efficiency and throughput.

Channel Access Type

Z-MAC is a [hybrid protocol](#) that combines Time Division Multiple Access (TDMA) with CSMA. Under low traffic conditions, called LCL for [low contention level](#), CSMA is used, while under high traffic conditions, called HCL for [high contention level](#), TDMA is used to avoid collisions. "It combines their strenth while offsettings their weaknesses"[15]



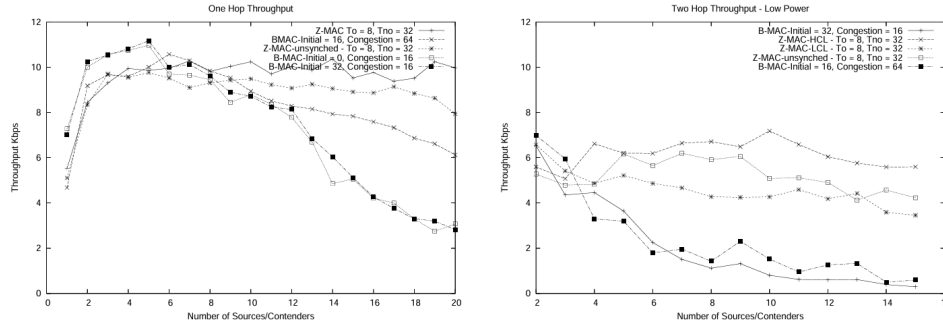


Figure 2.7: Comparison of the use of Z-MAC and B-MAC channels in 2 different environments [15]

As we see in the figure above, Z-MAC's energy and latency are comparable to B-MAC's, and Z-MAC achieves more than three times the throughput when HLC occurs.

Clock Synchronization

Z-MAC requires [global synchronization](#) due to its use of TDMA. Synchronization is maintained through periodic message exchanges to ensure that nodes are aligned with their time slots.

Localization Capability

Z-MAC does not include localization capabilities, but its global synchronization may allow integration of such features.

Security Mechanisms

No inherent security mechanisms are included in Z-MAC. Security must be handled by higher layers.

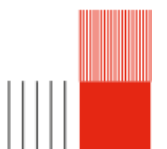
Mobility Support

Z-MAC provides limited mobility support, requiring reconfiguration and resynchronization as nodes move between time slots.

Energy Consumption

Z-MAC dynamically adapts its mode of operation to achieve a balance between energy efficiency and throughput:

- Under Low Contention: Nodes in CSMA mode experience lower energy consumption due to minimal coordination overhead. Idle listening is reduced, as nodes compete only when necessary [16].
- Under High Contention: TDMA scheduling introduces additional synchronization and slot management overhead, leading to higher energy consumption. However, this mode minimizes collisions and retransmissions, offsetting energy costs in dense networks. [16].



In multi-hop networks, energy consumption increases due to the relay of synchronization and ECN messages. Analytical studies indicate that Z-MAC performs better than pure CSMA or TDMA protocols under moderate traffic loads. For instance, in one-hop communication scenarios, Z-MAC achieves lower energy consumption compared to TDMA-based protocols, particularly when contention is low.

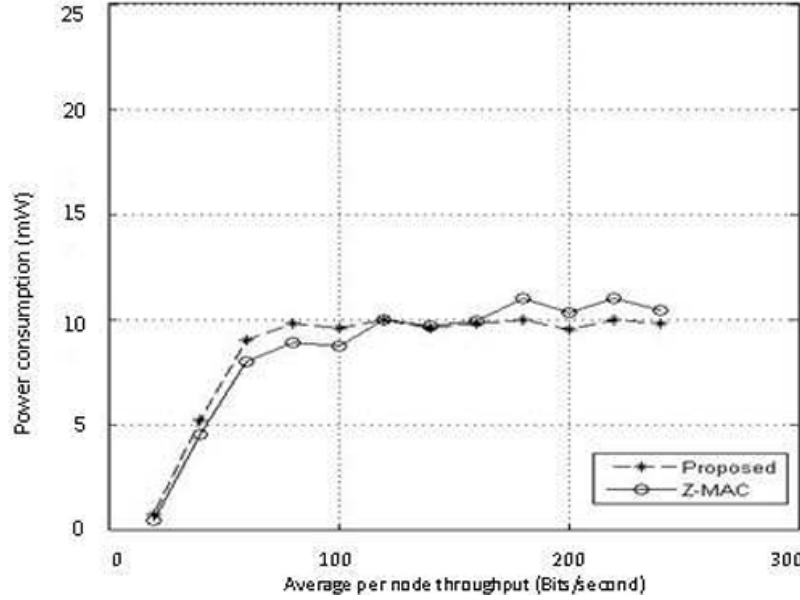


Figure 2.8: Z-MAC energy consumption [16]

2.6. Geographic Adaptive Fidelity (GAF)

GAF was introduced in 2001 by Ya Xu, John Heidemann, and Deborah Estrin at the University of Southern California. It has been designed to conserve energy by using node location information to form virtual grids.

Channel Access Type

GAF uses a [localization-based](#) channel access mechanism. The network is divided into a virtual grid, with one active node per grid cell to handle communication and conserve energy.

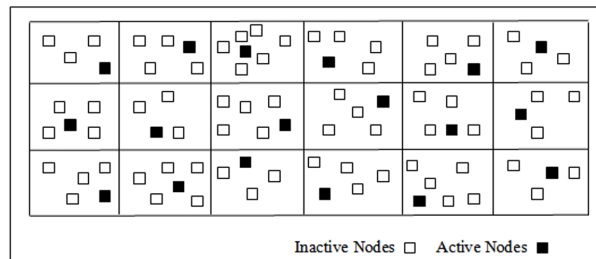
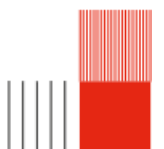


Figure 2.9: GAF grid network [17]



Clock Synchronization

GAF requires clock synchronization within each grid cell but does not require highly precise global synchronization. The active nodes in neighboring cells need to wake up at the same time to relay messages.

Localization Capability

GAF includes basic localization capabilities as it operates using a virtual geographic grid. Nodes need to know their approximate localization to determine their grid cell. To do that they can use information system like GPS, or GLONASS.

Security Mechanisms

GAF lacks inherent security features, necessitating the implementation of external security solutions.

Mobility Support

GAF supports node mobility effectively. As nodes move across grid cells, the protocol automatically assigns new active nodes to maintain coverage.

Energy Consumption

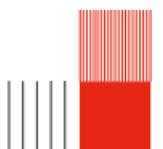
GAF significantly reduces power consumption by putting redundant nodes into sleep mode. Simulation studies show that:

- **Energy Savings:** GAF can save up to 40–60% of energy compared to non-location-aware protocols by turning off unnecessary nodes [18].
- **Grid Size Optimization:** The protocol's energy efficiency improves as grid size increases, reducing the frequency of state transitions and the number of active nodes. However, excessively large grids can compromise network connectivity.

GAF's energy efficiency is further enhanced by optimizing the discovery phase, where nodes compete to become active. Advanced versions, like Optimized GAF, reduce the number of discovery messages, further lowering energy consumption and extending network lifetime.

2.7. How to Choose a MAC Protocol for WSNs ?

For a Wireless Sensor Network (WSN), the choice of Medium Access Control (MAC) protocol is an important decision as it can affect the performance, power consumption and lifetime of the network. Because of the diversity of WSN needs and constraints, a single protocol will never be able to meet all application requirements. Selecting a MAC protocol is a process that includes defining the requirements and understanding the relevant parameters such as energy, latency and reliability that need to be optimised.



No Perfect Solution

No MAC protocol is universally ideal. For instance, energy-efficient protocols like S-MAC save battery life through sleep-wake cycles but introduce latency. Conversely, low-latency protocols like Z-MAC perform better under high traffic but consume more energy. The right protocol depends on the application's priorities, such as energy efficiency, low latency, or high reliability.

According to specific needs

Application requirements should guide protocol selection:

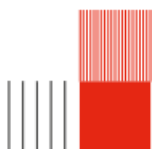
- **Energy Efficiency:** Essential for long-term deployments; B-MAC and S-MAC are excellent choices.
- **Low Latency:** Critical for time-sensitive applications; T-MAC and Z-MAC perform well.
- **Scalability:** Hybrid protocols like Z-MAC or TDMA-based systems handle dense networks better.
- **Mobility:** Protocols like GAF are ideal for dynamic or mobile networks.
- **Traffic Load:** Contention-based protocols like B-MAC are suited for low traffic, while hybrid or contention-free protocols excel in high traffic.

Optimize Energy, Performance, and Scalability

Optimizing energy consumption, latency, reliability and scalability is key. While protocols like T-MAC are good in energy conservation, they sacrifice latency, while Z-MAC strikes a balance by adapting its mechanism based on the traffic condition. Simulation using tools like NS-3 or Contiki OS can help test a protocol's performance before deployment.

Protocol	Channel Access	Clock Sync	Localization	Security	Mobility
S-MAC	CSMA/CA (contention)	Yes	No	No	Poor
T-MAC	CSMA/CA (contention)	Yes	No	No	Poor
B-MAC	CSMA with LPL	No	No	No	Tolerates slow
ESR-MAC	TDMA + CSMA (hybrid)	Yes (high)	No	Basic	Moderate support
Z-MAC	TDMA + CSMA (hybrid)	Yes	No	No	Limited
GAF	localization-based	Yes	Yes	No	Good

Table 2.1: Comparison of WSN MAC Protocols

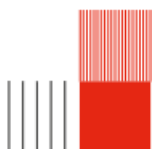


Conclusion

In the dynamic and resource-constrained world of WSNs, choosing an appropriate MAC protocol is a key concern for achieving optimal performance, energy efficiency, and adaptability. Further, each protocol analyzed herein presents unique strengths and associated trade-offs, making them suited for different applications and network conditions.

S-MAC and T-MAC stand out for their energy efficiency, though T-MAC has better adaptability to traffic variation. However, their dependence on fixed or coarse synchronization and limited mobility support ensure they best suit static deployments with moderate traffic. B-MAC, with asynchronous low-power listening, stands out for its energy savings and simplicity. Still, it specifically lacks features related to clock synchronization or any kind of mobility handling that restricts utility in dynamic networks. Z-MAC balances energy consumption and throughput well by hybrid adaptation between contention-based and schedule-based operations, making it very suitable for networks that have varying conditions of traffic. However, its reliance on global synchronization and limited mobility support presents challenges in highly dynamic environments. GAF offers a unique localization-based approach, optimizing energy consumption and supporting mobility through dynamic node management within virtual grids. That makes it very suitable for mobile or location-aware applications, but it does not include integrated security mechanisms.

Ultimately, there is no universally ideal protocol. The best choice really depends on the application's requirements for energy efficiency, latency, scalability, mobility, and security. Any future developments in the MAC protocols must integrate strengths from all different existing approaches by addressing the various limitations they have related to improving security, ensuring high mobility, and reducing energy consumption further with minimum sacrifice towards network performance. With appropriate trade-off analysis, WSN can fully understand and fit the needs according to applications running under severe to diverse scenarios.



Glossary

contention-based A type of communication protocol where multiple nodes compete for access to the same communication channel.. [5](#), [6](#), [10](#)

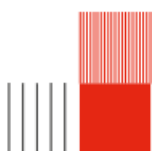
global synchronization Process of aligning the clocks of all nodes in a network to a common reference time. This is often required in protocols such as TDMA to ensure time slots are correctly aligned across the network. [12](#)

high contention level A network condition where many nodes simultaneously attempt to access the communication channel, increasing the likelihood of collisions and delays. [11](#)

hybrid protocol A protocol that combines two or more channel access techniques to leverage the benefits of each. [11](#)

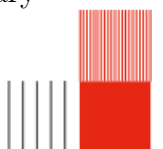
localization-based Refers to protocols or systems that utilize the geographical position of nodes to optimize network operations, such as routing or scheduling. [13](#)

low contention level A network condition where only a few nodes attempt to access the communication channel at any given time, resulting in minimal collisions and efficient data transmission. [11](#)



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