ROMAN NAUMENKO

Research Engineer

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gmail ♦ linkedin ♦ github

ABOUT MYSELF

I'm a computer vision engineer with extensive experience in GPU-accelerated computer graphics. I have strong expertise in systems engineering, integration, and machine learning. My current work focuses on optimizing AI algorithms for real-time applications on embedded hardware.

EDUCATION

Undergraduate of Software Engineering, National Technical University of Ukraine, Kyiv

2020-2022

Bachelor of Computer Science, Ukrainian Catholic University, Lviv

Expected 2025

SKILLS

Technical Skills C/C++, Python, PyTorch, NumPy, Pandas,

Linux, DirectX11/Vulkan/OpenGL, GLSL/HLSL

Soft skills Attention to detail, teamwork, leadership, problem-solving

Languages Ukrainian (native), English (upper-intermediate)

Other Computer vision, machine learning, multithreading, operating systems, modern

rendering techinques, compute shaders, BVHs, OOP, OOD

EXPERIENCE

Research Engineer

May 2024 - Now

FoxFour & UCU Machine Learning Laboratory

Lviv, Ukraine

- Achieved a 10x performance speedup in convolutional neural network inference on embedded platform.
- Developed an efficient and accurate deep learning-based keypoint extraction frontend for a visual-inertial odometry application.

Render Programmer

Fractured Byte

April 2022 - January 2023

(remote) Kyiv, Ukraine

- Gained experience in software-hardware integration and optimization for specific hardware (Nintendo Switch).
- Developed tools for technical artists, fixed render bugs and improved performance of the rendering system.

Trainee Software Developer

AMC Bridge

Nov 2021 - Dec 2021

(remote) Dnipro, Ukraine

• Worked in research department and build a program for handling 3D-objects transformations.

PROJECTS

SLAM for Drone Swarms: Contributed to a platform research project by adapting a CNN-based ALike solution for keypoint detection and feature extraction. Achieved real-time 20Hz inference on UAV-specialized onboard computers powered by Rockchip modules and successfully integrated it as a visual frontend in the SLAM pipeline.

Small Mamba Language Model. Custom implementation of Mamba state space model pretrained for NLP tasks. Took part in research of a completely different approach for building fundamental models, proposed by Albert Gu and Tri Dao from Stanford University. Implemented a simplified version of their SOTA model and trained for generating human like text.

Audio inpainting. Implemented inpainting funct variations of SAM and two generative models: a diff	ionality for the hackathon task. Tusion based and LaMa.	Researched and	tested different