

Ratnangshu Das

Ph.D., Prime Minister's Research Fellow (PMRF)
ROBERT BOSCH CENTRE FOR CYBER-PHYSICAL SYSTEMS
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EDUCATION

Year	Degree	Institution (Board)	GPA/Percentage
2023-Present	Ph.D., ROBERT BOSCH CENTRE FOR CYBER-PHYSICAL SYSTEMS	Indian Institute of Science, Bangalore, India	GPA: 9.3/10.0
2017-2022	BT-MT Dual Degree, Mechanical Engineering	Indian Institute of Technology, Kanpur, India	GPA: 10.0/10.0(PG) 9.5/10.0(UG)
2017	Indian School Certificate Examination (Intermediate)	St. Stephen's School, Kolkata, India	Percentage: 96.2%
2015	Indian Certificate of Secondary Education (Matriculation)	St. Stephen's School, Kolkata, India	Percentage: 96.6%

RESEARCH EXPERIENCE

Formal Control of Autonomous Systems

Supervisor: Dr. Pushpak Jagtap, *RBCCPS, IISc Bengaluru,*

Bangalore, India

Jan 2023 - Present

Telemedicine and Medical Robotics

CoE: Telemedicine and Healthcare Robotics, GSMST, IIT Kanpur

Kanpur, India

June 2022 - Dec 2022

Experimental Study and Modelling of Trust in Child Robot Interaction

Supervisor: Dr. Bishakh Bhattacharya, *Dept. of Mechanical Engineering, IIT Kanpur,*

Kanpur, India

May 2021 - Dec 2022

Co-supervisor: Dr. Mayank Shekhar Jha, *CRAN, Polytech Nancy, Universite de Lorraine, France,*

Ungrounded force feedback in portable haptic devices

Supervisor: Dr. Yasemin Vardar, *Cognitive Robotics Department, HITLab, Delft University of Technology,*

Delft, Netherlands

May 2021 - Nov 2021

Haptipedia, a database of numerous haptic devices

Supervisor: Dr. Katherine J. Kuchenbecker, *Haptic Intelligence Department, MPI-IS,*

Stuttgart, Germany

June 2020 - Sept 2020

Humanoid Robotics, IIT Kanpur

Supervisor: Dr. Indranil Saha, *Dept. of Computer Science and Engineering, IIT Kanpur*

Kanpur, India

Dec. 2017 - April 2020

LIST OF RECENT PUBLICATIONS AND PATENTS

- Das, R., Sawarkar, S., & Jagtap, P. (2025). Scalable and Approximation-free Symbolic Control for Unknown Euler-Lagrange Systems. *arXiv preprint arXiv:2509.19859*. (submitted to Automatica)
- Das, R., Basu, A., & Jagtap, P. (2025). Spatiotemporal tubes for temporal reach-avoid-stay tasks in unknown systems. *IEEE Transactions on Automatic Control*.
- Das, R., Basu, A., & Jagtap, P. (2025). Spatiotemporal Tubes Based Control of Unknown Multi-Agent Systems for Temporal Reach-Avoid-Stay Tasks. *IEEE Transactions on Control of Network Systems*.
- Das, R., Choudhury, S., & Jagtap, P. (2025). Approximation-free Control for Signal Temporal Logic Specifications using Spatiotemporal Tubes. *IEEE Control Systems Letters*.
- Das, R., Upadhyay, S., & Jagtap, P. (2025). Incorporating Social Awareness into Control of Unknown Multi-Agent Systems: A Real-Time Spatiotemporal Tubes Approach. *arXiv preprint arXiv:2510.25597*. (submitted to Automatica)
- Si, Y. A., Das, R., Monir, N., Soudjani, S., Jagtap, P., & Saoud, A. (2025). Maximally Resilient Controllers under Temporal Logic Specifications. *arXiv preprint arXiv:2509.01777*. (Accepted in CDC, 2025)
- Monir, N., Si, Y. A., Das, R., Jagtap, P., Saoud, A., & Soudjani, S. (2025). Computation of Feasible Assume-Guarantee Contracts: A Resilience-based Approach. *arXiv preprint arXiv:2509.01832*. (Accepted in CDC, 2025)
- Das, R., Bakshi, P., & Jagtap, P. (2025). Control Barrier Functions for Prescribed-time Reach-Avoid-Stay Tasks using Spatiotemporal Tubes. *arXiv preprint arXiv:2503.08106*. (Accepted in ECC, 2025)
- Faruqui, M., Das, R., & Jagtap, P. (2025). Reach-Avoid-Stay-Collision-Avoidance Negotiation Framework for Multi-Agent Systems via Spatiotemporal Tubes. *arXiv preprint arXiv:2503.10245*. (Accepted in ECC, 2025)
- Das, R., & Jagtap, P. (2024). Prescribed-time reach-avoid-stay specifications for unknown systems: A spatiotemporal tubes approach. *IEEE Control Systems Letters*.
- Das, R., & Jagtap, P. (2024, December). Funnel-based control for reach-avoid-stay specifications. In *2024 Tenth Indian Control Conference (ICC)* (pp. 54-59). IEEE.
- Das, R., & Jagtap, P. (2024, May). Spatiotemporal Tubes for Reach-Avoid-Stay Specifications. In *Proceedings of the 27th ACM International Conference on Hybrid Systems: Computation and Control* (pp. 1-2).
- Juvvi, M. S., Sundarsingh, D. S., Das, R., & Jagtap, P. (2024, May). Safe Multi-Robot Exploration using Symbolic Control. In *2024 IEEE International Conference on Robotics and Automation (ICRA)* (pp. 11619-11625). IEEE.
- Yadav, P., Jain, N., Das, R., & Saha, I. (2024). Computer-Implemented stigma separation system and method for separating stigmas from flowers. Indian Patent No. 564565, Patent Application No. 202311082765, filed Jan 2024.
- Das, R., Baishya, N. J., & Bhattacharya, B. (2023). A review on tele-manipulators for remote diagnostic procedures and surgery. *CSI Transactions on ICT*, 11(1), 31-37.

TECHNICAL SKILLS

Maple • MATLAB • Python • Arduino • AutoCAD • Autodesk Inventor • Git • \LaTeX • Linux • ROS • Simulink

TEACHING ASSISTANTSHIP

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|---|------------------------------|
| • Instructor , Formal Analysis and Control of Autonomous Systems, ISSS. | <i>May 2024 - Jun 2025</i> |
| • Teaching Assistant , CP275, Formal Analysis and Control, IISc Bengaluru. | <i>Jan 2025 - April 2025</i> |
| • Instructor , Robot Learning and Control, ISSS. | <i>Dec 2024 - Jan 2025</i> |
| • Teaching Assistant , E1 316o, Deep Learning for Robotics, IISc Bengaluru (Online). | <i>May 2024 - July 2024</i> |
| • Instructor , Linear Control Systems, ISSS. | <i>Mar 2024 - April 2024</i> |
| • Instructor , Applied Nonlinear Control Systems, ISSS. | <i>June 2024 - Aug 2024</i> |
| • Teaching Assistant , CP241, Applied Linear and Nonlinear Control, IISc Bengaluru. | <i>Aug 2023 - Dec 2023</i> |
| • Instructor , Analysis of Nonlinear Systems, ISSS. | <i>May 2023 - June 2023</i> |
| • Teaching Assistant , ME354A, Vibration & Control, IIT Kanpur. | <i>Jan 2022 - May 2022</i> |
| • Teaching Assistant , ME352A, Theory Of Mechanisms & Machines, IIT Kanpur. | <i>Aug 2021 - Dec 2021</i> |

HONORS AND AWARDS

- 2024, **Best Student Paper Award**, In the Tenth IEEE Indian Control Conference (ICC).
- 2023, **PMRF**: Selected as Prime Minister's Research Fellow.
- 2022, **SIIC Student Innovation Award**: For the best innovative project in path-breaking technology of global importance.
- 2022, 2021, 2020, Academic Excellence Award
- 2018, Second prize in **TCTD challenge**, Inter IIT, IIT Bombay.
- 2017, All India Rank 1201, Joint Entrance Exam Advanced, 200,000 candidates, India.
- 2017, All India Rank 1207, Joint Entrance Exam Main, 1.5 million candidates, India.
- 2016, KVPY Scholarship Awardee, Indian Institute of Science.
- 2015, NTSE Scholarship Awardee, National Council of Educational Research and Training.

REFERENCES

Pushpak Jagtap

Assistant Professor, Robert Bosch Centre for Cyber-Physical Systems, IISc Bangalore, India
Email: pushpak@iisc.ac.in
Relationship: PhD Supervisor

Sadegh Soudjani

Senior Research Group Leader, Max Planck Institute for Software Systems (MPI-SWS), Germany
Professor, Chair in Cyber-Physical Systems, Director of Global Engagement, University of Birmingham, United Kingdom
Email: sadegh@mpi-sws.org
Relationship: Research Collaborator

Adnane Saoud

Assistant Professor, University Mohammed IV Polytechnic (UM6P), Benguerir, Morocco
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Relationship: Research Collaborator

Christos Verginis

Assistant Professor, Division of Signals and Systems, Department of Electrical Engineering, Uppsala University, Sweden
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Relationship: Research Collaborator

Indranil Saha

Professor, Department of Computer Science and Engineering, Professor and Head, Department of Intelligent Systems, Indian Institute of Technology Kanpur, India
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Relationship: Research Collaborator

Bishakh Bhattacharya

Professor, Department of Mechanical Engineering, Indian Institute of Technology Kanpur, India
Email: bishakh@iitk.ac.in
Relationship: M.Tech Supervisor