

Ratnangshu Das

Ph.D., Prime Minister's Research Fellow (PMRF)
ROBERT BOSCH CENTRE FOR CYBER-PHYSICAL SYSTEMS
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EDUCATION

Year	Degree	Institution (Board)	GPA/Percentage
2023-Present	Ph.D., ROBERT BOSCH CENTRE FOR CYBER-PHYSICAL SYSTEMS	Indian Institute of Science, Bangalore, India	GPA: 9.3/10.0
2017-2022	BT-MT Dual Degree, Mechanical Engineering	Indian Institute of Technology, Kanpur, India	GPA: 10.0/10.0(PG) 9.5/10.0(UG)
2017	Indian School Certificate Examination (Intermediate)	St. Stephen's School, Kolkata, India	Percentage: 96.2%
2015	Indian Certificate of Secondary Education (Matriculation)	St. Stephen's School, Kolkata, India	Percentage: 96.6%

RESEARCH EXPERIENCE

Formal Control of Autonomous Systems Supervisor: Dr. Pushpak Jagtap, RBCCPS, IISc Bengaluru,	Bangalore, India Jan 2023 - Present
Telemedicine and Medical Robotics CoE: Telemedicine and Healthcare Robotics, GSMST, IIT Kanpur	Kanpur, India June 2022 - Dec 2022
Experimental Study and Modelling of Trust in Child Robot Interaction Supervisor: Dr. Bishakh Bhattacharya, Dept. of Mechanical Engineering, IIT Kanpur, Co-supervisor: Dr. Mayank Shekhar Jha, CRAN, Polytech Nancy, Universite de Lorraine, France,	Kanpur, India May 2021 - Dec 2022
Ungrounded force feedback in portable haptic devices Supervisor: Dr. Yasemin Vardar, Cognitive Robotics Department, HITLab, Delft University of Technology,	Delft, Netherlands May 2021 - Nov 2021
Haptipedia, a database of numerous haptic devices Supervisor: Dr. Katherine J. Kuchenbecker, Haptic Intelligence Department, MPI-IS,	Stuttgart, Germany June 2020 - Sept 2020
Humanoid Robotics, IIT Kanpur Supervisor: Dr. Indranil Saha, Dept. of Computer Science and Engineering, IIT Kanpur	Kanpur, India Dec. 2017 - April 2020

LIST OF RECENT PUBLICATIONS AND PATENTS

- Das, R., Sawarkar, S., & Jagtap, P. (2025). Scalable and Approximation-free Symbolic Control for Unknown Euler-Lagrange Systems. arXiv preprint arXiv:2509.19859. (submitted to Automatica)
- Das, R., Basu, A., & Jagtap, P. (2025). Spatiotemporal tubes for temporal reach-avoid-stay tasks in unknown systems. IEEE Transactions on Automatic Control.
- Das, R., Basu, A., & Jagtap, P. (2025). Spatiotemporal Tubes Based Control of Unknown Multi-Agent Systems for Temporal Reach-Avoid-Stay Tasks. IEEE Transactions on Control of Network Systems.
- Das, R., Choudhury, S., & Jagtap, P. (2025). Approximation-free Control for Signal Temporal Logic Specifications using Spatiotemporal Tubes. IEEE Control Systems Letters.
- Das, R., Upadhyay, S., & Jagtap, P. (2025). Incorporating Social Awareness into Control of Unknown Multi-Agent Systems: A Real-Time Spatiotemporal Tubes Approach. arXiv preprint arXiv:2510.25597. (submitted to Automatica)
- Si, Y. A., Das, R., Monir, N., Soudjani, S., Jagtap, P., & Saoud, A. (2025). Maximally Resilient Controllers under Temporal Logic Specifications. arXiv preprint arXiv:2509.01777. (Accepted in CDC, 2025)
- Monir, N., Si, Y. A., Das, R., Jagtap, P., Saoud, A., & Soudjani, S. (2025). Computation of Feasible Assume-Guarantee Contracts: A Resilience-based Approach. arXiv preprint arXiv:2509.01832. (Accepted in CDC, 2025)
- Das, R., Bakshi, P., & Jagtap, P. (2025). Control Barrier Functions for Prescribed-time Reach-Avoid-Stay Tasks using Spatiotemporal Tubes. arXiv preprint arXiv:2503.08106. (Accepted in ECC, 2025)
- Faruqui, M., Das, R., & Jagtap, P. (2025). Reach-Avoid-Stay-Collision-Avoidance Negotiation Framework for Multi-Agent Systems via Spatiotemporal Tubes. arXiv preprint arXiv:2503.10245. (Accepted in ECC, 2025)
- Das, R., & Jagtap, P. (2024). Prescribed-time reach-avoid-stay specifications for unknown systems: A spatiotemporal tubes approach. IEEE Control Systems Letters.
- Das, R., & Jagtap, P. (2024, December). Funnel-based control for reach-avoid-stay specifications. In 2024 Tenth Indian Control Conference (ICC) (pp. 54-59). IEEE.
- Das, R., & Jagtap, P. (2024, May). Spatiotemporal Tubes for Reach-Avoid-Stay Specifications. In Proceedings of the 27th ACM International Conference on Hybrid Systems: Computation and Control (pp. 1-2).
- Juvvi, M. S., Sundarsingh, D. S., Das, R., & Jagtap, P. (2024, May). Safe Multi-Robot Exploration using Symbolic Control. In 2024 IEEE International Conference on Robotics and Automation (ICRA) (pp. 11619-11625). IEEE.
- Yadav, P., Jain, N., Das, R., & Saha, I. (2024). Computer-Implemented stigma separation system and method for separating stigmas from flowers. Indian Patent No. 564565, Patent Application No. 202311082765, filed Jan 2024.
- Das, R., Baishya, N. J., & Bhattacharya, B. (2023). A review on tele-manipulators for remote diagnostic procedures and surgery. CSI Transactions on ICT, 11(1), 31-37.

TECHNICAL SKILLS

Maple • MATLAB • Python • Arduino • AutoCAD • Autodesk Inventor • Git • L^AT_EX • Linux • ROS • Simulink

TEACHING ASSISTANTSHIP

• Instructor , Formal Analysis and Control of Autonomous Systems, ISSS.	<i>May 2024 - Jun 2025</i>
• Teaching Assistant , CP275, Formal Analysis and Control, IISc Bengaluru.	<i>Jan 2025 - April 2025</i>
• Instructor , Robot Learning and Control, ISSS.	<i>Dec 2024 - Jan 2025</i>
• Teaching Assistant , E1 316o, Deep Learning for Robotics, IISc Bengaluru (Online).	<i>May 2024 - July 2024</i>
• Instructor , Linear Control Systems, ISSS.	<i>Mar 2024 - April 2024</i>
• Instructor , Applied Nonlinear Control Systems, ISSS.	<i>June 2024 - Aug 2024</i>
• Teaching Assistant , CP241, Applied Linear and Nonlinear Control, IISc Bengaluru.	<i>Aug 2023 - Dec 2023</i>
• Instructor , Analysis of Nonlinear Systems, ISSS.	<i>May 2023 - June 2023</i>
• Teaching Assistant , ME354A, Vibration & Control, IIT Kanpur.	<i>Jan 2022 - May 2022</i>
• Teaching Assistant , ME352A, Theory Of Mechanisms & Machines, IIT Kanpur.	<i>Aug 2021 - Dec 2021</i>

HONORS AND AWARDS

- 2024, **Best Student Paper Award**, In the Tenth IEEE Indian Control Conference (ICC).
- 2023, **PMRF**: Selected as Prime Minister's Research Fellow.
- 2022, **SIIC Student Innovation Award**: For the best innovative project in path-breaking technology of global importance.
- 2022, 2021, 2020, Academic Excellence Award
- 2018, Second prize in **TCTD challenge**, Inter IIT, IIT Bombay.
- 2017, All India Rank 1201, Joint Entrance Exam Advanced, 200,000 candidates, India.
- 2017, All India Rank 1207, Joint Entrance Exam Main, 1.5 million candidates, India.
- 2016, KVPY Scholarship Awardee, Indian Institute of Science.
- 2015, NTSE Scholarship Awardee, National Council of Educational Research and Training.

REFERENCES

Pushpak Jagtap

Assistant Professor, Robert Bosch Centre for Cyber-Physical Systems, IISc Bangalore, India
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Relationship: PhD Supervisor

Sadegh Soudjani

Senior Research Group Leader, Max Planck Institute for Software Systems (MPI-SWS), Germany
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