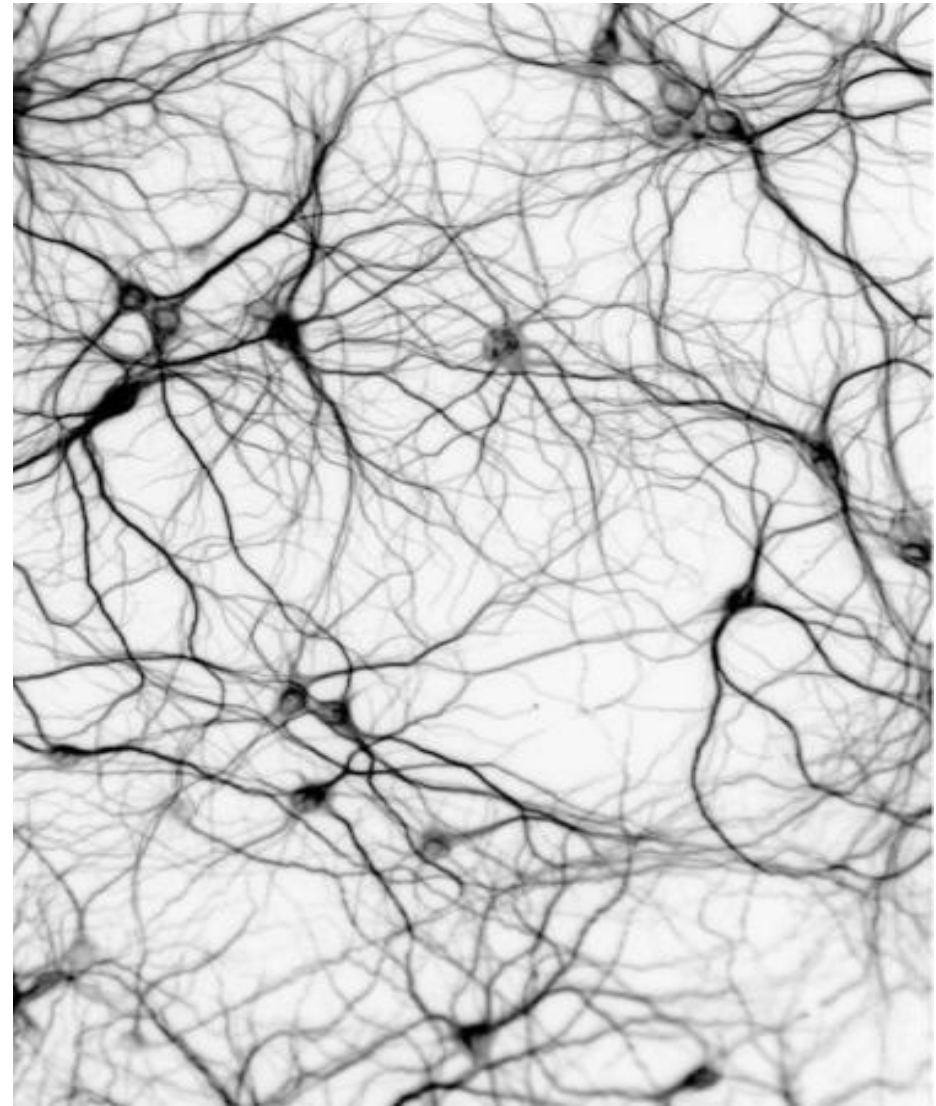


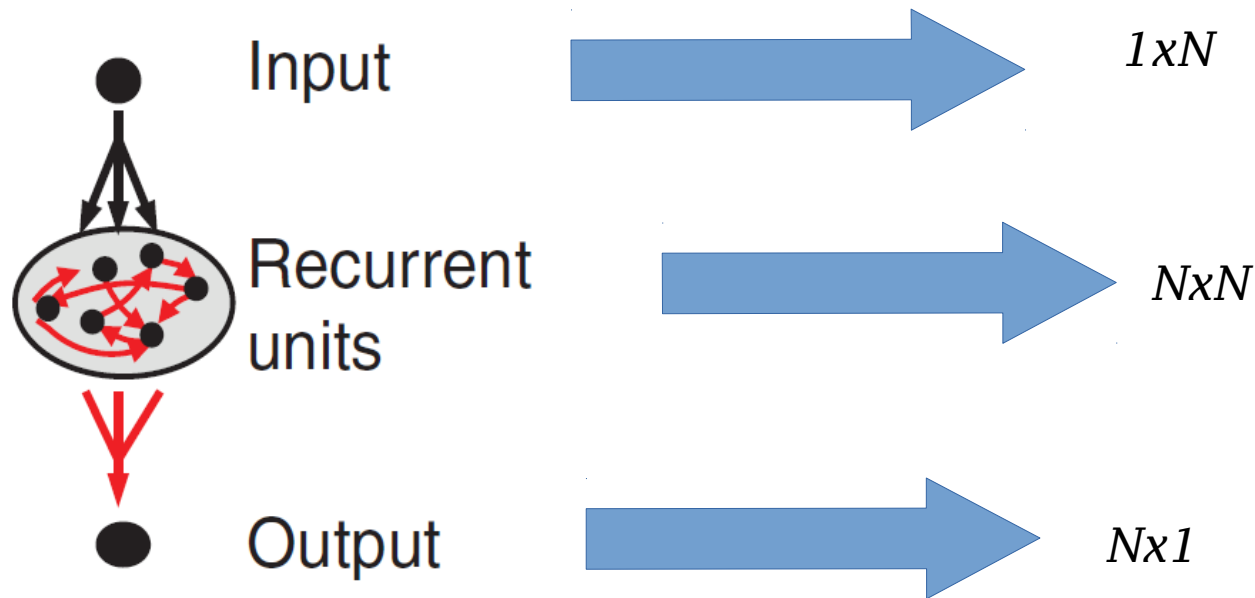
# *Timing and sequences from chaos*

Ernesto  
Raul



*Raúl Pérez Peláez  
Ernesto Segredo Otero*

# *Timing and sequences from chaos*



$$\tau \frac{dx_i}{dt} = -x_i + \sum_{j=1}^N W_{ij}^{\text{Rec}} r_j + \sum_{j=1}^2 W_{ij}^{\text{In}} y_j + I_i^{\text{noise}}$$

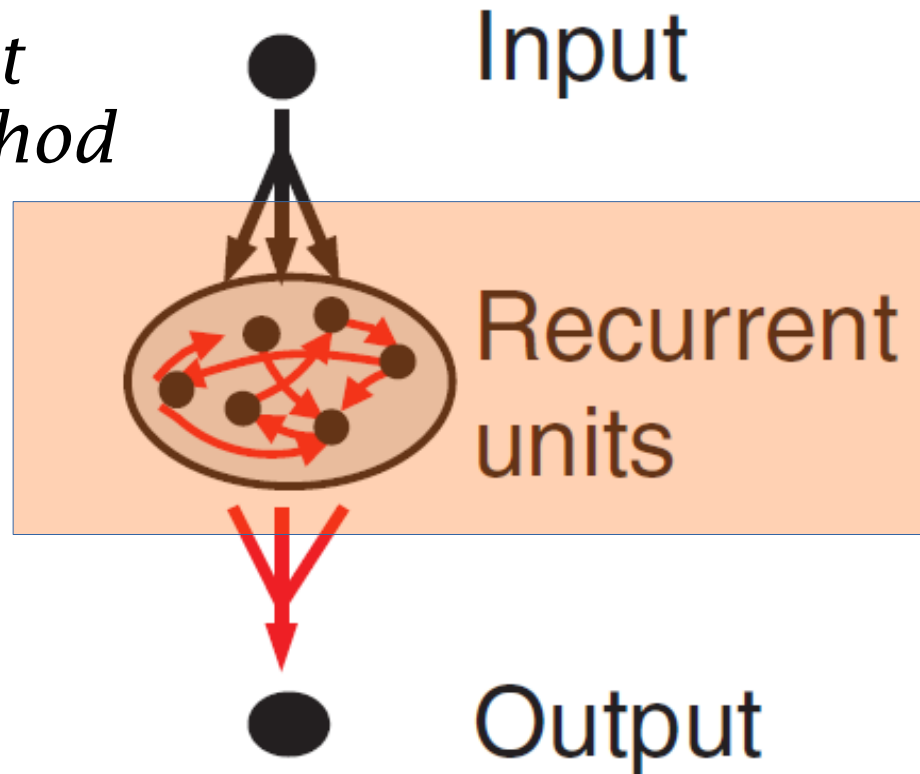
$$r_i = \tanh(x_i)$$

$$z = \sum_{j=1}^N W_{ij}^{\text{Out}} r_j$$

*Dynamic  
system*

# Timing and sequences from chaos

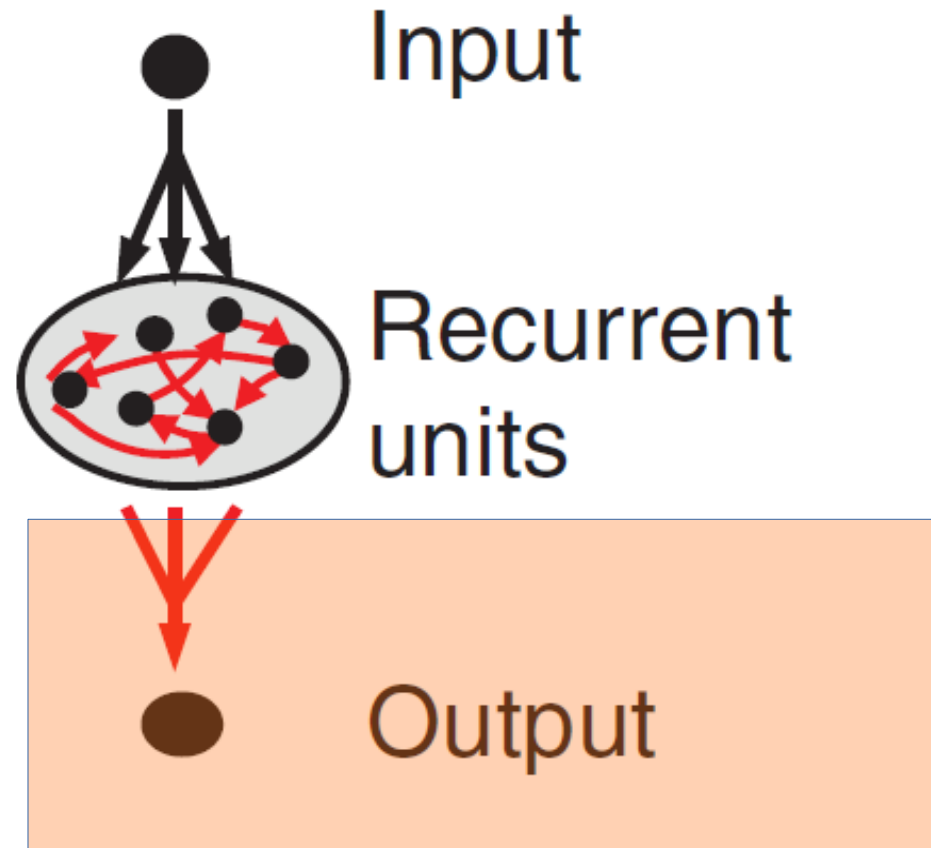
*Sussillo & Abbott*  
*RLS/FORCE method*



$$W_{ij}^{\text{Rec}}(t) = W_{ij}^{\text{Rec}}(t - \Delta t) - e(t) \sum_{k \in B(i)} P_{jk}^i(t) r_k(t)$$
$$e(t) = \sum_j W_j^{\text{out}}(t - \Delta t) r_j(t) - f(t)$$

# *Timing and sequences from chaos*

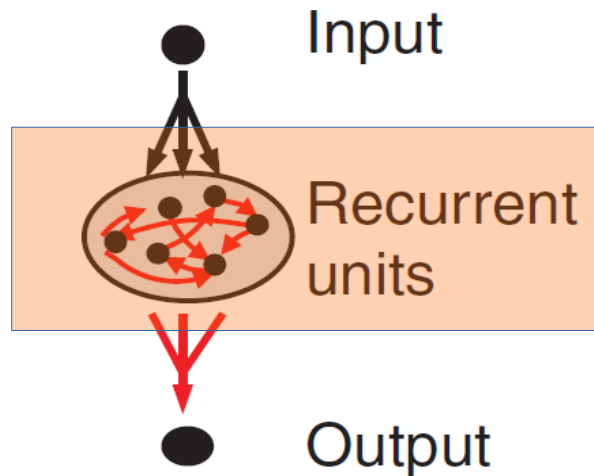
*Authors*



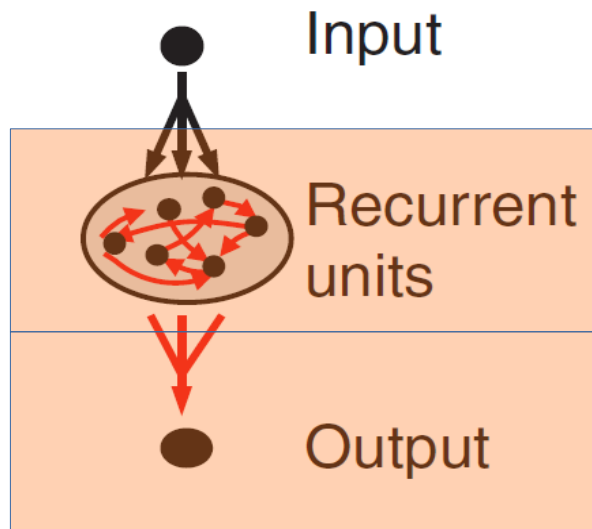
$$W_i^{\text{Out}}(t) = W_i^{\text{Out}}(t - \Delta t) - e(t) \sum_j P_{ij}(t) r_j(t)$$

$$e(t) = \sum_j W_j^{\text{out}}(t - \Delta t) r_j(t) - f(t)$$

# Timing and sequences from chaos



➡ *Less chaos*



*RLS/FORCE adaptation method*

$$W_{ij}^{\text{Rec}}(t) = W_{ij}^{\text{Rec}}(t - \Delta t) - e_i(t) \sum_{k \in B(i)} P_{jk}^i(t) r_k(t)$$

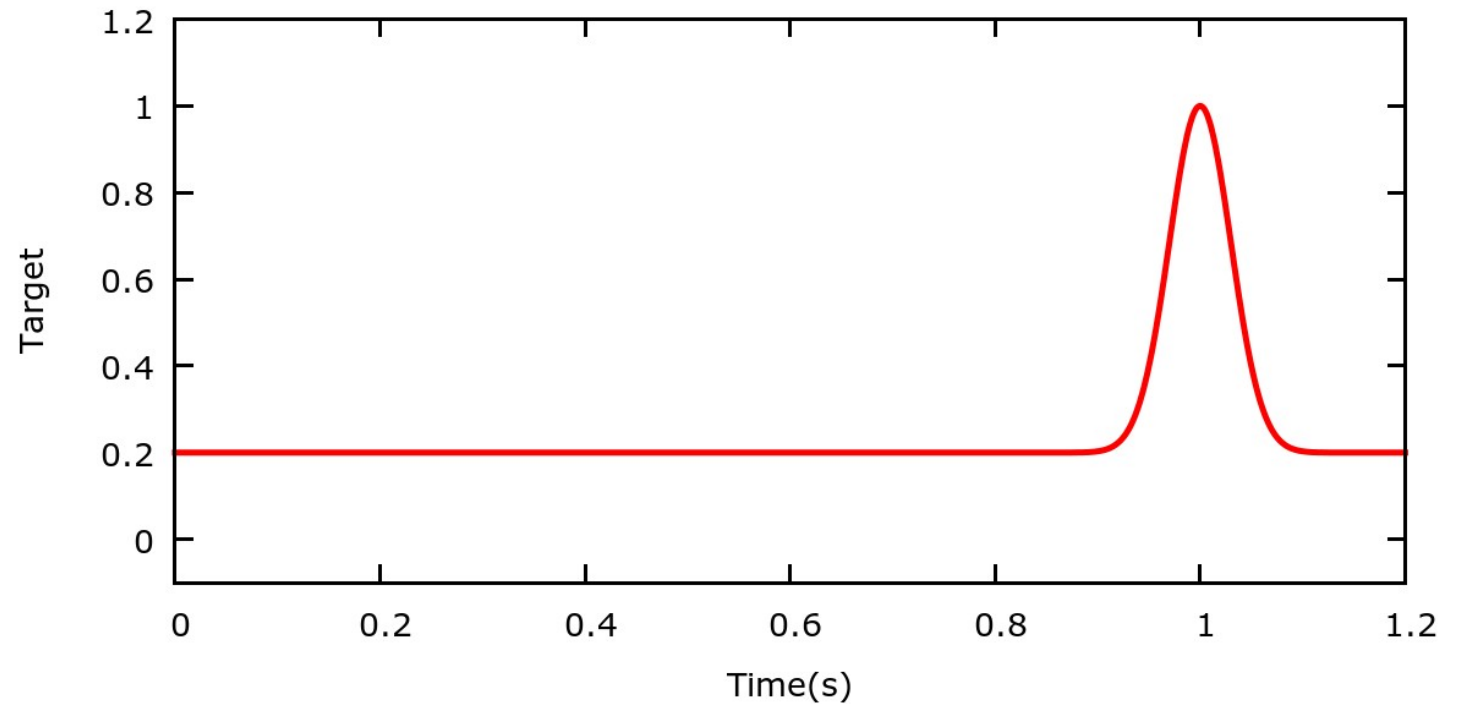
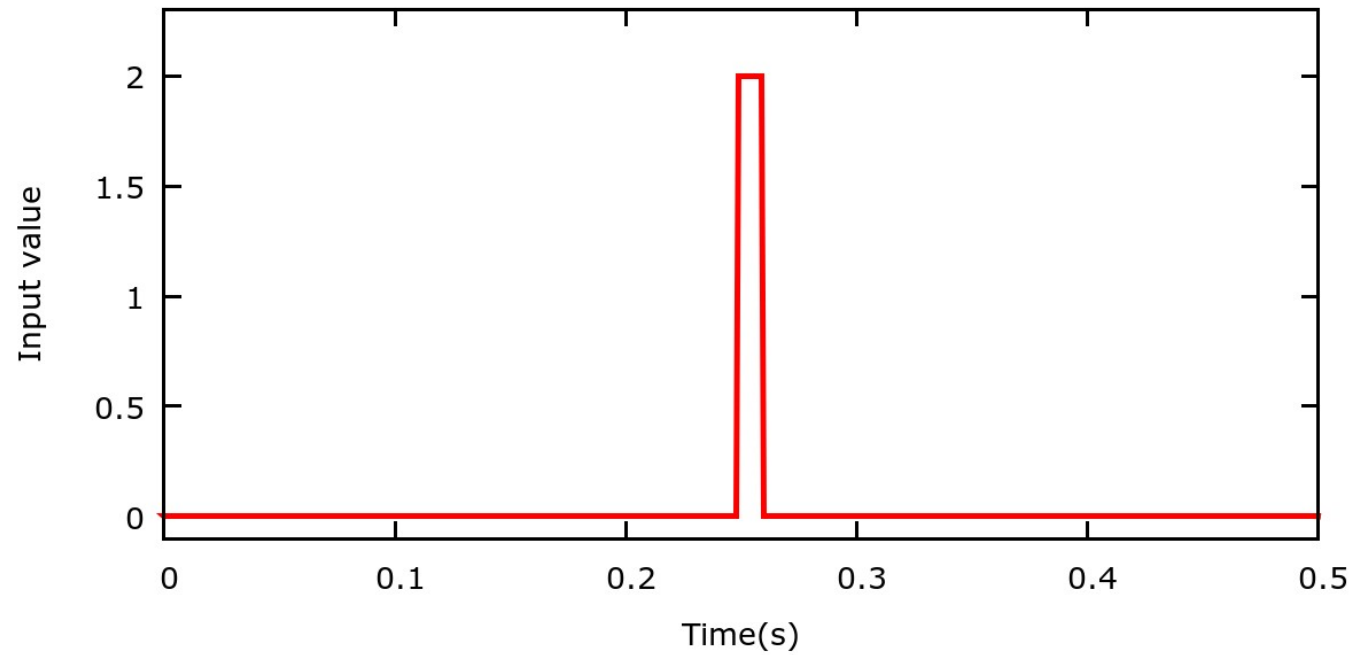
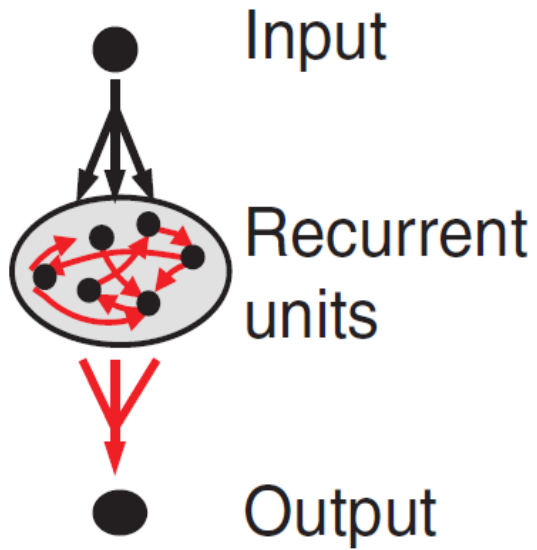
$$e_i(t) = r_i(t) - R_i(t)$$

# *Timing and sequences from chaos*

## *Learning process*

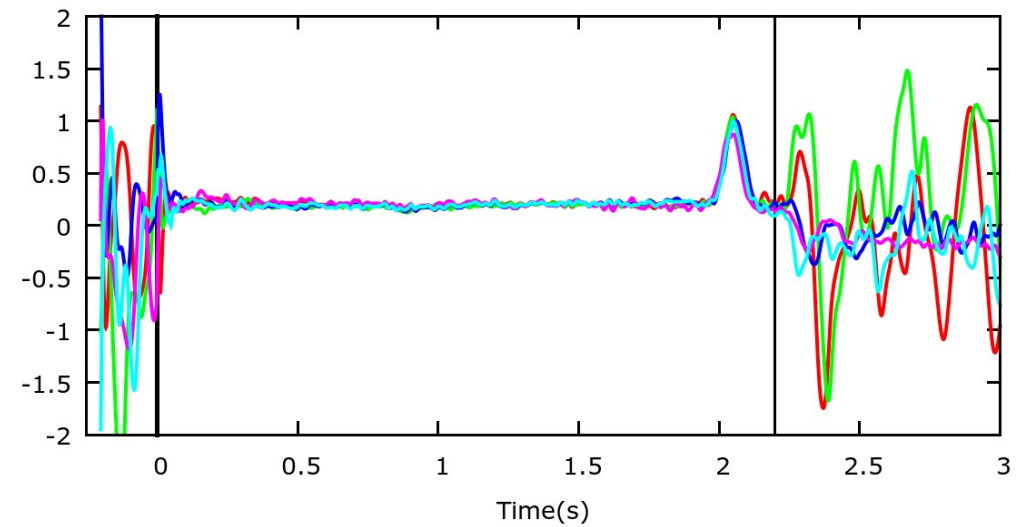
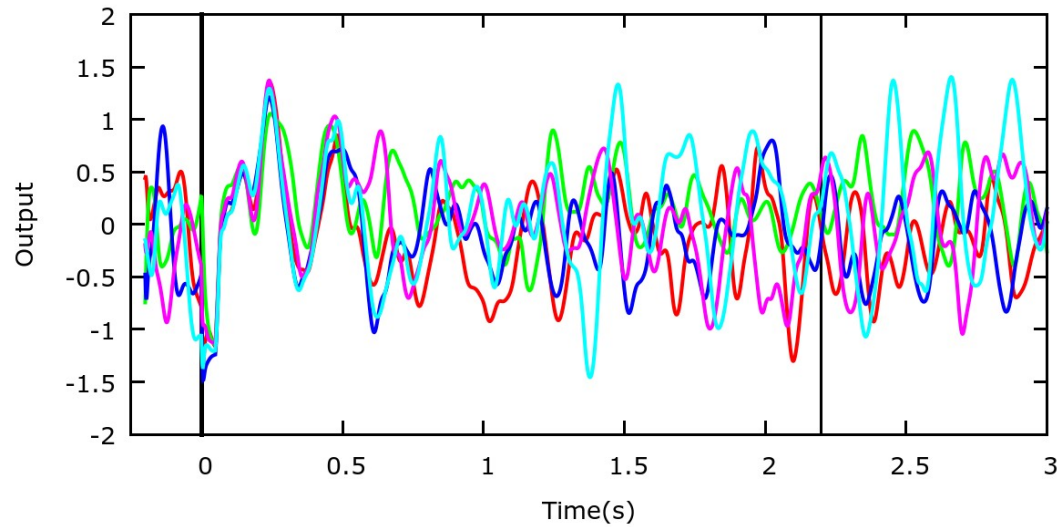
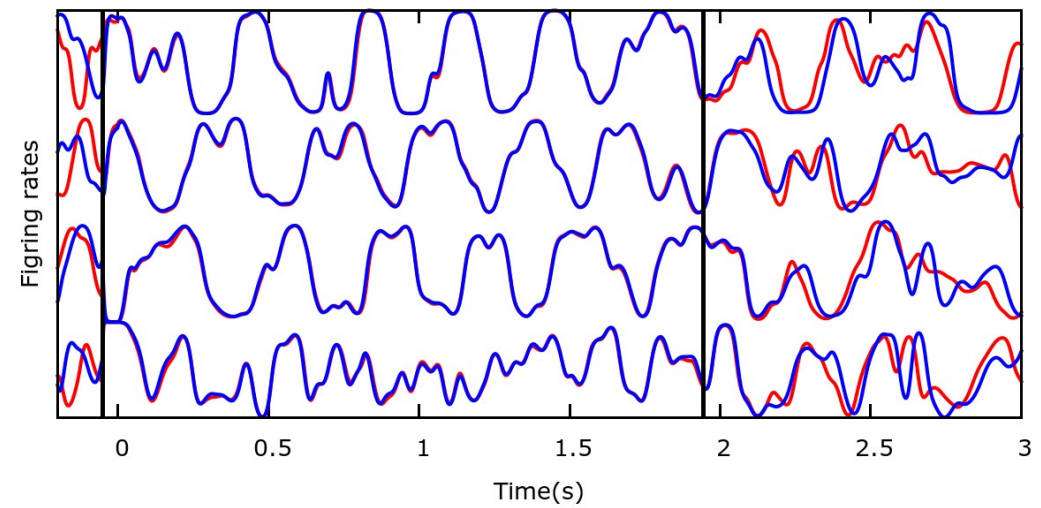
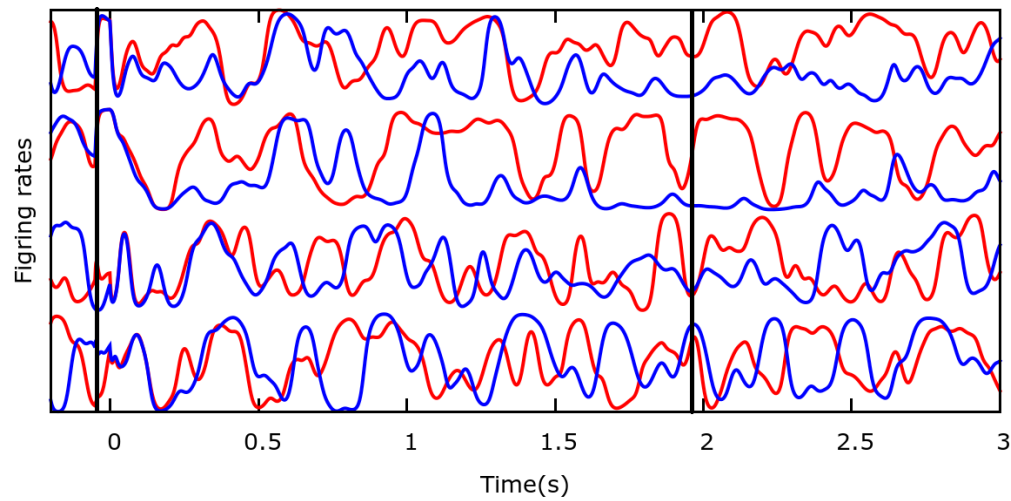
- 1. Let the system evolve freely (only dynamic system).*
- 2. At the end of the step “1”, save the activity (rates) of the recurrent units.*
- 3. Apply our new training rule, using the saved activity as the innate trajectories.*
- 4. After training the RRN, train (with the FORCE/RLS) some output network to reproduce any desired pattern.*

# *Timing and sequences from chaos*





# *Timing and sequences from chaos*



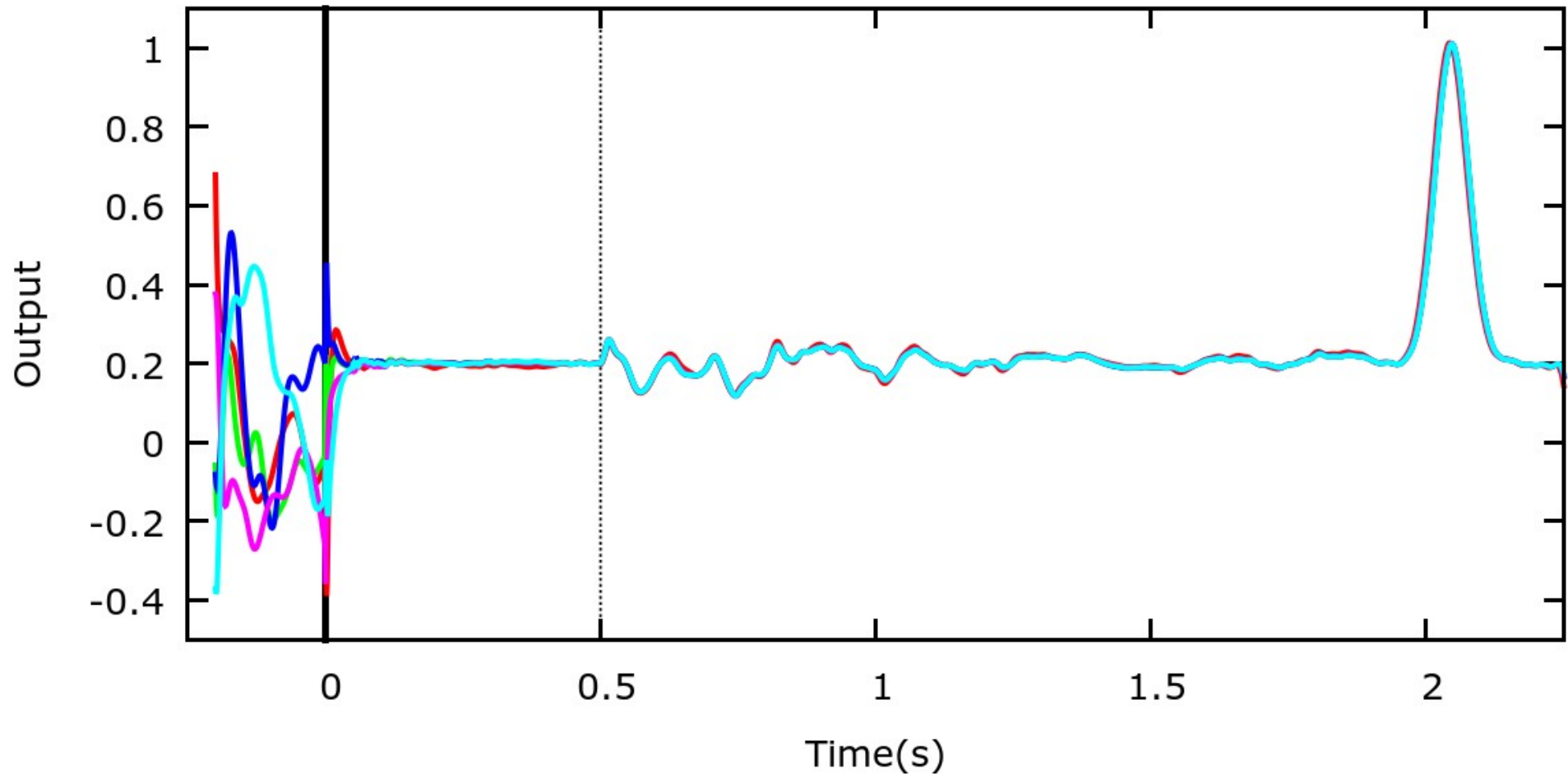
*Not trained process*

*Trained process*



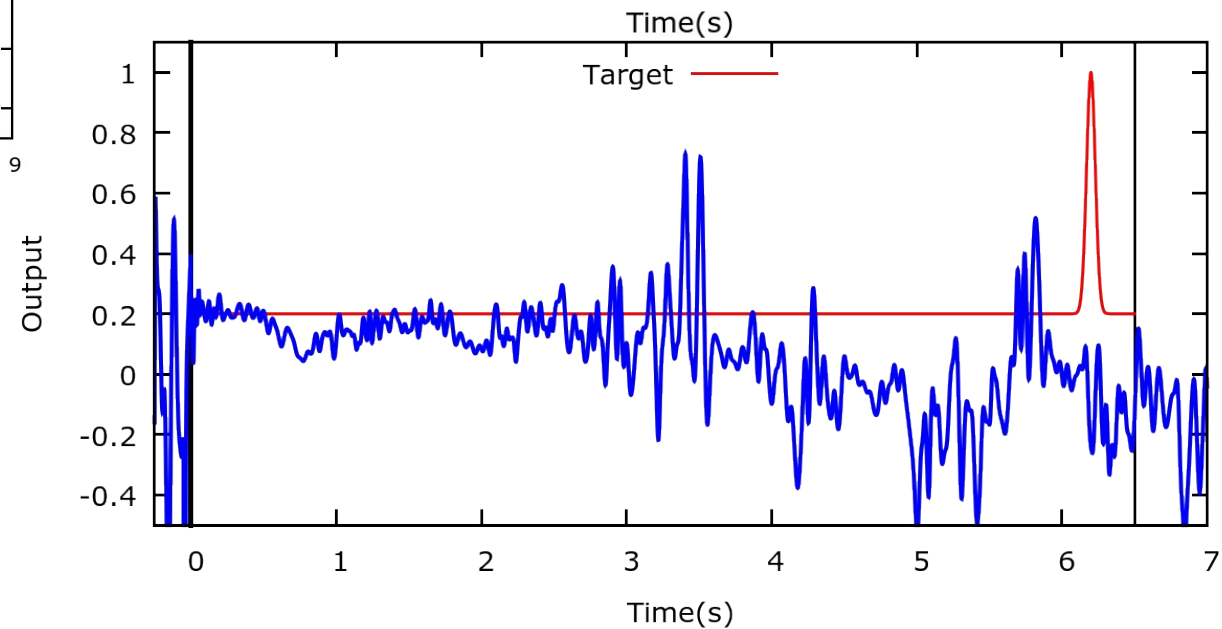
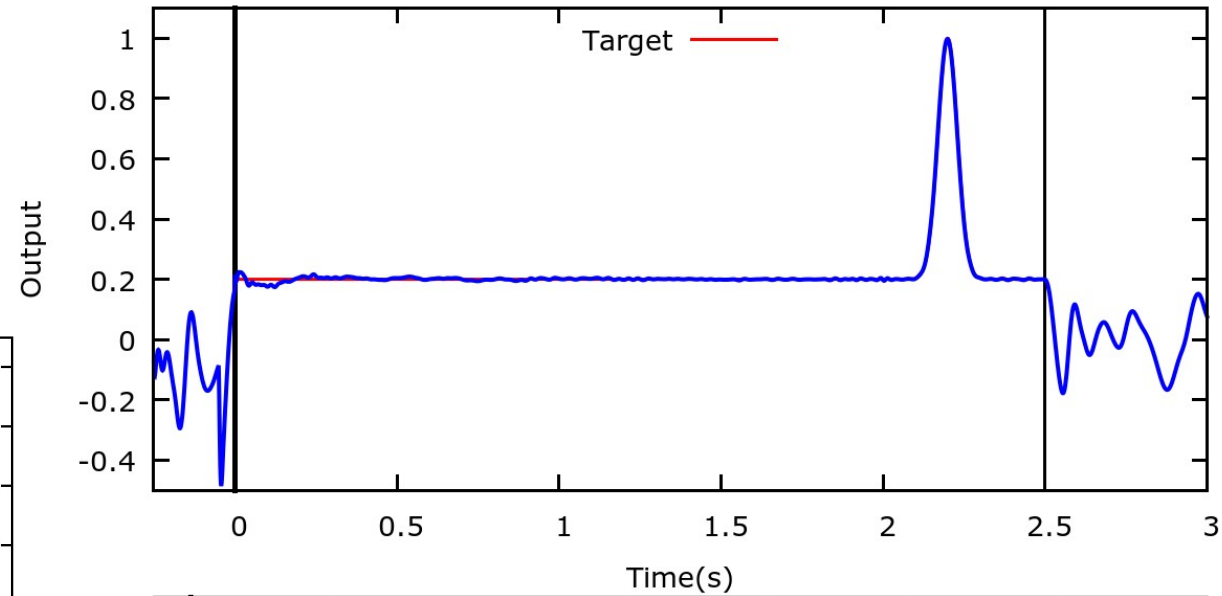
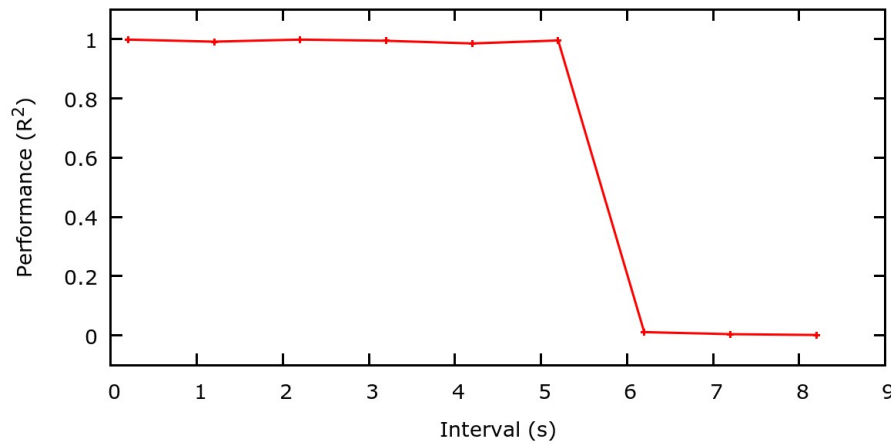
# *Timing and sequences from chaos*

*The system recovers from a perturbation!*



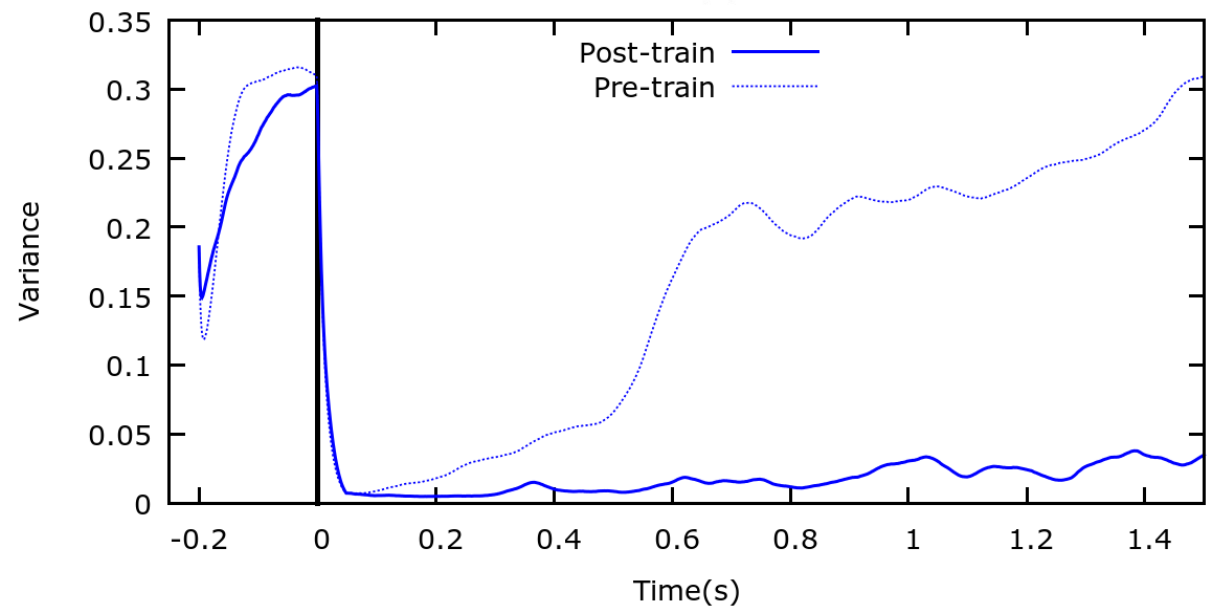
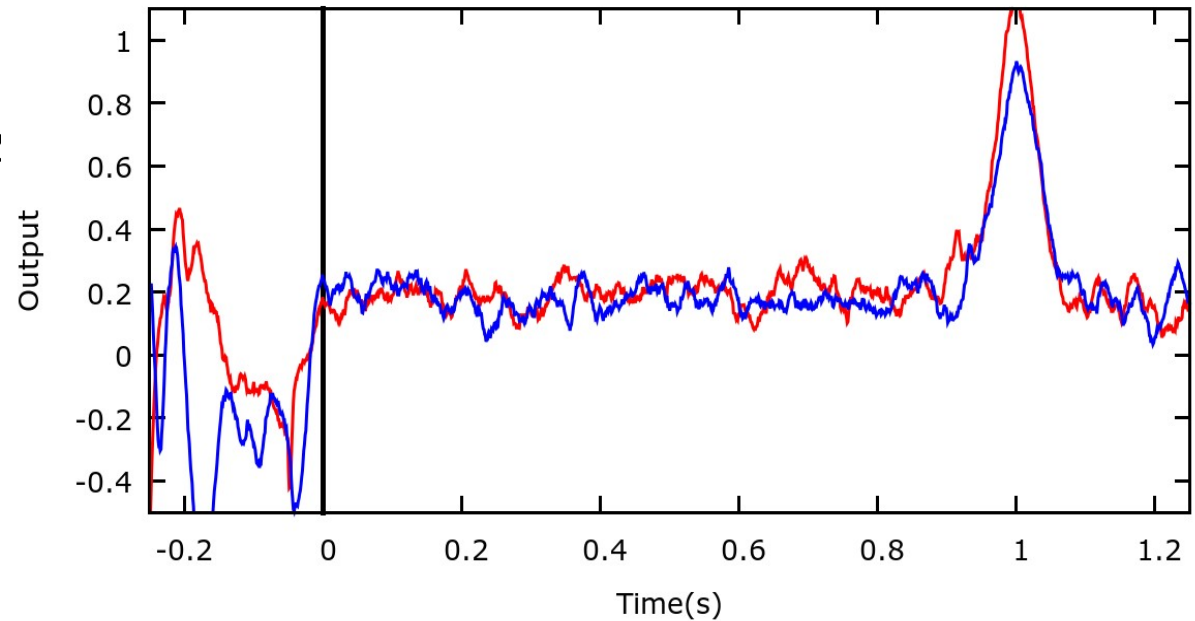
# *Timing and sequences from chaos*

*The system has a memory limit*

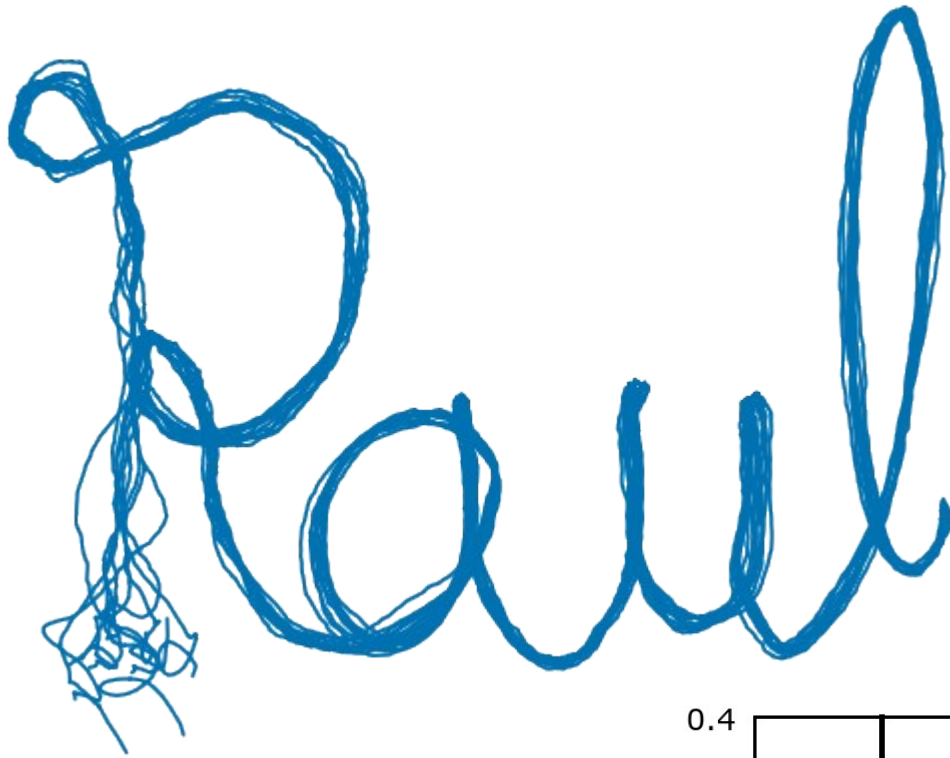


# *Timing and sequences from chaos*

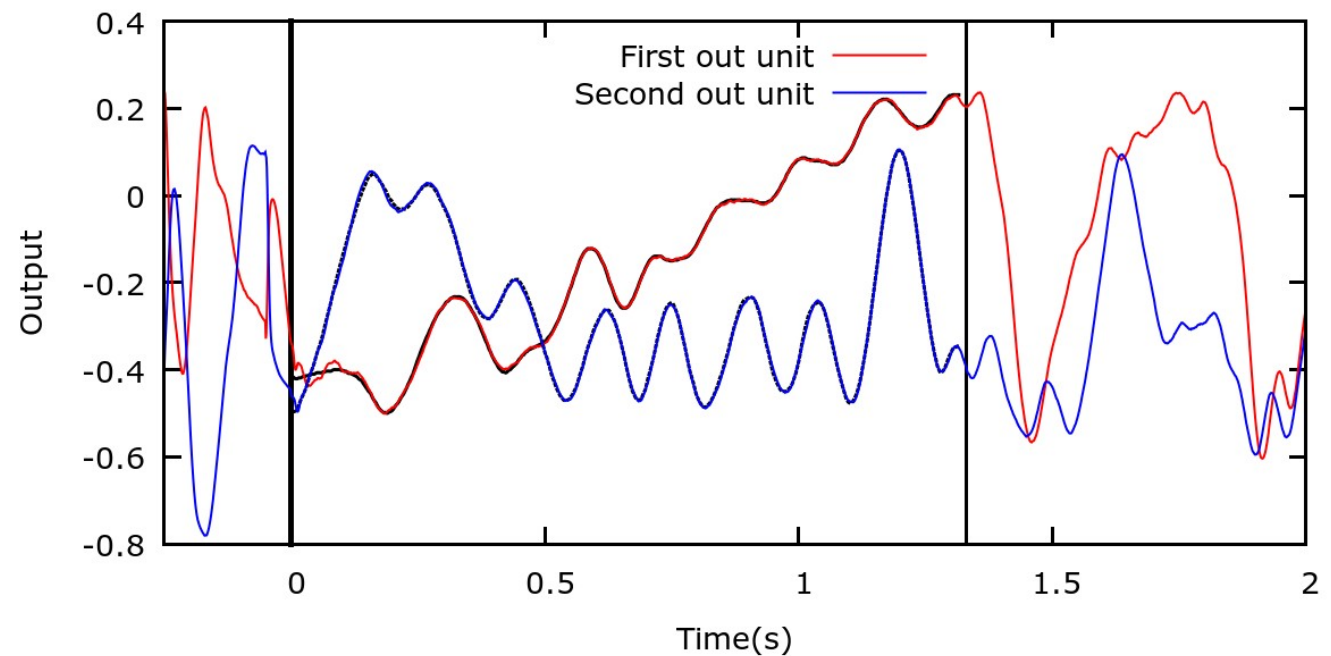
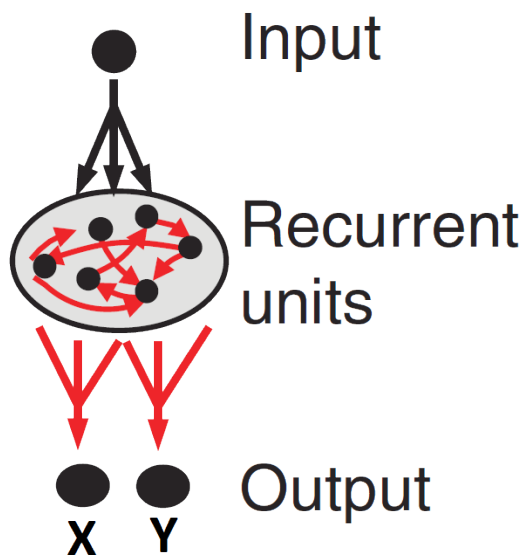
*Training reduces the chaotic response!*



# *Timing and sequences from chaos*



*We can have multiple  
input/output units!*



# *Timing and sequences from chaos*

## *Summary*

*The authors train the RRN to do some natural pattern, and use the right output network to generate any desirable pattern.*

*We studied their model and performed a c++ code which reproduces most of their results.*

*We were able to check, as the authors claimed, that the training process reduces the chaotic behavior of the RRN, and increases the memory of the system*

*We developed a faster code to study the system, and created an Android app which allowed us to analyze any 2D pattern in an easy way.*

# *Timing and sequences from chaos*