Groups Formulary

Raúl Ultralaser

Semigroups and groups

The simplest algebraic structure to recognize is a semigroup, which is defined as a nonempty set S with an associative binary operation.

Definition 1. Let (S, \cdot) be a semigroup. If there is an element e, in S such that

$$ex = x = xe$$
 for all $x \in S$,

then e is called the identity of the semigroup (S, \cdot) .

Definition 2. Let (S, \cdot) be a semigroup with identity e. Let $a \in S$. If there exist an element b in S such that

$$ab=e=ba$$

then b is called the inverse of a, and a is said to be invertible

Definition 3. A nonempty set G with a binary operation \cdot on G is called a group if the following axioms hold:

- (i) $a(bc) = (ab)c \text{ for all } a, b, c \in G.$
- (ii) There exist $e \in G$ such that ea = a for all $a \in G$.
- (iii) For every $a \in G$ there exist $a' \in G$ such that a'a = e

Theorem 1. A semigroup G is a group if and only if for all a, b in G, each of the equations ax = b and ya = b has a solution.

Theorem 2. A finite semigroup G is a group if and only if the cancelation laws hold for all elements in G; that is,

$$ab = ac \Rightarrow b = c$$
 and $ba = ca \Rightarrow b = c$

for all $a, b, c \in G$

Homomorphism

Definition 1. Let G, H be groups. A mapping

$$\phi: G \to H$$

is called a homomorphism if for all $x, y \in G$

$$\phi(xy) = \phi(x)\phi(y)$$

Furthermore, if ϕ is bijective, then ϕ is called an isomorphism of G onto H, and we write $G \simeq H$. If ϕ is just injective, that is, 1-1, then we say that ϕ is an isomorphism (or monomorphism) of G into H. if ϕ is surjective, that is, onto, then ϕ is called an epimorphism, A homomorphism of G into itself is called an endomorphism of G that is both G and onto is called an automorphism of G.

If $\phi: G \to H$ is called an intro homomorphism, then H is called a homomorphic image of G; also, G is said to be homomorphic to H. If $\phi: G \to H$ is a 1-1 homomorphism, then G is said to be embeddable in H, and we write $G \circlearrowleft H$.

Theorem 1. Let G and H be groups with identities e and e', respectively, and let $\phi: G \to H$ be a homomorphism. Then

- (i) $\phi(e) = e'$
- (ii) $\phi(x^{-1}) = (\phi(x))^{-1}$ for each $x \in G$.

Definition 2. Let G and H be groups, and let ϕ : $G \to H$ be a homomorphism. The kernel of ϕ is defined to be the set

$$Ker\phi = \{x \in G | \phi(x) = e'\}$$

where e' is the identity in H

Theorem 2. A homomorphism $\phi: G \to H$ is injective if and only if $Ker\phi = \{e\}$

Subgroups and cosets

Definition 1. Let (G, \cdot) be a group and let H be a subset of G. H is called a subgroup of G, written H < G, if H is a group relative to the binary operation in G.

Theorem 1. Let G be a group. A nonempty subset H of G is a subgroup of G if and only if either of the following holds:

- (i) For all $a, b \in H$, $ab \in H$, and $a^{-1} \in H$.
- (ii) For all $ab \in H$, $ab^{-1} \in H$.

Theorem 2. Let (G, \cdot) be a group. A nonempty finite subset H of G is a subgroup if and only if $ab \in H$ for all $a.b \in H$

Theorem 3. Let $\phi: G \to H$ be a homomorphism of groups. Then $Ker\phi$ is a subgroup of G and $Im\phi$ is a subgroup of H.

Definition 2. The center of a group G, written Z(G), is the set of those elements in G that commute with every element in G; that is,

$$Z(G) = \{ a \in G | ax = xa \text{ for all } x \in G \}$$

Theorem 4. The center of a group G is a subgroup of G

Theorem 5. Let H and K be subgroups of a group (G, \cdot) . Then HK is a subgroup of G if and only if HK = KH.

Theorem 6. Let S be a nonempty subset of a group G. Then the subgroup generated by S is the set M of all finite products $x_1, x_2, ..., x_n$ such that, for each i, $x_i \in S$ or $x_i^{-1} \in S$

Theorem 7. Let G be a group and $a \in G$

- (i) If $a^n = e$ for some integer $n \neq 0$, then o(a)|n
- (ii) If o(a) = m then for all integers $i, a^i = a^{r(i)}$, where r(i) is the remainder of i modulo m.
- (iii) [a] is of order m if and only if o(a) = m.

Corollary 1. If G is a finite group, then there exist a positive integer k such that $x^k = e$ for all $x \in G$.

Definition 3. Let H be a subgroup of G. Given $a \in G$, the set

$$aH = \{ah | h \in H\}$$

is called the left coset of H determined by a. A subset C of G is called a left coset of H in G if C = aH for some a in G. The set of all left cosets of H in G is written G/H

Definition 4. Let H be a subgroup of G. The cardinal number of the set of left (right) cosets of H in G is called the index of H in G and denoted by [G:H].

Theorem 8 (Lagrange). Let G be a finite group. Then the order of any subgroup of G divides the order of G.

Corollary 2. Let G be a finite group of order n. Then for every $a \in G$, o(a)|n, and, hence, $a^n = e$.

Consequently, every finite group of prime order is cyclic and, hence, abelian.

Cyclic groups

Theorem 1. Every cyclic group is isomorphic to \mathbb{Z} or to $\mathbb{Z}/(n)$ for some $n \in \mathbb{N}$

Theorem 2. Any two cyclic groups of the same order (finite or infinite) are isomorphic.

Theorem 3. Every subgroup of a cyclic group is cyclic.

Theorem 4. Let G be a finite cyclic group of order n, and let d be a positive divisor of n. Then G has exactly one subgroup of order d.

Permutation groups

Definition 1. Let X be a nonempty set. The group of all permutations of X under composition of mappings is called the symmetric group on X and is denoted by S_x . A subgroup of S_x is called a permutation group on X.

Definition 2. Let $\sigma \in S_n$. If there exist a list of distinct integers $x_1, ..., x_n \in n$, such that,

$$\sigma(x_i) = x_{i+1}, \qquad i = 1, ..., r - 1,$$

$$\sigma(x_r) = x_1,$$

$$\sigma(x) = x \qquad \text{if } x \notin \{x_1, ..., x_r\}.$$

then σ is called a cycle of length r and denoted by $(x_1,...,x_r)$. A cycle of length 2 is called a transposition.

Theorem 1 (Cayley). Every group is isomorphic to a permutation group.

Definition 3. The group of symmetries of a regular polygon P_n of n sides is called the dihedral group of degree n and denoted by D_n

Theorem 2. The dihedral group D_n is a group of order 2n generated by two elements σ, τ satisfying $\sigma^n = e = \tau^2$ and $\tau \sigma = \sigma^{n-1}\tau$, where

$$\sigma = (1 \ 2 \dots n), \quad \tau = \begin{pmatrix} 1 & 2 & \cdots & n \\ 1 & n & \cdots & 2 \end{pmatrix}$$

Geometrically, σ is a rotation of the regular polygon P_n through an angle $2\pi/n$ in its own plane, and τ is a reflection (or a turning over) in the diameter through the vertex 1.

Definition 4. The dihedral group D_4 is called the octic group.

Generators and relations

Definition 1. Let G be a group generated by a subset X of G. A set of equations $(r_j = 1)_{j \in A}$ that suffice to construct the multiplication table of G is called a set of defining relations for the group $(r_j$ are products of elements of X).

The set X is called a set of generators. The system $(X; (r_j = 1)_{j \in A})$ is called a presentation of the group.

Normal subgroups

Normal subgroups and quotient groups

Definition 1. Let G be a group. A subgroup N of G is called a normal subgroup of G, written $N \triangleleft G$, if $xNx^{-1} \subset N$ for every $x \in G$.

Theorem 1. Let N be a subgroup of a group G. Then the following are equivalent.

- (i) $N \triangleleft G$
- (ii) $xNx^{-1} = N$ for every $x \in G$
- (iii) xN = Nx for every $x \in G$
- (iv) (xN)(yN) = xyN for all $x, y \in G$.

Theorem 2. Let N be a normal subgroup of the group G. Then G/N is a group under multiplication. The mapping $\phi: G \to G/N$, given by $x \mapsto xN$, is a surjective homomorphism, and $Ker\phi = N$

Definition 2. Let N be a normal subgroup of G. The group G/N is called the quotient group of G by N. The homomorphism $G \to G/N$, given by $x \mapsto xN$, is called the natural (or canonical) homomorphism of G onto G/N.

Definition 3. Let G be a group, and let S be a nonempty subset of G. The normalizer of S in G is the set

$$N(S) = \{ x \in G | xSx^{-1} = S \}$$

The normalizer of a singleton $\{a\}$ is written N(a).

Theorem 3. Let G be a group. For any nonempty subset S of G, N(S) is a subgroup of G. Further, for any subgroup H of G,

- (i) N(H) is the largest subgroup of G in which H is normal;
- (ii) if K is a subgroup of N(H), then H is a normal subgroup of KH.

Definition 4. Let G be a group. For any $a, b \in G$, $aba^{-1}b^{-1}$ is called a commutator in G. The subgroup of G generated by the set of all commutators in G is called the commutator subgroup of G (or the derived group of G) and denoted by G'

Theorem 4. Let G be a group, and let G' be the derived of G. Then

- (i) $G' \triangleleft G$
- (ii) G/G'isabelian
- (iii) if $H \triangleleft G$, then G/H is abelian if and only if $G' \subseteq H$.

Isomorphism theorems

Theorem 1 (First isomorphism theorem). Let $phi: G \to G'$ be a homomorphism of groups. Then

$$G/Ker\phi \simeq Im\phi$$

Hence, in particular, if ϕ is surjective, then

$$G/Ker\phi \simeq G'$$

Corollary 1. Any homomorphism $\phi: G \to G'$ of groups can be factored as

$$\phi = j \cdot \psi \cdot \eta$$

where $\eta: G \to G/Ker\phi$ is the natural homomorphism, $\psi: G/Ker\phi \to Im\phi$ is the isomorphism obtained in the theorem, and $j: Im\phi \to G'$ is the inclusion map.

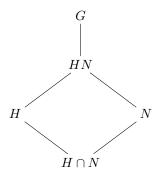
$$G \xrightarrow{\phi} G'$$

$$\downarrow^{\eta} \qquad \qquad j \\
G/Ker\phi \xrightarrow{\phi} Im\phi$$

Theorem 2 (Second isomorphism theorem). Let H and N be subgroups of G, and $N \triangleleft G$. Then

$$H/H\cap N\simeq HN/N$$

The inclusion diagram shown below is helpful in visualizing the theorem. Because of this, the theorem is known as the "diamond isomorphism theorem".



Theorem 3 (Third isomorphism theorem). Let H and K be normal subgroups of G and $K \subset H$. Then

$$(G/K)(H/K) \simeq G/H$$

This theorem is also known as the "double quotient isomorphism theorem".

Theorem 4. Let G_1 and G_2 be groups, and $N_1 \triangleleft G_1, N_2 \triangleleft G_2$. Then $(G_1 \times G_2)/(N_1 \times N_2) \simeq (G_1/N_1) \times (G_/N_2)$.

Theorem 5 (correspondence theorem). Let ϕ : $G \to G'$ be a homomorphism of a group G onto a group G'. Then the following are true:

- (i) $H < G \Rightarrow \phi(H) < G'$.
- $(i)' \quad H' < G' \Rightarrow \phi^{-1}(H') < G.$
- (ii) $H \triangleleft G \Rightarrow \phi(H) \triangleleft G'$
- (ii)' $H' \triangleleft G' \Rightarrow \phi^{-1}(H') \triangleleft G$
- (iii) $H < G \text{ and } H \supset Ker \phi \Rightarrow H = \phi^{-1}(\phi(H))$
- (iv) The maping $H \mapsto \phi(H)$ is a 1-1 correspondence between the family of subgroups of G'; futhermore, normal subgroups of G correspond to normal subgroups of G'.

Corollary 2. Let N be a normal subgroup of G. Given any subgroup H' of G/N, there is a unique subgroup H of G such that H' = H/N. Further, $H \triangleleft G$ if and only if $H/N \triangleleft G/N$.

Definition 1. Let G be a group. A normal subgroup N of G is called a maximal normal subgroup if

- (i) $N \neq G$
- (ii) $H \triangleleft G$ and $H \supset N \Rightarrow H = N$ or H = G.

Definition 2. A group of G is said to be simple if G has no proper normal subgroups; that is, G has no normal subgroups except (e) and G.

Corollary 3. Let N be a proper normal subgroup of G. Then N is a maximal normal subgroup of G if and only if G/N is simple.

Corollary 4. Let H and K be a distinct maximal normal subgroups of G. Then $H \cap K$ is a maximal normal subgroup of H and also of K.

Automorphisms

Recall that an automorphism of a group G is an isomorphism of G onto G. The set of all automorphism of G is denoted by Aut(G). We have seen that every $g \in G$ determines an automorphism I_g of G (called an inner automorphism) given by $x \mapsto gxg^{-1}$. The set of all inner automorphism of G IS DENOTED BY In(G).

Theorem 1. The set Aut(G) of all automorphism of a group G is a group under composition of mappings, and $In(G) \triangleleft Aut(G)$. Moreover,

 $G/Z(G) \simeq In(G)$

Conjugacy and G-sets

Normal series

Normal series

Solvable groups

Nilpotent groups

Permutation groups

Cyclic decomposition

Alternating group

Simplicity of A_n

Structure theorems of groups

Direct products