

5/4/24

- Ohm's law :

$$\boxed{\vec{J} = \sigma \vec{E}}$$

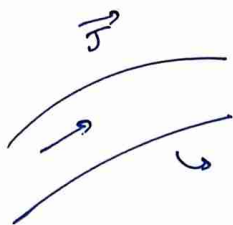
, σ : conductance.

→ Insulators have very low σ , and conductors very high σ .

Can approximate σ to ∞ .

$$\Rightarrow \text{For conductors, } \vec{E} = \frac{\vec{J}}{\sigma} = 0$$

→ \Rightarrow Current flow is there but without electric field

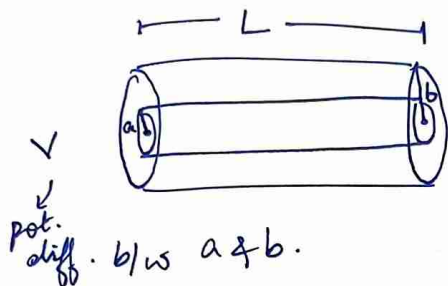


Conductor : $\vec{E} = 0$ inside conductor.

& But there is current flow. (Contradiction!)
How?

Because $\vec{E} = 0$ is valid only for electrostatics.

Eg:



Both cylinders are charged.

pot. diff. b/w a & b.

There'll be current flow radially.

$$\text{From } E(2\pi r L) = \frac{Q}{\epsilon_0} \quad \text{on cyl. on rad. } a$$

At some dist. r

$$\vec{E} = \frac{Q/L}{2\pi\epsilon_0 r} \hat{r}$$

$$V = - \int_b^a \vec{E} \cdot d\vec{l}$$

$$= - \int_b^a \frac{Q}{2\pi\epsilon_0 L r} dr$$

$$= \frac{+Q}{2\pi\epsilon_0 L} \ln\left(\frac{b}{a}\right)$$

$$= \frac{\lambda}{2\pi\epsilon_0} \ln\left(\frac{b}{a}\right)$$

$$J = \sigma E = \frac{\sigma \lambda}{2\pi\epsilon_0 r}$$

$$\begin{aligned}
 I &= \int \vec{J} \cdot d\vec{a} \\
 &= \int \frac{\sigma \lambda}{2\pi \epsilon_0 r} 2\pi r L \\
 &= \frac{\sigma \lambda L}{\epsilon_0}
 \end{aligned}$$

$$I = \iiint \frac{\sigma \lambda}{2\pi \epsilon_0 r} r dr d\phi dz$$

$$= \frac{\sigma \lambda (b-a) L}{2\pi \epsilon_0}$$

$$= \frac{\sigma \lambda (b-a) L}{\epsilon_0}$$

$$\Rightarrow \lambda = \frac{I \epsilon_0}{\sigma (b-a) L}$$

$$V = \frac{I \epsilon_0}{\sigma (b-a) L} \left(\frac{1}{2\pi \epsilon_0} \right) \ln \left(\frac{b}{a} \right)$$

$$\Rightarrow V \propto I$$

→ So if there is electric field, then $F = qE$.

⇒ Charge is accelerated.

So then $i = \frac{dq}{dt}$ should continuously increase.

But this doesn't happen because the charges are continuously colliding with each other.

So they can't accelerate.

~~File~~

→ Joule's law.

$$\text{Power} = VI$$

$$= I^2 R$$

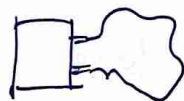
$$\left(V = \frac{W}{q}, I = \frac{q}{t} \Rightarrow VI = \frac{W}{t} \right)$$

Energy per unit time

So energy is lost continuously.

How is the energy loss getting compensated?

What is the work done by the \vec{E} .



$$\oint \vec{E} \cdot d\vec{l} = 0$$

$$\int (\vec{\nabla} \times \vec{E}) \cdot d\vec{a} = 0$$

So the electric field that is driving the charges is not doing any work.

So the energy that is actually driving the current comes from the battery and it's called ~~elect~~

ELECTROMOTIVE FORCE

→ (Not force, it's energy).

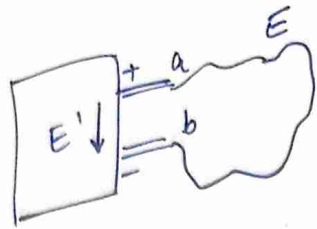
→ Inside the battery, charge gets accumulated on both the terminal. So \vec{E} exists inside battery.

$$\Rightarrow \vec{J} = \sigma (\vec{E} + \vec{E}')$$

(Inside battery)

If ideal conductor,

$$\frac{J}{\sigma} = 0 \Rightarrow \vec{E} + \vec{E}' = 0 \Rightarrow \boxed{\vec{E} = -\vec{E}'}$$



Pot. diff. in battery / Voltage of battery =

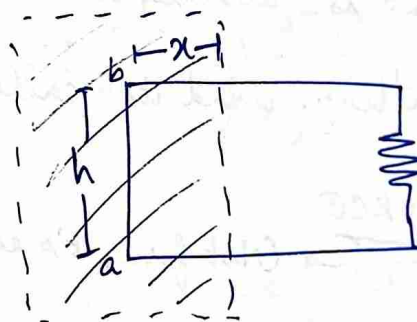
Voltage of battery = The energy lost by the battery to drive a charge from a to b

$$V = - \int_a^b \vec{E} \cdot d\vec{l} = \oint \vec{E} \cdot d\vec{l} = \mathcal{E}$$

\mathcal{E} is there only inside the battery. So can be written as $\oint \vec{E} \cdot d\vec{l} :: E=0$ outside

→ Other examples of electromotive force:
Generator.

• Principle of generators



$$b-a=h$$

$\vec{B} \otimes$

Current flows thru the loop.

Because of Lorentz force, ~~the~~ the charge experience force, and current flows thru the wire.

$$\mathcal{E} = \int \vec{E}_{\text{mg}} \cdot d\vec{\ell}$$

$$= \int \frac{\text{Force}}{q} \cdot d\vec{\ell} = \int \frac{q(\vec{v} \times \vec{B})}{q} \cdot d\vec{\ell}$$

$$= \int (\vec{v} \times \vec{B}) \cdot d\vec{\ell}$$

Here $\vec{v} \perp \vec{B} \Rightarrow \vec{v} \times \vec{B} = vB$

$$\mathcal{E} = vB(b-a)$$

$$\boxed{\mathcal{E} = vBh}$$

→ The magnetic field doesn't do any work.

→ The work is actually done by the mechanical force which is pulling the loop to give it a velocity v .

(See proof in Griffiths)

Φ → Total flux of magnetic field.

$$\Phi = \int \vec{B} \cdot d\vec{a}$$

$$= Bhx$$

$$\Rightarrow \frac{d\Phi}{dt} = Bh \frac{dx}{dt} = -vBh = -\mathcal{E}$$

$$\Rightarrow \boxed{\mathcal{E} = -\frac{d\Phi}{dt}} \rightarrow \text{Faraday's law}$$

⇒ The ~~rate~~ of change of magnetic field produces electric field.
 ↳ Faraday's.

$\oint \vec{E} \cdot d\vec{l} = - \frac{d\Phi}{dt}$

E.d.l. thru the entire loop

$$\int (\vec{\nabla} \times \vec{E}) \cdot d\vec{a} = \cancel{\frac{d}{dt}} - \frac{\partial}{\partial t} \int \vec{B} \cdot d\vec{a}$$

$$\Rightarrow \boxed{\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}}$$

↳ FARADAY'S LAW.

This is for moving charges.

In electrostatics, $\vec{\nabla} \times \vec{E} = 0$

→ Two methods to generate \vec{E} :

1) → Put a set of charges together

2) → Take a closed loop, and change the magnetic field through the loop. ~~can get~~

→ $\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$, Here \vec{E} is the electric field inside the conductor.

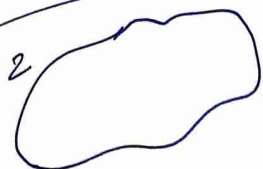
→ Microphone works on this principle.



↳ This vibrates

So then the flux thru the closed loop change. So \vec{E} is generated & hence mechanical energy is converted to electrical energy.

Inductance :

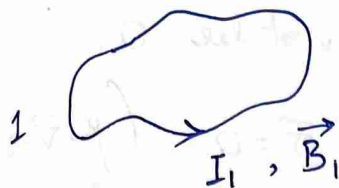


$$I_2 = M_{21} I_1$$

$$I_1 = M_{12} I_2$$

$$M_{21} = M_{12}$$

Mutual inductance.



$$\Phi = \int \vec{B} \cdot d\vec{a}$$

$$B = \frac{\mu_0}{4\pi} I \int ()$$

dependent on geometry of system.

So then if geometry of the system remains same.

$$M_{12} = M_{21}$$

Self inductance

$$\Phi = LI$$

Self inductance

Applications: Transformers

12/4/24

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

Divergence of curl of a vector is 0.

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$$

~~curl of divergence of vector~~

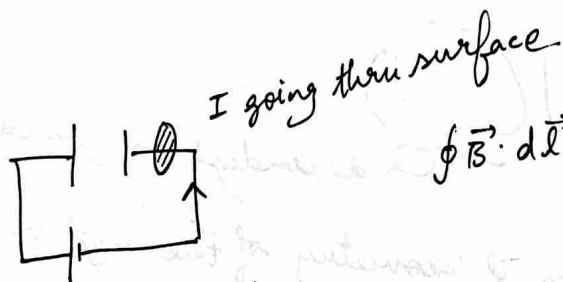
$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) = - \vec{\nabla} \cdot \left(\frac{\partial \vec{B}}{\partial t} \right)$$

$$0 = \cancel{0} \quad (✓)$$

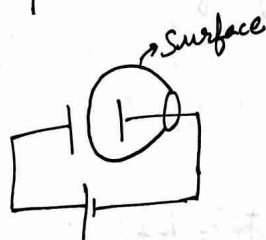
$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0 \quad \text{But } \underbrace{\mu_0 \vec{\nabla} \cdot \vec{J}}_{\substack{\downarrow \\ 0 \text{ only when } \vec{J} = 0}} \text{ need not be } 0. \quad \left(\mu_0 \vec{\nabla} \cdot \vec{J} = \mu_0 \frac{\partial \rho}{\partial t} \right)$$

→ Fundamental problem in Ampere's law. ∴

Experiment.



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}. \quad I \neq 0$$



But now thru this surface, there is no current.
So $I_{enc} = 0$.

Contradiction

So correction term req.

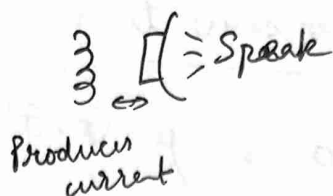
$$\begin{aligned} \mu_0 (\vec{\nabla} \cdot \vec{J}) &= -\mu_0 \frac{\partial \rho}{\partial t} = -\mu_0 \frac{\partial}{\partial t} (\epsilon_0 \vec{\nabla} \cdot \vec{E}) \\ &= -\epsilon_0 \vec{\nabla} \cdot \left(\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) \end{aligned}$$

⇒ Corrected Ampere's law:

$$\boxed{\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}} \quad \rightarrow \text{CORRECTED AMPERE'S LAW}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \cdot (\mu_0 \vec{J}) + \vec{\nabla} \cdot \left(\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) = 0$$

Physical significance of the corrected term is
changing electric field produces magnetic field.



$$\rightarrow \mathcal{I}_d = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

• MAXWELL'S EQ^{NS}:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

→ All these eq^{ns}:
medium: vacuum

In other media,

$$\vec{E} \rightarrow \vec{D} = \epsilon_0 \vec{E}$$

$$\vec{B} \rightarrow \vec{H} = \frac{1}{\mu_0} \vec{B}$$

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

• Charge and energy conservation

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0 = \mu_0 \vec{\nabla} \cdot \vec{J} + \mu_0 \epsilon_0 \frac{\partial}{\partial t} \vec{\nabla} \cdot \vec{E}$$

$$0 = \vec{\nabla} \cdot \vec{J} + \epsilon_0 \frac{\partial \rho}{\partial t}$$

↪ Local charge conservation

• Poynting's theorem

$$U = U_e + U_m = \int_V d^3x \left(\frac{1}{2} \epsilon_0 \vec{E} \cdot \vec{E} \right) + \int_V d^3x \left(\frac{1}{2\mu_0} \vec{B} \cdot \vec{B} \right)$$

$$\frac{dU}{dt} = \int d^3x \left(\frac{1}{2\epsilon_0} \epsilon_0 \frac{\partial}{\partial t} (\vec{E} \cdot \vec{E}) + \frac{1}{2\mu_0} \frac{\partial}{\partial t} (\vec{B} \cdot \vec{B}) \right)$$

$$= \int d^3x \left(\epsilon_0 \vec{E} \cdot \frac{\partial \vec{E}}{\partial t} + \frac{1}{\mu_0} \vec{B} \cdot \frac{\partial \vec{B}}{\partial t} \right)$$

$$= \int d^3x \left[\frac{1}{\mu_0} \vec{E} \cdot (\vec{\nabla} \times \vec{B}) - \vec{E} \cdot \vec{J} - \frac{1}{\mu_0} \vec{B} \cdot (\vec{\nabla} \times \vec{E}) \right]$$

$$\left(-\vec{\nabla} \cdot (\vec{E} \times \vec{B}) = \vec{E} \cdot (\vec{\nabla} \times \vec{B}) - \vec{B} \cdot (\vec{\nabla} \times \vec{E}) \right)$$

$$= - \int d^3x (\vec{E} \cdot \vec{J}) - \frac{1}{\mu_0} \int \vec{\nabla} \cdot (\vec{E} \times \vec{B}) d^3x$$

$$= - \int d^3x (\vec{E} \cdot \vec{J}) - \frac{1}{\mu_0} \oint (\vec{E} \times \vec{B}) \cdot d\vec{S}$$

Work done on charges

Energy diverging out of surface

$$\left(\begin{aligned} \delta W &= q \vec{E} \cdot \vec{v} \delta t \\ &= \vec{E} \cdot \vec{I} \delta t \\ &\quad \vec{I} \rightarrow \text{Current} \end{aligned} \right)$$

$$\left(\frac{\delta W}{\delta t} = \vec{E} \cdot \vec{J} \right)$$

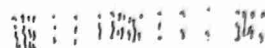
$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B})$$

→ Poynting vector.

Physical signif. : Dirⁿ of the energy

Waves

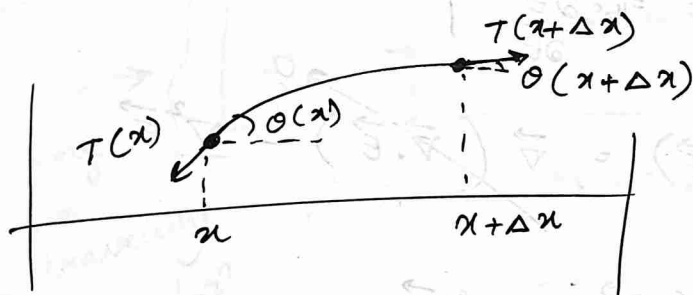
Types of waves : Longitudinal
Transverse.



$u(x, t)$
→ Represents displacement.

$$\frac{\partial^2 u(x, t)}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 u(x, t)}{\partial t^2}$$

→ Can get wave eqⁿ from this



$$T(x) \cos(\theta(x)) = T(x + \Delta x) \cos(\theta(x + \Delta x))$$

$$\cancel{T(x) \sin(\theta(x))} = \cancel{T(x + \Delta x) \sin(\theta(x + \Delta x))}$$

$$\cancel{\left(\frac{\partial u}{\partial x} \right)}$$

$$\frac{\partial^2 u}{\partial t^2} = T(x + \Delta x) \sin(\theta(x + \Delta x)) - T(x) \sin(\theta(x)).$$

When θ is very small,

$$\sin \theta \approx \theta$$

$$\cancel{\left(\frac{\partial u}{\partial x} \right)}$$

Solutions :

$$u = A \sin(kz - \omega t), \quad k = \frac{2\pi}{\lambda}, \quad \omega = \frac{v}{k}$$

Amplitude

In general, amplitudes are complex nos.

~~Imaginary~~ (Imaginary nos. are very REAL then :))

$$u(z, t) = A e^{i(kz - \omega t)}$$

16/4/24

• EM Waves : Free space : $\rho = 0, \quad J = 0$

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\left\{ \begin{array}{l} \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \\ \vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{array} \right.$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{E}) = \vec{\nabla} (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E}$$

$$\vec{\nabla} \times \left(-\frac{\partial \vec{B}}{\partial t} \right) = -\nabla^2 \vec{E}$$

$$-\nabla^2 \vec{E} = \vec{\nabla} \times \left(-\frac{\partial \vec{B}}{\partial t} \right)$$

$$= -\frac{\partial}{\partial t} (\vec{\nabla} \times \vec{B})$$

$$= -\frac{\partial}{\partial t} \left(\frac{\partial \vec{E}}{\partial t} \right) \mu_0 \epsilon_0$$

$$= -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\boxed{\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}}$$

Very similar to wave eqⁿ.

Solve it for some medium

wave eqⁿ $\frac{\partial^2 V}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 V}{\partial t^2}$

$$v = \frac{1}{\sqrt{\mu_0 \epsilon_0}} \approx 3 \times 10^8 \text{ m/s.}$$

The same thing if we do it for \vec{B} , then.

$$\nabla^2 \vec{B} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2}$$

Both electric & magnetic field travel with the speed of light.

We still don't know how \vec{E} & \vec{B} are oriented.

Sol^{ns} :
$$\begin{cases} \vec{E} = \vec{E}_0 e^{i(kz - \omega t)} \\ \vec{B} = \vec{B}_0 e^{i(kz - \omega t)} \end{cases}$$

Assuming the wave is travelling along z-dirⁿ.

\vec{E}_0 & \vec{B}_0 are amplitudes (Const.)

$$k = \frac{2\pi}{\lambda}, \quad \omega = \frac{2\pi}{T}, \quad \omega = kc$$

$$\vec{\nabla} \cdot \vec{E} = 0 \Rightarrow \vec{\nabla} \cdot (\vec{E}_0 e^{i(kz - \omega t)}) = 0$$

$$\frac{\partial}{\partial z} (\vec{E}_0 e^{i(kz - \omega t)}) = 0$$

$$\left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (\vec{E}_0 e^{i(kz - \omega t)}) = 0$$

$$\hat{z} \cdot \vec{E}_0 (ik) = 0 \Rightarrow \vec{E} \text{ is } \perp \text{ to } \hat{z}$$

$$\hat{z} \cdot \vec{E}_0 e^{i(kz - \omega t)} ik = 0.$$

||dy \vec{B} is also \perp to \hat{z} .

→ When an EM wave is propagating, then \vec{E} & \vec{B} are always \perp to direction of propagation

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

Diagram illustrating the curl of the electric field vector \vec{E} . The coordinate system has unit vectors \hat{x} , \hat{y} , and \hat{z} . The partial derivatives are calculated as follows:

$$\frac{\partial}{\partial x} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\frac{\partial}{\partial y} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\frac{\partial}{\partial z} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ E_z \end{pmatrix}$$

The result is a vector pointing in the \hat{y} direction, which is perpendicular to the direction of propagation (\hat{z}).

$$\begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & 0 \end{vmatrix} = \hat{x} \left(- \frac{\partial}{\partial z} (E_y e^{i(kz-\omega t)}) \right) - \hat{y} \left(- \frac{\partial}{\partial z} (E_x e^{i(kz-\omega t)}) \right)$$

$$= - \hat{x} \left(E_y e^{i(kz-\omega t)} \cdot ik \right) + \hat{y} \left(E_x e^{i(kz-\omega t)} \cdot ik \right)$$

$$\begin{aligned} - \frac{\partial \vec{B}}{\partial t} &= - \frac{\partial}{\partial t} \left(\vec{B}_0 e^{i(kz-\omega t)} \right) = - \vec{B}_0 e^{i(kz-\omega t)} \cdot (-i\omega) \\ &= i\omega \left(\hat{x} B_{0x} + \hat{y} B_{0y} \right) e^{i(kz-\omega t)} \end{aligned}$$

$$\Rightarrow \left[-\hat{x}(E_y i k) + \hat{y}(E_x i k) \right] e^{i(kz - \omega t)} = i\omega(\hat{x}B_x + \hat{y}B_y) e^{i(kz - \omega t)}$$

Comparing comp.

$$\Rightarrow -E_y/k = \omega B_x, \quad E_x/k = \omega B_y$$

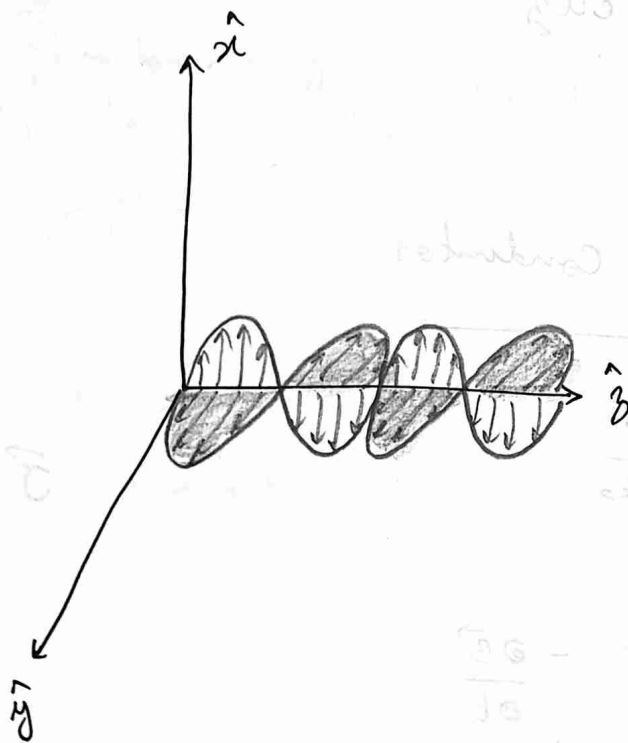
$$\Rightarrow \frac{k}{\omega} = -\frac{B_x}{E_y}, \quad \frac{k}{\omega} = \frac{B_y}{E_x}$$

$$\Rightarrow E_x B_x + E_y B_y = 0.$$

$$\Rightarrow \vec{B}_0 = \frac{k}{\omega} \hat{z} \times \vec{E}_0$$

↳ Tells us that \vec{B} , \hat{z} , \vec{E} are mutually perpendicular.

$$\Rightarrow B_0 = \frac{k}{\omega} E_0 = \frac{E_0}{c}$$



$$\begin{aligned} \vec{E}_0 e^{i(kz - \omega t)} \\ = \vec{E}_0 (\cos(kz - \omega t) \\ + i \sin(kz - \omega t)) \end{aligned}$$

→ If a phase is added $\vec{E}_0 e^{i(kz - \omega t + \delta)}$
 then \vec{E} & \vec{B} won't be in phase.
 There'll be a phase difference.

$$\text{Energy} = \frac{1}{2} \epsilon_0 E^2 + \frac{1}{2\mu_0} B^2$$

$$= \epsilon_0 E^2 \cos^2(kz - \omega t)$$

→ Density

Total energy = avg. over time

$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B})$$

After a lot of math //

$$= cu \hat{z}$$

→ Energy is carried with speed of light along \hat{z} .

EM wave in conductor

$$\vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{J} = \sigma \vec{E}$$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

→ local charge cons.

$$\vec{J} = \sigma \vec{E} \Rightarrow \sigma \vec{\nabla} \cdot \vec{E} = -\frac{\partial \rho}{\partial t}$$

$$\Rightarrow \sigma \left(\frac{\rho}{\epsilon_0} \right) = -\frac{\partial \rho}{\partial t}$$

$$\Rightarrow -\frac{\sigma}{\epsilon_0} t = \ln \rho$$

$$\Rightarrow \rho(t) = \rho_0 e^{-\sigma/\epsilon_0 t}$$

Conductors, $\sigma \rightarrow$ very large.

$$\rho(t) \approx 0$$

⇒ Even if we start with free charges, ~~& so~~ the free charges spread out on the boundary of the conductor.

So we don't have to worry about the free charges inside the conductor.

Eq^{ns} 2

$$\nabla^2 \vec{E} = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2} + \mu \sigma \frac{\partial \vec{E}}{\partial t}$$

Similar to damped oscillation.

So the amplitude keeps on decreasing.