

Vibrations of a linear triatomic molecule:

Here we are describing the linear triatomic molecule, you should go through other problems with two degrees of freedom, you may refer section-9.5 of J.C. Upadhyay's Classical Mechanics where two coupled pendulum has been solved fully.

Let us consider a linear triatomic molecule of the type AB_2 (e.g. CO_2) in which A atom is in the middle and B atom are at the ends [See figure below]. The mass of A atom is M and that of each of the B atom is m . The interatomic force between A and B atom is approximated by elastic force of spring force constant k . The motion of the three atoms is constrained along the line joining them. There are three coordinates marking the positions of three atoms on the line. If x_1, x_2 and x_3 are the positions of the three atoms at any instant from some arbitrary origin, then

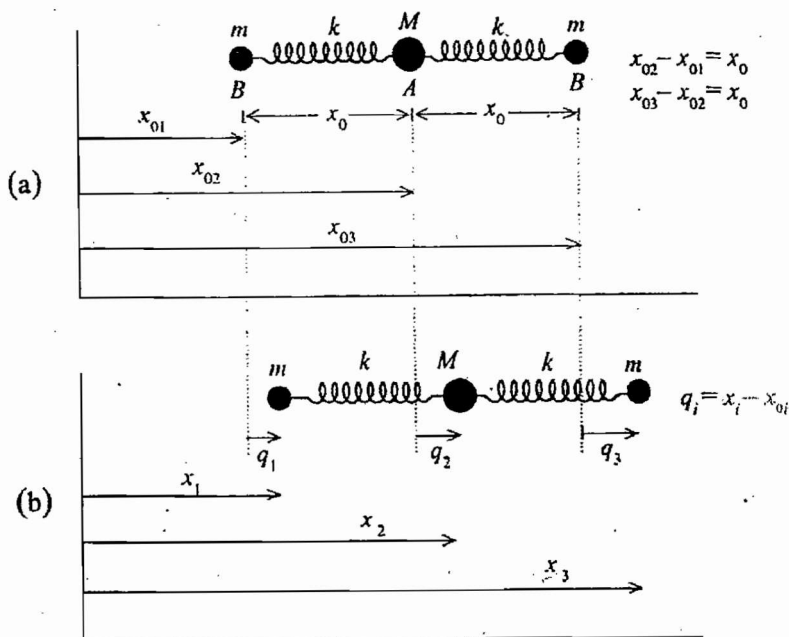


Figure: Longitudinal oscillations of a linear symmetric triatomic molecule
(a) Equilibrium configuration, (b) Configuration at any instant t .

Note that q 's are same as η 's used in our derivation, also note that q_i can be positive or negative depending on x_i .

where,

$$x_{02} - x_{01} = x_{03} - x_{02} = x_0$$

Then,

$$T = \frac{1}{2} m (\dot{q}_1^2 + \dot{q}_3^2) + \frac{1}{2} M \dot{q}_2^2 = \frac{1}{2} \begin{pmatrix} \dot{q}_1 & \dot{q}_2 & \dot{q}_3 \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \dot{q}_3 \end{pmatrix}$$

and
$$V = \frac{1}{2} k (q_2 - q_1)^2 + \frac{1}{2} k (q_3 - q_2)^2$$

We can visualize it as follows:

The change in length of spring on the left part is $(q_2 - q_1)$ and on the right part it is $(q_3 - q_2)$. So, the potential energy $V = \frac{1}{2} k (\text{change in length on right part})^2 + \frac{1}{2} k (\text{change in length on left part})^2$.

Now,
$$V = \frac{1}{2}k(q_1^2 + q_2^2 - 2q_1q_2 + q_2^2 + q_3^2 - 2q_2q_3)$$

We can write the V matrix by inspection only because

$$\begin{aligned} V &= \frac{1}{2}V_{ij}\eta_i\eta_j \equiv \sum_{i=1}^3 \sum_{j=1}^3 \frac{1}{2}V_{ij}q_iq_j \\ &= \frac{1}{2}(V_{11}q_1^2 + V_{12}q_1q_2 + V_{13}q_1q_3 + V_{21}q_2q_1 + V_{22}q_2^2 + V_{23}q_2q_3 + V_{31}q_3q_1 + V_{32}q_3q_2 + V_{33}q_3^2) \\ &= \frac{1}{2}(V_{11}q_1^2 + 2V_{12}q_1q_2 + 2V_{13}q_1q_3 + V_{22}q_2^2 + 2V_{23}q_2q_3 + V_{33}q_3^2) \end{aligned}$$

because $V_{ij} = V_{ji}$.

Comparing above expression with our potential energy $\frac{1}{2}k(q_1^2 - 2q_1q_2 + 0 + 2q_2^2 - 2q_2q_3 + q_3^2)$

We get, $V_{11} = V_{33} = k$, $V_{22} = 2k$, $V_{12} = V_{21} = V_{23} = V_{32} = -k$ and $V_{13} = V_{31} = 0$

So,
$$V = \begin{pmatrix} V_{11} & V_{12} & V_{13} \\ V_{21} & V_{22} & V_{23} \\ V_{31} & V_{32} & V_{33} \end{pmatrix} = \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix}$$

Also, note that $\left(\frac{\partial^2 V}{\partial q_1^2}\right)_{q_1=0} = k = V_{11}$, $\left(\frac{\partial^2 V}{\partial q_2^2}\right)_{q_2=0} = 2k = V_{22}$, $\left(\frac{\partial^2 V}{\partial q_3^2}\right)_{q_3=0} = k = V_{33}$

$\left(\frac{\partial^2 V}{\partial q_1 q_2}\right)_{q_1=0, q_2=0} = -k = V_{12} = V_{21}$, $\left(\frac{\partial^2 V}{\partial q_1 q_3}\right)_{q_1=0, q_3=0} = 0 = V_{13} = V_{31}$

and $\left(\frac{\partial^2 V}{\partial q_2 q_3}\right)_{q_2=0, q_3=0} = -k = V_{23} = V_{32}$

Thus the T and V matrices are

$$T = \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \text{ and } V = \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix} \quad \dots (11.23)$$

The secular equation is

$$|\mathbf{V} - \omega^2 \mathbf{T}| = \begin{vmatrix} k - m\omega^2 & -k & 0 \\ -k & 2k - M\omega^2 & -k \\ 0 & -k & k - m\omega^2 \end{vmatrix} = 0 \quad \dots (11.24)$$

Applying the operation, $R_1 \rightarrow R_1 - R_3$

We have,
$$\begin{vmatrix} k - m\omega^2 & 0 & -(k - m\omega^2) \\ -k & 2k - M\omega^2 & -k \\ 0 & -k & k - m\omega^2 \end{vmatrix} = 0$$



Again applying, $C_3 \rightarrow C_3 + C_1$

$$\begin{vmatrix} k - m\omega^2 & 0 & 0 \\ -k & 2k - M\omega^2 & -2k \\ 0 & -k & k - m\omega^2 \end{vmatrix} = 0$$

$$\Rightarrow (k - m\omega^2)[(2k - M\omega^2)(k - m\omega^2) - 2k^2] = 0$$

$$\Rightarrow (k - m\omega^2)(2k^2 - 2km\omega^2 - M\omega^2k + mM\omega^4 - 2k^2) = 0$$

$$\Rightarrow (k - m\omega^2)[-2km\omega^2 - M\omega^2k + mM\omega^4] = 0$$

$$\Rightarrow \omega^2(k - m\omega^2)[mM\omega^2 - k(2m + M)] = 0$$

$$\text{We get } \omega_1 = 0, \omega_2 = \sqrt{\frac{k}{m}} \text{ and } \omega_3 = \sqrt{\frac{k}{m}\left(1 + \frac{2m}{M}\right)} \quad \dots (11.25)$$

The first eigenvalue $\omega_1 = 0$ corresponds to non-oscillatory motion and refers to translatory motion of the molecule as a whole rigidly.

To determine the eigenvectors, we use the equation

$$(\mathbf{V} - \omega_k^2 \mathbf{T}) \mathbf{a}_k = 0 \quad \text{or} \quad \begin{pmatrix} k - m\omega_k^2 & k & 0 \\ -k & 2k - M\omega_k^2 & -k \\ 0 & -k & k - m\omega_k^2 \end{pmatrix} \begin{pmatrix} a_{1k} \\ a_{2k} \\ a_{3k} \end{pmatrix} = 0$$

Let us now discuss the eigen vectors for the three modes of vibrations.

(1) For $\omega_1 = 0$,

$$\begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix} \begin{pmatrix} a_{11} \\ a_{21} \\ a_{31} \end{pmatrix} = 0$$

$$\text{Or, } a_{11} - a_{21} = 0, -a_{11} + 2a_{21} - a_{31} = 0, -a_{21} + a_{31} = 0$$

$$\text{Or, } a_{11} = a_{21} = a_{31} = \alpha \text{ (say)}$$

Thus for $\omega_1 = 0$, the eigen vector is given by

$$\mathbf{a}_1 = \begin{pmatrix} \alpha \\ \alpha \\ \alpha \end{pmatrix}$$

(2) For $\omega_2 = \sqrt{k/m}$,

$$\begin{pmatrix} 0 & -k & 0 \\ -k & 2k - \frac{Mk}{m} & -k \\ 0 & -k & 0 \end{pmatrix} \begin{pmatrix} a_{12} \\ a_{22} \\ a_{32} \end{pmatrix} = 0$$

Or, $a_{22} = 0, -a_{12} - a_{32} = 0$

Therefore, $a_{22} = 0, a_{12} = -a_{32} = \beta$ (say)

Thus, for $\omega_2 = \sqrt{k/m}$, $\mathbf{a}_2 = \begin{pmatrix} \beta \\ 0 \\ -\beta \end{pmatrix}$

(3) For $\omega_3 = \sqrt{\frac{k}{m} \left(1 + \frac{2m}{M}\right)}$, $\begin{pmatrix} -\frac{2mk}{M} & -k & 0 \\ -k & -\frac{kM}{m} & -k \\ 0 & -k & -\frac{2mk}{M} \end{pmatrix} \begin{pmatrix} a_{13} \\ a_{23} \\ a_{33} \end{pmatrix} = 0$

which gives, $\frac{2m}{M}a_{13} + a_{23} = 0, a_{13} + \frac{M}{m}a_{23} + a_{33} = 0, a_{23} + \frac{2m}{M}a_{33} = 0$

Therefore, $a_{13} = a_{33} = \gamma$ (say) and $a_{23} = -(2m/M)\gamma$

Thus for, $\omega_3 = \sqrt{\frac{k}{m} \left(1 + \frac{2m}{M}\right)}$, $\mathbf{a}_3 = \begin{pmatrix} \gamma \\ -(2m/M)\gamma \\ \gamma \end{pmatrix}$

Now, the \mathbf{A} matrix is

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} \alpha & \beta & \gamma \\ \alpha & 0 & -\frac{2m}{M}\gamma \\ \alpha & -\beta & \gamma \end{bmatrix}$$

Now, we have to determine α, β and γ

We impose the condition, Given in equation (9.18)

$$\bar{\mathbf{A}}\mathbf{T}\mathbf{A} = \mathbf{I}$$

i.e. $\begin{pmatrix} \alpha & \alpha & \alpha \\ \beta & 0 & -\beta \\ \gamma & -\frac{2m}{M}\gamma & \gamma \end{pmatrix} \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \begin{pmatrix} \alpha & \beta & \gamma \\ \alpha & 0 & -\frac{2m}{M}\gamma \\ \alpha & -\beta & \gamma \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

$\Rightarrow \begin{pmatrix} \alpha & \alpha & \alpha \\ \beta & 0 & -\beta \\ \gamma & -\frac{2m}{M}\gamma & \gamma \end{pmatrix} \begin{bmatrix} m\alpha & m\beta & m\gamma \\ M\alpha & 0 & -2m\gamma \\ m\alpha & -m\beta & m\gamma \end{bmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Or,

$$\begin{pmatrix} \alpha^2(2m+M) & 0 & 0 & 0 & 0 \\ 0 & 2\beta^2 m & 0 & 1 & 0 \\ 0 & 0 & 2\gamma^2 m & 0 & 1 \end{pmatrix}$$

Thus,

$$\alpha = \frac{1}{\sqrt{2m+M}}, \quad \beta = \frac{1}{\sqrt{2m}}, \quad \gamma = \frac{1}{\sqrt{m}}$$

Hence the eigen vectors are

$$\mathbf{a}_1 = \frac{1}{\sqrt{2m+M}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{a}_2 = \frac{1}{\sqrt{2m}} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{a}_3 = \frac{1}{\sqrt{2m}} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

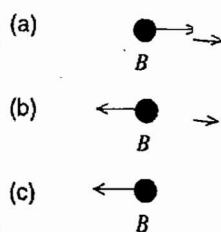


Figure: Longitudinal normal modes of a triatomic molecule

- (a) Mode 1, all the three atoms are displaced equally in the same direction.
 (b) Mode 2, A atom does not vibrate and B atoms oscillate with equal amplitudes in opposite directions.
 (c) B atoms vibrate in phase with equal amplitudes and the middle atom vibrates in opposite phase with different amplitude.

Thus, in case (1), $a_{11} = a_{21} = a_{31}$ means that the displacements of all atoms are the same in the same direction (see in figure below). This is what expected from translation.

In case (2), $a_{22} = 0$, and $a_{12} = -a_{32}$ implies that the middle atom does not vibrate and the end atoms (B) oscillate with equal amplitudes but in opposite phase.

$$a_{13} = a_{33} = \gamma \text{ and } a_{23} = -\left(\frac{2m}{M}\right)\gamma$$

show that end atoms oscillate in phase with equal amplitude and the central atom vibrates in opposite phase with different amplitude.

The generalized coordinates q_1, q_2 and q_3 are related to the normal coordinates Q_1, Q_2 and Q_3 by the relation

$$q_i = a_{ik} Q_k \quad \text{where summation over } k$$

i.e. $q_1 = q_{11}Q_1 + q_{12}Q_2 + q_{13}Q_3$, $q_2 = q_{21}Q_1 + q_{22}Q_2 + q_{23}Q_3$ and $q_3 = q_{31}Q_1 + q_{32}Q_2 + q_{33}Q_3$

Therefore,

$$\begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix} = \begin{pmatrix} \alpha & \beta & \gamma \\ \beta & 0 & -\frac{2m}{M}\gamma \\ \gamma & -\beta & \gamma \end{pmatrix} \begin{pmatrix} Q_1 \\ Q_2 \\ Q_3 \end{pmatrix}$$

Further the normal coordinate Q_1 oscillates with frequency $\omega_1 = 0$, Q_2 with $\omega_2 = \sqrt{\frac{k}{m}}$ and Q_3 with

$$\omega_3 = \sqrt{\frac{k}{m} \left(1 + \frac{2m}{M} \right)}. \text{ So}$$

$$Q_1 = f_1 \cos(\omega_1 t + \phi_1), \quad Q_2 = f_2 \cos(\omega_2 t + \phi_2) \text{ and}$$

$$Q_3 = f_3 \cos(\omega_3 t + \phi_3)$$

where f_1, f_2 and f_3 are the amplitudes of the normal coordinates (Q 's) and ϕ_1, ϕ_2 and ϕ_3 are the phase factors of Q 's.

$$\text{Thus,} \quad q_1 = \alpha f_1 \cos(\omega_1 t + \phi_1) + \beta f_2 \cos(\omega_2 t + \phi_2) + \gamma f_3 \cos(\omega_3 t + \phi_3)$$

$$\text{Since,} \quad x_1 = q_1 + x_{01}$$

$$\text{So,} \quad x_1 = A' \cos(\omega_1 t + \phi_1) + B \cos(\omega_2 t + \phi_2) + C \cos(\omega_3 t + \phi_3) + x_{01}$$

But $\omega_1 = 0$, therefore,

$$x_1 = A' + B \cos(\omega_2 t + \phi_2) + C \cos(\omega_3 t + \phi_3) + x_{01}$$

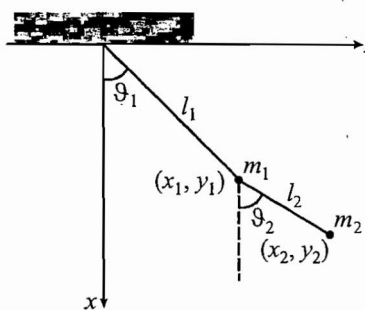
$$\text{Similarly,} \quad x_2 = \alpha Q_1 + 0 - \frac{2m}{M} \gamma Q_3 = A' - \frac{2m}{M} C \cos(\omega_3 t + \phi_3) + x_{02} \quad (\because \gamma f_3 = C)$$

$$\text{and} \quad x_3 = \alpha Q_1 - \beta Q_2 + \gamma Q_3 = A' - B \cos(\omega_2 t + \phi_2) + C \cos(\omega_3 t + \phi_3) + x_{03}$$

where A' represents a constant corresponding to rigid translation and as stated in the beginning x_{0i} is the equilibrium position of an atom.

Double pendulum

Determine the normal vibrations and frequencies.



Coordinates of the double pendulum

The Lagrangian is

$$L = T - V = \frac{1}{2} m_1 l_1^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 [l_1^2 \dot{\theta}_1^2 + l_2^2 \dot{\theta}_2^2 + 2l_1 l_2 \dot{\theta}_1 \dot{\theta}_2 \cos(\theta_1 - \theta_2)] \\ - m_1 g [l_1 + l_2 - l_1 \cos \theta_1] - m_2 g [l_1 + l_2 - (l_1 \cos \theta_1 + l_2 \cos \theta_2)].$$

The Lagrange equations with θ_1 and θ_2 read

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}_1} \right) - \frac{\partial L}{\partial \theta_1} = 0, \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}_2} \right) - \frac{\partial L}{\partial \theta_2} = 0.$$

One has