

Regression

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Office hours: W 1030-1130, SL-210

Previously:

Linear Regression

Matrix-vector notation

Today:

1. Linear regression: validation, regularization
2. Nonlinear regression

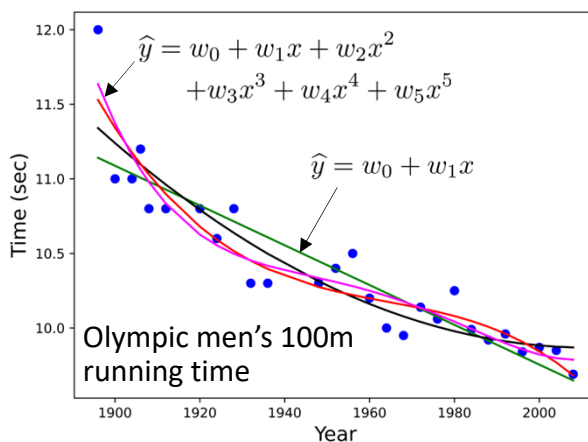
HW due:

August 16, 2024

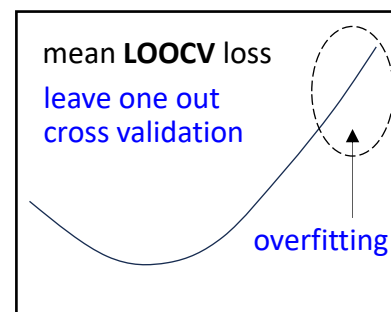
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Validation for hypothesis selection



Calculating R^2 (or similar parameters) are necessary but not enough



degree of polynomial

LOOCV: $n-1$ data are used for training, 1 for test; calculated n times changing the test data and the losses are averaged; hypothesis with minimum loss is selected

For large number of data, K-fold cross validation is used

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Overfitting is the outcome of noise creeping into the signal
difficult to avoid with noisy data

Regularization is a procedure to control overfitting

consider fitting a linear hypothesis: $\hat{y} = \mathbf{x}^T \mathbf{w}$

In **regularized regression**, we define a cost function $E = \underbrace{\frac{1}{n} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y})}_{\text{penalty term}} + \lambda \mathbf{w}^T \mathbf{w}$

λ : penalty parameter

$\lambda \rightarrow 0$: classical least square regression

$\lambda \rightarrow \infty$: $\hat{y} \rightarrow 0$

Ridge regression (Tikonov regularization)

minimization of E requires

$$\nabla E(\mathbf{w}) = \mathbf{0} \Rightarrow (\mathbf{X}^T \mathbf{X} + n\lambda \mathbf{I}) \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

Thus regularization tends to reduce the model complexity by reducing \mathbf{w}

Optimum value of λ is decided based on cross-validation

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consider fitting the linear hypothesis:

$$\hat{y} = w_0 + w_1 x + w_2 x^2 + w_3 x^3 + w_4 x^4 + w_5 x^5$$

$$E = \frac{1}{n} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y}) + \lambda \mathbf{w}^T \mathbf{w}$$

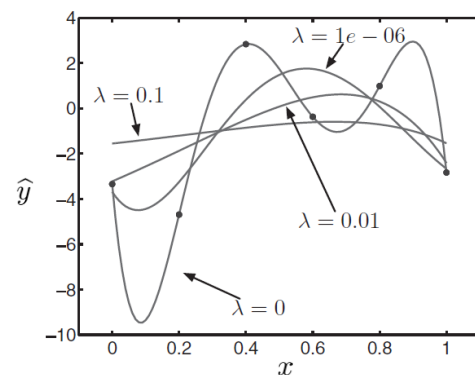
$$\Rightarrow (\mathbf{X}^T \mathbf{X} + n\lambda \mathbf{I}) \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

Other forms of regularization

Lasso regression:

$$E = \frac{1}{n} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y}) + \lambda \|\mathbf{w}\|_1 \quad \|\mathbf{w}\|_1 = \sum |w|$$

$$\text{Elastic net regression: } E = \frac{1}{n} (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y}) + \lambda [\alpha \|\mathbf{w}\|_1 + (1 - \alpha) \mathbf{w}^T \mathbf{w}]$$



increasing λ reduces fluctuations

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Susceptibility to **Outlier**

least square fit, due to squaring of residual, is heavily influenced by outliers

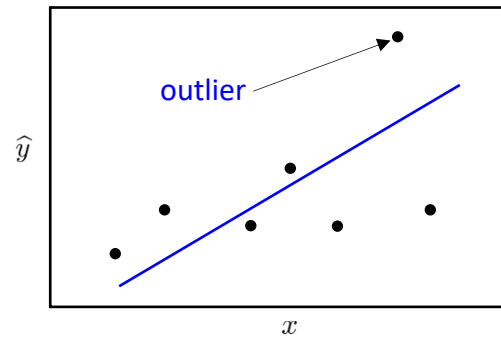
Least absolute deviation fit is often used to reduce the dependence on outlier

$$E = \frac{1}{n} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|_1$$

Least absolute deviation has zero double derivative, precludes use of some optimization algorithms

In most cases, **Least absolute deviation** reduces cost function to a lower value than that of the least square regression

Outlier may also be removed based on appropriate criterion of loss function



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Nonlinear regression: normal equations are **nonlinear**

Linear regression: $\hat{y} = \mathbf{x}^T \mathbf{w}$ $\hat{y}_i = \mathbf{x}_i^T \mathbf{w}$ $i = 1, 2, \dots, n$

In general, $\hat{y} = f(\mathbf{x}, \mathbf{w})$ $\hat{y}_i = f(\mathbf{x}_i, \mathbf{w})$

Cost function $E(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n [f(\mathbf{x}_i, \mathbf{w}) - y_i]^2$

$$\frac{\partial E}{\partial \mathbf{w}} = 0 \Rightarrow \sum_{i=1}^n [f(\mathbf{x}_i, \mathbf{w}) - y_i] \frac{\partial f(\mathbf{x}_i, \mathbf{w})}{\partial w_j} = 0 \quad j = 0, 1, 2, \dots, k$$

$$\Rightarrow \sum_{i=1}^n [f(\mathbf{x}_i, \mathbf{w}) - y_i] \nabla f(\mathbf{x}_i, \mathbf{w}) = 0 \quad \text{Normal equations; solves } \mathbf{w}$$

$$\mathbf{x}^T = [1 \quad x_1 \quad x_2 \quad \dots \quad x_k]$$

$$\mathbf{x}_i^T = [1 \quad x_{i1} \quad x_{i2} \quad \dots \quad x_{ik}]$$

$$\mathbf{w}^T = [w_0 \quad w_1 \quad w_2 \quad \dots \quad w_k]$$

We wish to find

$$\arg \min_{\mathbf{w}} E(\mathbf{w})$$

In **nonlinear regression**, normal equations are **nonlinear**

- **direct minimization of** $E(\mathbf{w})$
- solving nonlinear normal equations using suitable numerical methods
- **linearization**

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Example: Given a set of discrete data points $\mathcal{T} = \{(x_i, y_i)\}_{i=1}^n$

We wish to fit $\hat{y} = w_0 x^{w_1}$

Cost function: $E(w_0, w_1) = \frac{1}{n} \sum_{i=1}^n (y_i - w_0 x_i^{w_1})^2$

$$\frac{\partial E}{\partial w_0} = 0 = -\frac{2}{n} \sum_{i=1}^n (y_i - w_0 x_i^{w_1}) x_i^{w_1} \quad \frac{\partial E}{\partial w_1} = 0 = -\frac{2}{n} \sum_{i=1}^n (y_i - w_0 x_i^{w_1}) w_0 \ln(x_i) x_i^{w_1}$$

We can calculate w_0, w_1 by solving the **normal** equations

$$\begin{aligned} \sum_{i=1}^n (y_i - w_0 x_i^{w_1}) x_i^{w_1} &= 0 \\ \sum_{i=1}^n (y_i - w_0 x_i^{w_1}) w_0 \ln(x_i) x_i^{w_1} &= 0 \end{aligned}$$

← the normal equations are nonlinear

One approach to avoid nonlinearity:

modifying $\hat{y} = w_0 x^{w_1}$

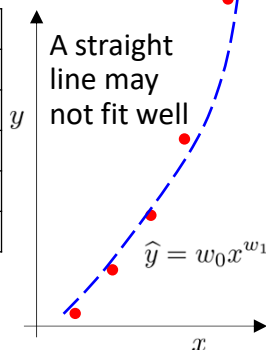
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Example: linearization

Let's consider this **dataset**

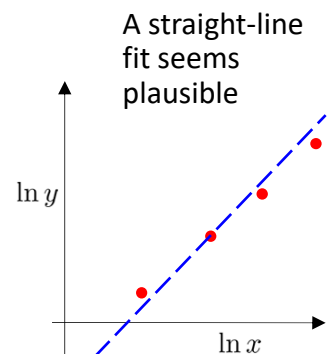
x	y
1	0.4
2	1.7
3	3
4	5.5
5	8.4



Linearization

Transforming

$\ln x$	$\ln y$
0	-0.916
0.693	0.531
1.099	1.099
1.386	1.705
1.609	2.128



We are trying to fit $\hat{y} = w_0 x^{w_1} \Rightarrow \ln \hat{y} = \ln(w_0) + w_1 \ln x$

Simple linear regression seems now applicable

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Limitations of linearization

Use of a hypothesis $\hat{y} = f(x)$ assumes existence of a model $y = g(x)$

such that the experiments (observations) generate $y_i = g(x = x_i) + \epsilon_i$

use of least square regression facilitates $f(x) \rightarrow g(x)$ with more training data

Linearization tacitly assumes multiplicative noise $y_i = \epsilon_i \theta_0 x^{\theta_1}$

If the noise is additive $y_i = \theta_0 x^{\theta_1} + \epsilon_i$ linearization may not be [acceptable](#)

[Linearization is not possible](#) for all nonlinear models

For instance, a model $y \approx \theta_0 + \theta_1 x^{\theta_2} + \theta_3 x^{\theta_4}$

cannot be linearized using the procedure discussed