

# Feiyang Wu

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## EDUCATION

**Harvard University, Cambridge, MA** Sep 2025 – May 2027  
*M.S. in Computational Science and Engineering from Harvard University — expected May 2027*

**University of Illinois Urbana-Champaign, Champaign, IL** Sep 2021 – Jun 2025  
*B.S. in Computer Engineering from UIUC, graduated with High Honors — GPA: 3.98/4.00*

## SKILLS

**Programming:** C, Python, C++, MySQL, CUDA, x86, MongoDB, HTML, CSS, Node.js, Javascript, Verilog  
**Framework:** Pytorch, Tensorflow, JAX, ROS2, TensorRT, Hugo, Drake, Mujoco, YOLO  
**Tools:** Git, Docker, Linux, Wandb, Netlify, Huggingface, STM32, Xilinx Spartan 7, Jetson Nano  
**Knowledge Base:** LLM, VLA, Generative Models, Control Theory, Reinforcement Learning

## WORKING EXPERIENCE

**LimX Dynamics** July 2025 – Aug 2025  
*Machine Learning Engineer Intern for Manipulation* Beijing, China

- Studied **Large Language Models**(LLM) and its application in **Vision Language Action**(VLA) models;
- Collaborated to build code base that contains several VLA models including **OpenVLA** and  $\pi_0$ ;
- Transplanted and merged original source code from **OpenVLA** and **OpenVLA-OFT** into the new codebase;
- Conducted training, finetuning and evaluation on **LIBERO** dataset to test the validity of the code base.

## RESEARCH EXPERIENCE

**Project Leader, Diffusion Policy with Joint Torque Modality** Nov 2024 – May 2025  
*Physical Intelligence Lab, ZJU-UIUC Institute*

- Studied **Diffusion Policy** and built **teleoperation** and evaluation pipeline to run it on **ARX** robotic arm;
- Incorprated joint torque modality and analyzed its impact on pick-and-place, wiping and flipping tasks.

**Project Leader, Research on Multiplexed Spiking Neural Network** Jun 2024 – Aug 2024

- Conducted research on algorithms related to **LIF** (Leaky-Integrate and Fire) in **Spiking Neural Networks**;
- Modified **STBP** (Spatio-Temporal Backpropagation) algorithm based on **SNN** backpropagation to propose a novel method to multiplex and demultiplex two channels of signals and evaluated on **MNIST** dataset.

## PROJECTS

**Dodge Ball Launcher** 📄 Spring 2025

- Designed a dodge ball launching system that is able to interact with human players and launch dodge ball;
- Implemented low level real-time drivers for motor hardware and **YOLO** based human tracking system;
- Built the system on **ros2-control**, deployed and optimized **YOLO** with **TensorRT** on **Jetson**.

**Xilinx Spartan-7 FPGA Based Plants vs. Zombie** 📄 Spring 2024

- Implemented VGA screen display peripheral using **Xilinx FPGA** development board and **System Verilog**;
- Designed an naive version of game Plants vs. Zombies, which included four types of plants and one type of zombie, a sunshine collection system, and a PWM sound system optimized on **Microblaze**.

**RazelOS, a Unix-Like Operating System** 📄 Fall 2023

- Developed a kernel for a toy operating system called RazelOS using **x86** assembly and **C** language;
- Added **paging** mechanism, file system, signaling, **round-robin** process scheduling, **interrupt handling**, iterative terminal, user and kernel program, and many other inspiring features.

## PUBLICATION

Song, E., Chai, W., Wang, G., Zhang, Y., Zhou, H., Wu, F., Chi, H., Guo, X., Ye, T., Zhang, Y., Lu, Y., Hwang, J.-N., & Wang, G. *MovieChat: From Dense Token to Sparse Memory for Long Video Understanding*. (CVPR 2024)  
 ArXiv.org. <https://doi.org/10.48550/arXiv.2307.16449> 📄