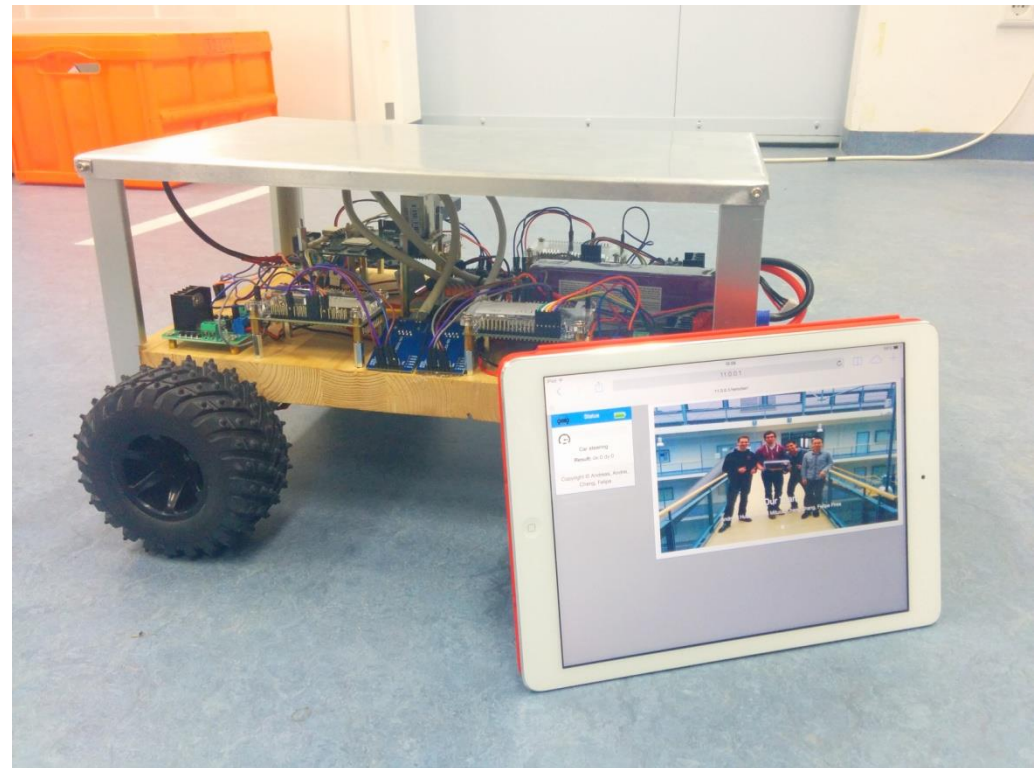




# Hardware/Software Co-Design with a LEGO car

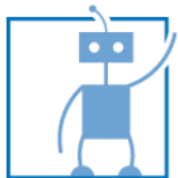
- Andreas Huber
- Andrei Mituca
- 张程 (Cheng Zhang)
- Felipe Pires



# General Topics

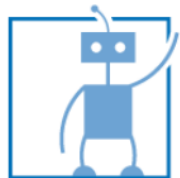
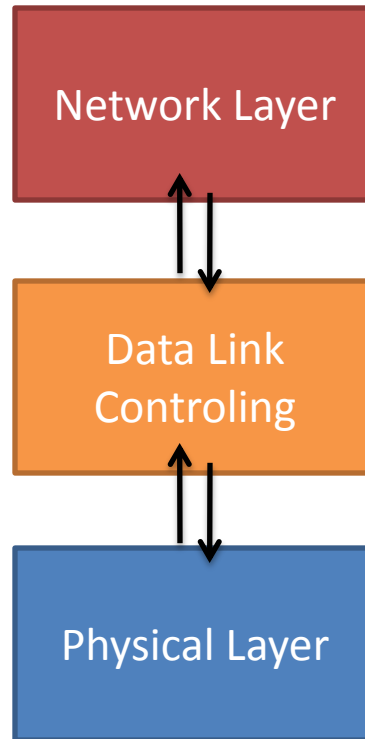
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- Hardware
  - Data Flow
  - Power Supply
  - Overview
- Software
  - FPGA
  - IMX6
  - Client interface
- Future steps

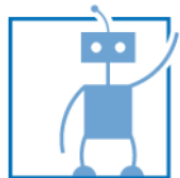
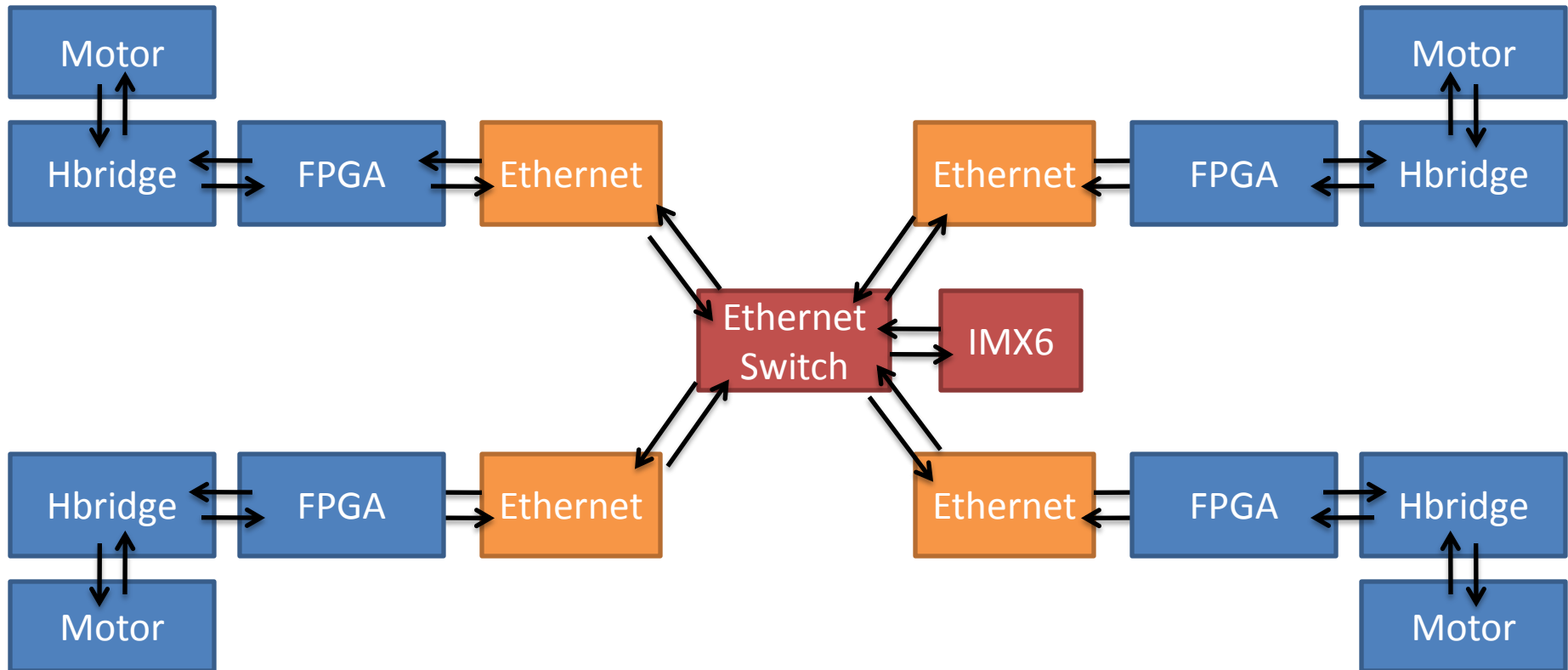


# Hardware - Overview

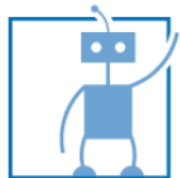
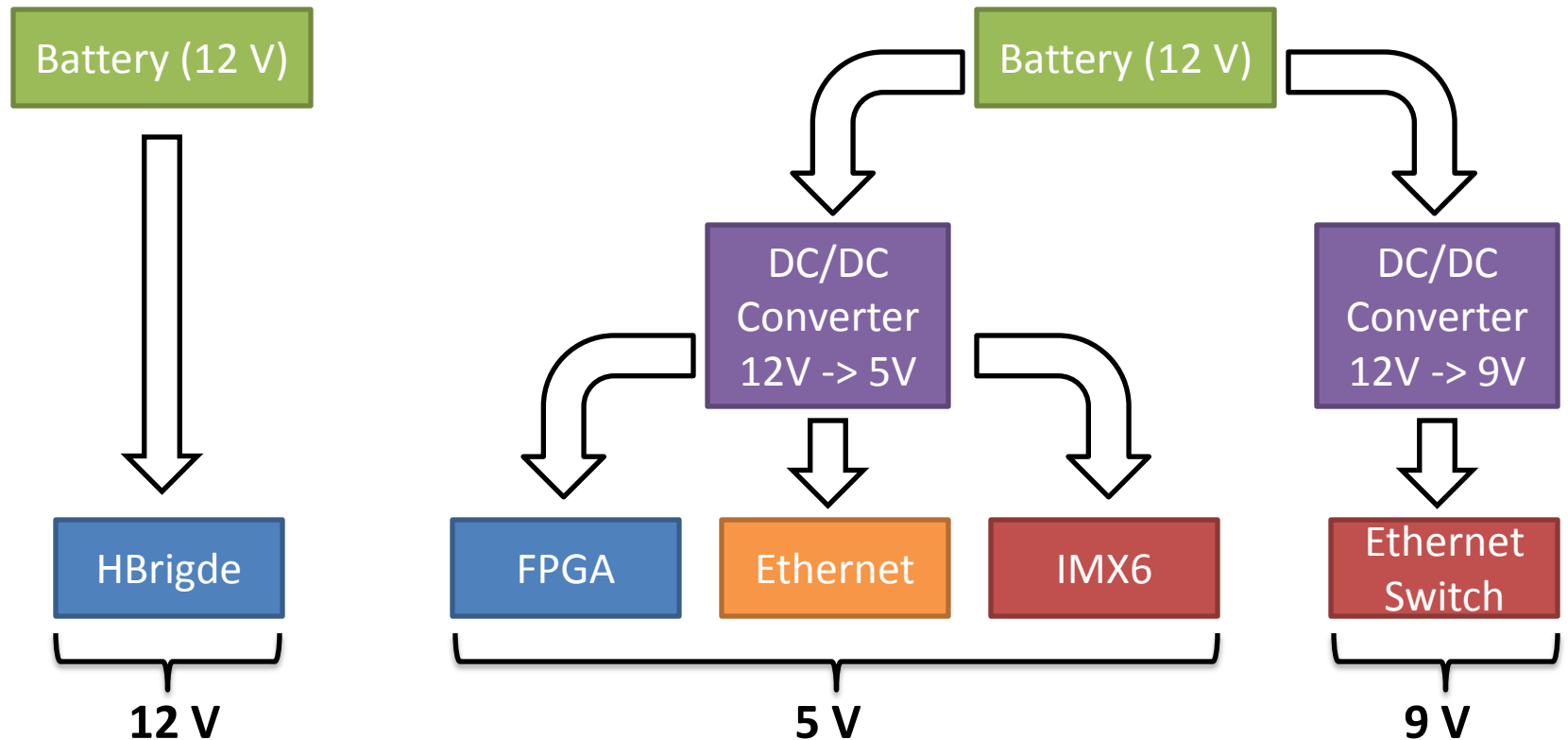
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# Hardware – Data flow

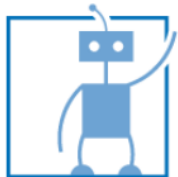
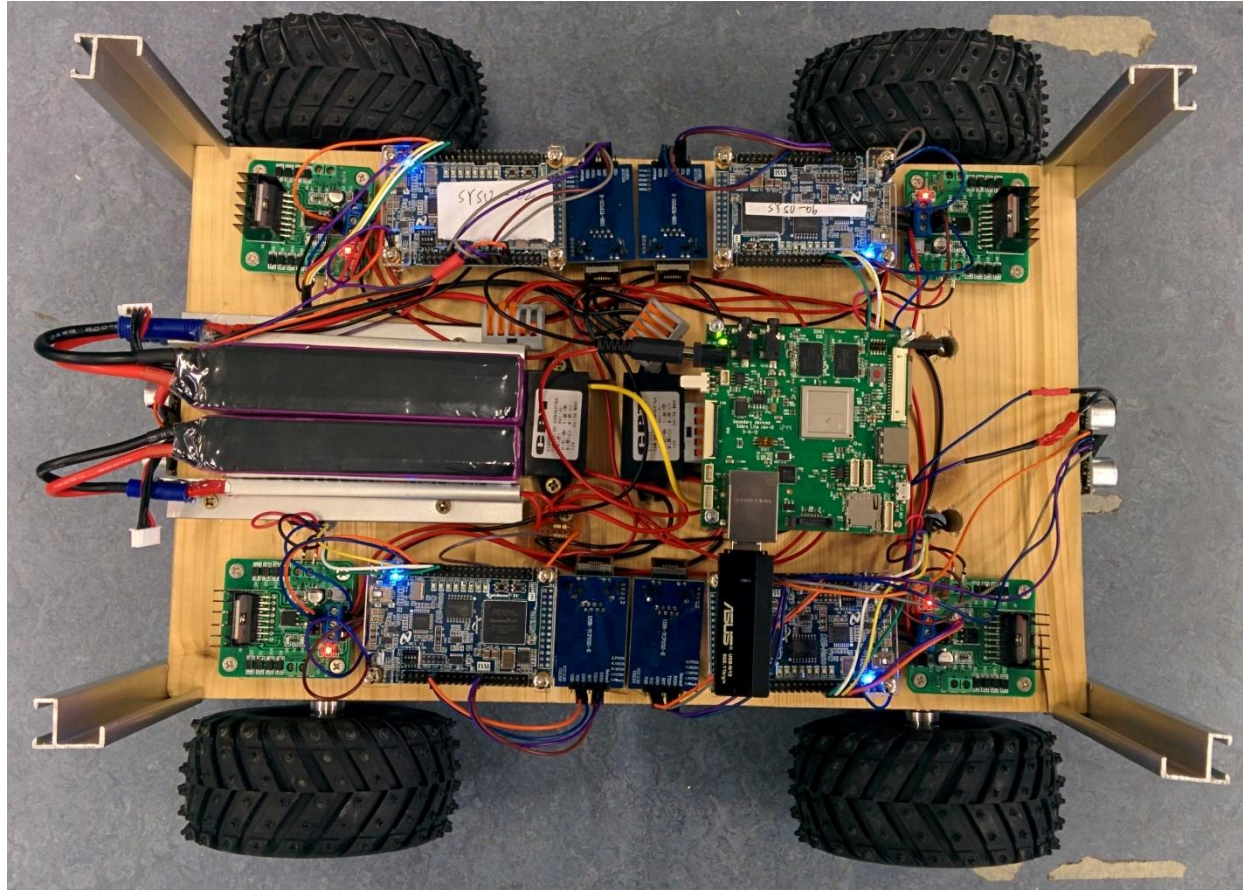


# Hardware – Power supply



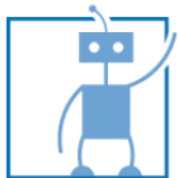
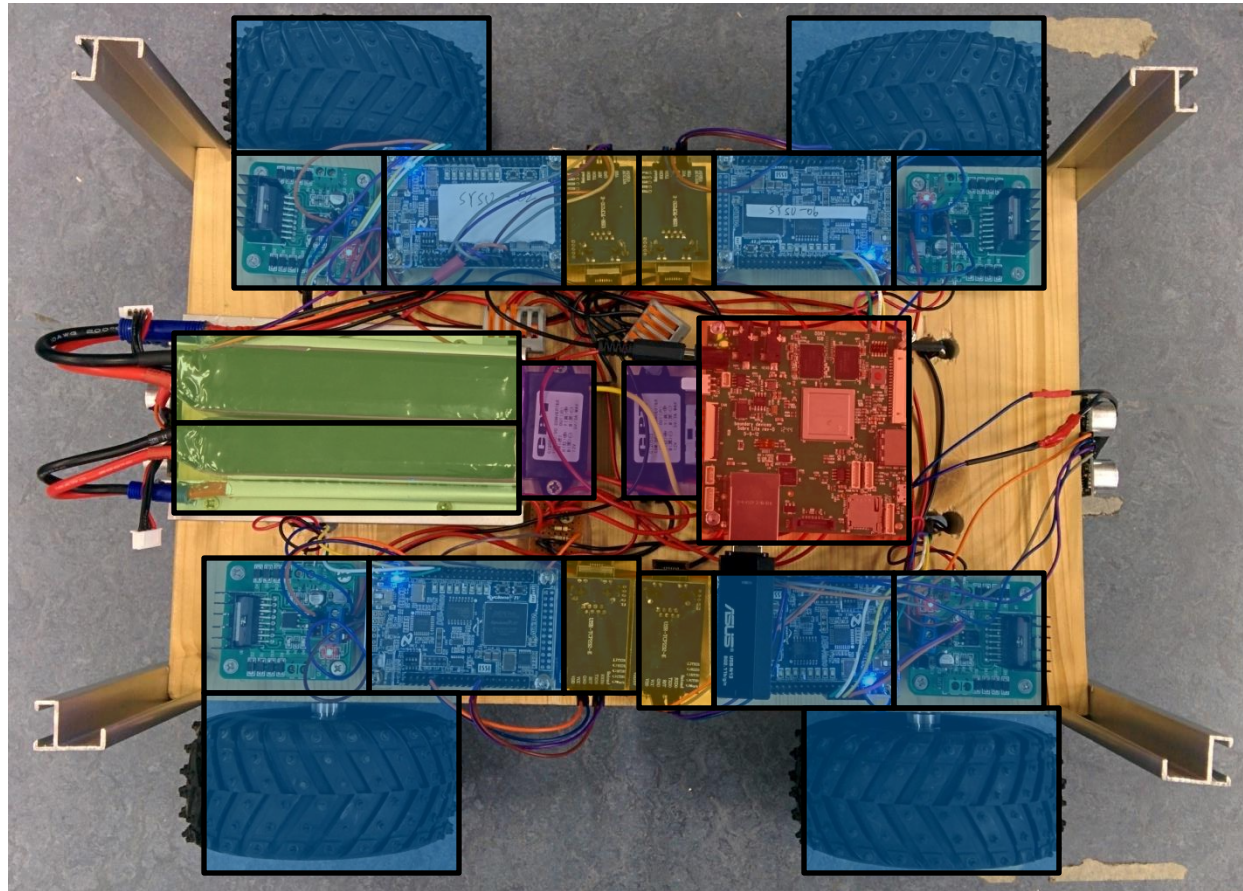
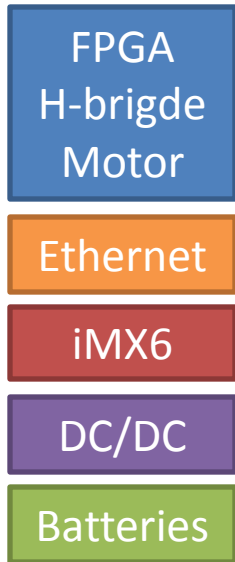
# Hardware – Overview

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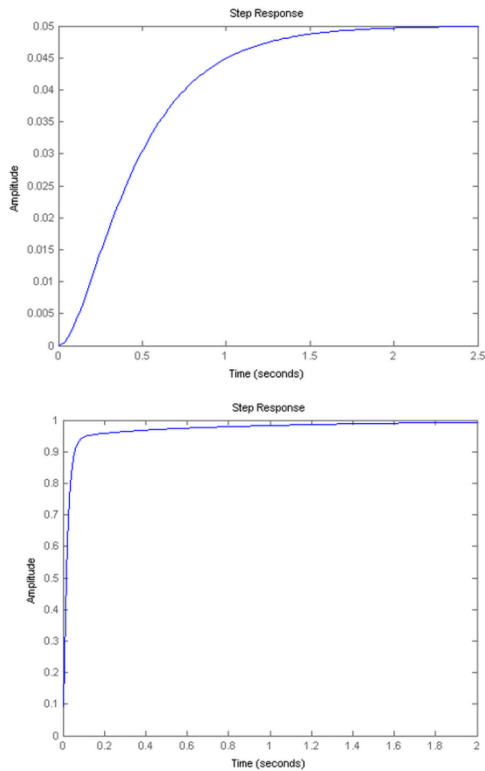


# Hardware – Overview



# Software - FPGA

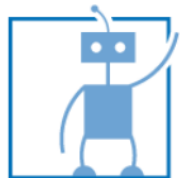
## Control motor PID control



## Ultra Sound distance measurement



## Battery/Voltage measurement





# Software – IMX6

## Debian 7 „Wheezy“

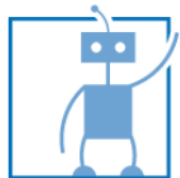
Kernel 3.0.35



## Connectivity



## Control unit

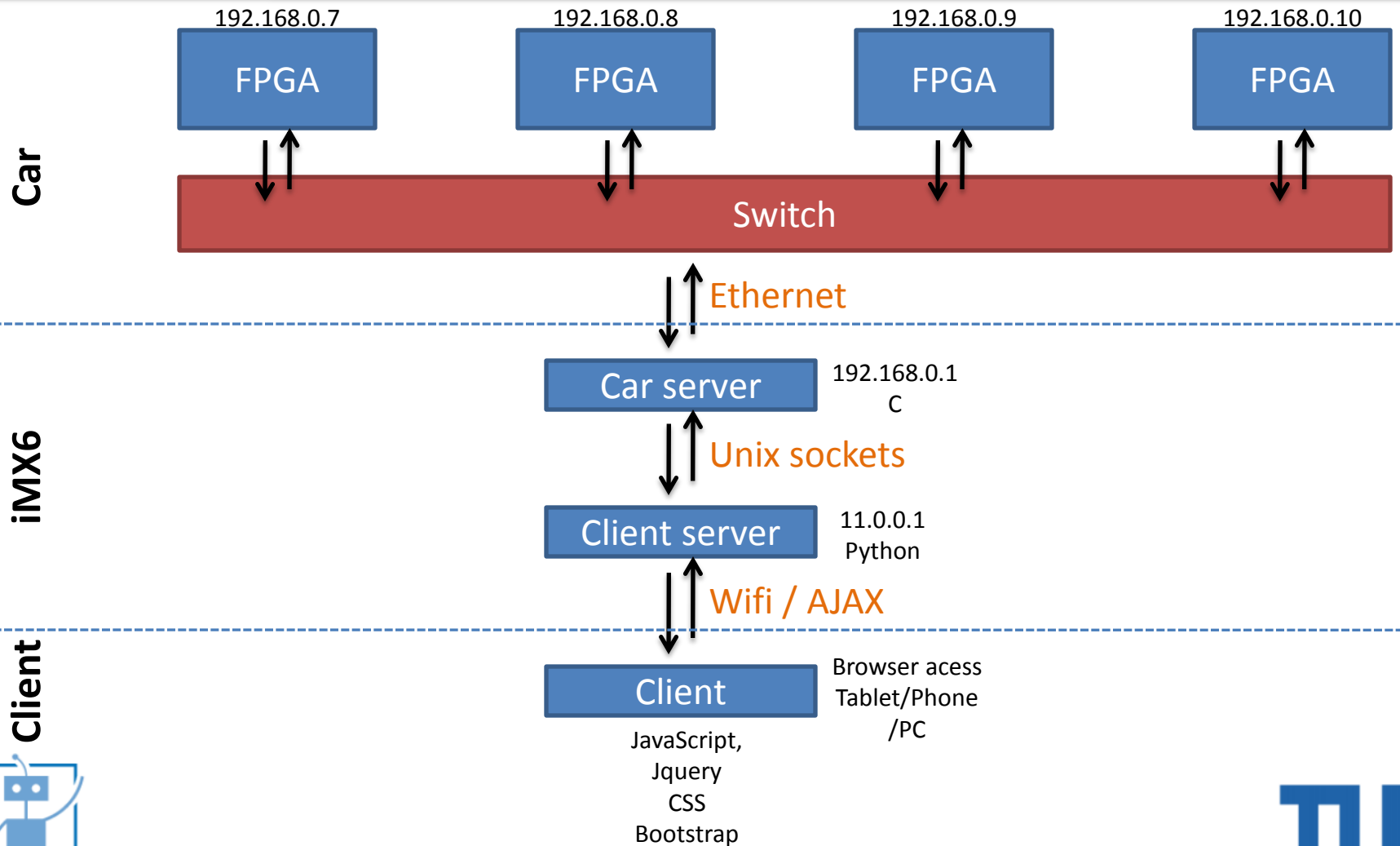


# Client interface

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# Software Architecture



# Future steps

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- Implement ABS/ESP
- Obstacle detection v2.0
- Autonomous driving



# Results

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**Live demo!**

