Performance Characteristics

Sorting

ALGORITHM	IN PLACE	STABLE	BEST	AVERAGE	WORST	REMARKS
selection sort	Χ		½ n^2	½ n^2	½ n^2	n exchanges; quadratic in best case
insertion sort	Χ	X	n	1⁄4 n^2	½ n^2	use for small or partially-sorted arrays
bubble sort	Χ	X	n	½ n^2	½ n^2	rarely useful; use insertion sort instead
shellsort	Χ		n log3 n	unknown	c n^3/2	tight code; subquadratic
mergesort		X	½ n lg n	n lg n	n lg n	n log n guarantee; stable
quicksort	X		n lg n	2 n ln n	½ n^2	n log n probabilistic guarantee; fastest in practice
heapsort	Χ		n †	2 n lg n	2 n lg n	n log n guarantee; in place

Priority Queues

DATA STRUCTURE	INSERT	DEL-MIN	MIN	DEC-KEY	DELETE	MERGE
array	1	n	n	1	1	n
binary heap	log n	log n	1	log n	log n	n
d-way heap	logd n	d logd n	1	logd n	d logd n	n
binomial heap	1	log n	1	log n	log n	log n
Fibonacci heap	1	log n†	1	1 †	log n†	log n

^{• †} n lg n if all keys are distinct

Symbol Tables

DATA STRUCTURE	SEARCH	INSERT	DELETE	SEARCH	INSERT	DELETE
sequential search (in an unordered array)	n	n	n	n	n	n
binary search (in a sorted array)	log n	n	n	log n	n	n
binary search tree (unbalanced)	n	n	n	log n	log n	sqrt(n)
red-black BST (left-leaning)	log n					
hash table (separate-chaining)	n	n	n	1 †	1 †	1 †
hash table (linear-probing)	n	n	n	1 †	1†	1 †

• † uniform hashing assumption

Graph Processing

PROBLEM	ALGORITHM	TIME	SPACE
path	DFS	E + V	V
cycle	DFS	E + V	V
directed cycle	DFS	E + V	V
topological sort	DFS	E + V	V
bipartiteness / odd cycle	DFS	E + V	V
connected components	DFS	E + V	V
strong components	Kosaraju-Sharir	E + V	V
Eulerian cycle	DFS	E + V	E+V
directed Eulerian cycle	DFS	E + V	V
transitive closure	DFS	V (E + V)	V 2
minimum spanning tree	Kruskal	E log E	E+V
minimum spanning tree	Prim	E log V	V
minimum spanning tree	Boruvka	E log V	V
shortest paths (unit weights)	BFS	E + V	V
shortest paths (nonnegative weights)	Dijkstra	E log V	V
shortest paths (negative weights)	Bellman-Ford	V (V + E)	V
all-pairs shortest paths	Floyd-Warshall	V 3	V 2
maxflow-mincut	Ford-Fulkerson	E V (E + V)	V

PROBLEM	ALGORITHM	TIME	SPACE
bipartite matching	Hopcroft-Karp	V ½ (E + V)	V
assignment problem	successive shortest paths	n^3 log n	n^2

Sorting

Selection Sort

```
sort(A)
    n = A.length
    for i in [0:n)
        min = i
        for j in [i + 1:n)
            if A[j] < A[min]
                 min = j
        swap(A[i], A[min])</pre>
```

Insertion Sort

```
sort(A)
  n = A.length
  for i in [0:n)
```

```
for j=i;\ j>0 and A[j]< A[j-1];\ --j swap(A[j],\ A[j-1])
```

Bubble Sort

Shellsort

```
sort(A)
    n = A.length
    h = 1
    while h < n / 3
        h = 3 * h + 1
    while h >= 1
        for i in [h:n)
        for j = i; j >= h and A[j] < A[j - h]; j -= h</pre>
```

```
swap(A[j], A[j - h])
h = h / 3
```

Mergesort

```
sort(A)
   Aux = A
    sort(A, Aux, 0, A.length - 1)
sort(A, Aux, lo, hi)
    if hi <= lo
        return
    mid = (hi + lo) / 2
    sort(A, Aux, lo, mid)
    sort(A, Aux, mid + 1, hi)
    merge(A, Aux, lo, mid, hi)
merge(A, Aux, lo, mid, hi)
    for k in [lo:hi] // closed-interval, includes hi
        Aux[k] = A[k]
    i = lo
    j = mid + 1
    for k in [lo:hi] // closed-interval, includes hi
        if mid < i
            A[k] = Aux[j++]
        else if hi < j
            A[k] = Aux[i++]
        else if Aux[j] < Aux[i]</pre>
            A[k] = Aux[j++]
```

```
else
A[k] = Aux[i++]
```

Quicksort

```
sort(A)
   sort(A, 0, A.length - 1)
sort(A, lo, hi)
    if hi <= lo
        return
   j = partition(A, lo, hi)
    sort(A, lo, j - 1)
    sort(A, j + 1, hi)
partition(A, lo, hi)
   i = lo
   j = hi + 1
   v = A[lo]
   while true
       while A[++i] < v
           if i == hi
                break
       while v < A[--j]
           if j == lo
                break
        if j \le i
           break
        swap(A[i], A[j])
```

```
swap(A[lo], A[j])
return j
```

Heapsort

• NOTE: uses elements from 1 to n - 1 (rather than 0 to n - 1) to simplify index arithmetic

```
sort(A)
    n = A.length
    for k = n / 2; k >= 1; --k
        sink(A, k, n)
    while n > 1
        swap(A[1], A[n--])
        sink(A, 1, n)
sink(A, k, n)
    while 2 * k \le n
       j = 2 * k
        if j < n and A[j] < A[j + 1]
            ++j
        if A[j] \ll A[k]
            break
        swap(A[k], A[j])
        k = j
```

Bucket Sort

set bucket_size based on size of A, default to 5

```
sort(A, bucket_size)
  if A.length < 10
    // use another sort
  num_buckets = (A.max - A.min / bucket_size) + 1
  Aux // array of arrays num_buckets in size</pre>
```

```
for e in A
    Aux[(e - A.min) / bucket_size].push(e)

j = 0

for Arr in Aux
    for e in Arr
    A[j++] = e
```

Counting Sort

```
sort(A)
  if A.length < 10
    // use another sort
  range = A.max - A.min + 1
  Counts // size of range, initialized to 0's
  for e in A
    ++Counts[e - A.min]
  for i in [1:range)
    Counts[i] += Counts[i - 1]
  Aux // size of A
  for a in A
    Aux[--Counts[e - min]] = e
  A = Aux</pre>
```

Binary Search

Ordered Array

```
binary_search(A, key)
  lo = 0
  hi = A.length - 1

while lo <= hi
  mid = (hi + lo) / 2</pre>
```

```
if key < A[mid]
   hi = mid - 1
else if A[mid] < key
   lo = mid + 1
else
   return mid

return -1</pre>
```

Binary Search Tree

```
contains(BST, key)
  if key == null
    throw
  return get(BST, key) != null

get(BST, key)
  if key == null
    throw
  if BST == null
    return null
  if key < BST.key
    return get(BST.left, key)
  else if BST.key < key
    return get(BST.right, key)
  return BST.value</pre>
```

Binary Search Tree Size

```
size(BST)
  if BST == null
    return 0
  return 1 + size(BST.right)
```

Tree Traversal

Recursive

Preorder

```
traverse(root)
  if root == null
    return
  visit(root)
  traverse(root.left)
  traverse(root.right)
```

Inorder

```
traverse(root)
  if root == null
    return
  traverse(root.left)
  visit(root)
  traverse(root.right)
```

Postorder

```
traverse(root)
  if root == null
    return
  traverse(root.left)
  traverse(root.right)
  visit(root)
```

Iterative

Level Order (Breadth First)

```
traverse(root)
  if root == null
    return
Queue = 0
Queue.enqueue(root)
while Queue != 0
    t = Queue.dequeue()
    visit(t)
    if t.left != null
        Queue.enqueue(t.left)
    if t.right != null
        Queue.enqueue(t.right)
```

Preorder

```
traverse(root)
  if root == null
    return
Stack = 0
Stack.push(root)
while Stack != 0
    t = Stack.pop()
    visit(t)
    if t.right != null
        Stack.push(t.right)
```

```
if t.left != null
    Stack.push(t.left)
```

Inorder

```
traverse(root)
    if root == null
        return
    Stack = 0
   t = root
    while t != null
       while t != null
            if t.right != null
                Stack.push(t.right)
            Stack.push(t)
            t = t.left
       t = Stack.pop()
       while Stack != 0 and t.right == null
            visit(t)
            t = Stack.pop()
        visit(t)
        if Stack == 0
            return
       t = Stack.pop()
```

Postorder

```
traverse(root)
  if root == null
    return
Stack = 0
  t1 = root
  t2 = root
  while t1 != null
    while t1.left != null
    Stack.push(t1)
```

```
t1 = t1.left
while t1.right == null or t1.right == t2
    visit(t1)
    t2 = t1
    if Stack == 0
        return
    t1 = Stack.pop()
Stack.push(t1)
t1 = t1.right
```

Tree Printing

Inorder Recursive

```
print_node(item, h)
    for i in [0:h)
        print(" ")
    print(item)
    print_tree(root, h)
    if root == null
        print_node("*", h)
        return
    print_tree(root.right, h + 1)
    print_node(root.value, h)
    print_tree(root.left, h + 1)
```

Level Order (Breadth First)

```
print_tree(root)
  if root == null
    return
```

```
Queue = 0
dummy
Queue.enqueue(root)
Queue.enqueue(dummy)
while Oueue != 0
    t = Queue.dequeue()
    if t != dummy
        print(t.item)
        if t.left != null
            Queue.enqueue(t.left)
        if t.right != null
            Queue.enqueue(t.right)
     else
        print("\n")
        if Queue != 0
            Queue enqueue (dummy)
```

Priority Queues

Heap Priority Queue

• PQ - an array of keys with a size that is set on construction

```
class MaxPriorityQueue
  PQ
  size

insert(key)
    PQ[++size] = key
    swim(size)

pop() // delete max
    max = PQ[1]
    swap(PQ[1], PQ[size--])
    PQ[size + 1] = null
```

Symbol Tables

Red-Black BST

```
class Node
   key
   value
   left
   right
   size
   color

class RedBlackBST
   Node root
   is_red(node)
```

```
if node == null
        return false
    return node.color == red
rotate_left(node)
   x = node.right
   node.right = x.left
   x.left = node
   x.color = node.color
   node.color = red
   x.size = node.size
   node.size = 1 + size(node.left) + size(node.right)
    return x
rotate_right(node)
   x = node.left
   node.left = x.right
   x.right = node
   x.color = node.color
   node.color = red
   x.size = node.size
   node.size = 1 + size(node.left) + size(node.right)
    return x
flip_colors(node)
    node.color = red
    node.left.color = black
   node.right.color = black
put(key, value)
    root = put(root, key, value)
    root.color = black
put(node, key, value)
    if node == null
```

```
return Node(key, value, 1, red)
if key < node.key
    node.left = put(node.left, key, value)
else if node.key < key
    node.right = put(node.right, key, value)
else
    node.value = value

if !is_red(node.left) and is_red(node.right)
    node = rotate_left(node)
if is_red(node.left) and is_red(node.left.left)
    node = rotate_right(node)
if is_red(node.left) and is_red(node.right)
    flip_colors(node)

node.size = size(node.left) + size(node.right) + 1
return node</pre>
```

Hash Tables

Hashing

- REMEMBER:
 - hash is a template class in C++ that is overloaded for operator()
 - libcxx uses Murmur2 and CityHash
- radix

```
std::numeric_limits<Type>::max() - std::numeric_limits<Type>::min() + 1
```

floating point numbers

• sign

```
std::numeric_limits<Type>::is_signed
```

exponent

```
sizeof(type) * std::numeric_limits<unsigned char>::digits - std::numeric_limits<type>::is_signed - std::numeric_limits
```

mantissa

```
std::numeric_limits<float>::digits
```

- floating point types in libcxx
 - can use a union of the float type and size_t or reinterpret_cast (better to use reinterpret cast)

· Sedgewick hashing

```
return (hash(x) & 0x7FFFFFFF) % modulo_divisor  
// or  
return (hash(x) & (\sim(0UL) >> 1) % modulo_divisor  
// or  
return hash(x) % modulo_divisor // the masking is not needed because C++ uses std::size_t
```

· Sedgewick string hashing

```
hash(Str)
h = 0
for c in Str
h = (radix * h + c) % modulo_divisor
return h
```

· Java-style hashing

```
class Example
   c // char
   s // short
   i // int
   l // long
   f // float
   d // double
hash(object)
   h = 17
   h = 31 * h + hash(object.c)
   h = 31 * h + hash(object.s)
   h = 31 * h + hash(object.i)
   h = 31 * h + hash(object.l)
   h = 31 * h + hash(object.f)
   h = 31 * h + hash(object.d)
   return h
```

Hash Table (Separate Chaining)

- ST is an array of LinkedLists
- NOTE: need to handle resizing and re-hashing, etc

```
class HashTable
ST
size
```

```
hash(key)
    return (hash_code(key) & 0x7FFFFFFF) % M

get(key)
    return ST[hash(key)].get(key) // get scans linked list for key

put(key, value)
    ST[hash(key)].pu(key, value) // put adds key, value node to linked list
```

Hash Table (Linear Probing)

· Keys and Values are arrays with capacity

```
class HashTable
   Keys
   Values
   capacity
   size
   hash(key)
        return (hash_code(key) & 0x7FFFFFFF) % M
   resize(n)
       t = HashTable(n)
       for i in [0:capacity)
            if Keys[i] != null
                t.put(Keys[i], Values[i])
       Keys = t.Keys
       Values = t.Values
        capacity = t.capacity
   put(key, value)
```

```
if size >= capacity / 2
        resize(2 * capacity)
    i = hash(key)
   while Keys[i] != null
        if Keys[i] == key
            return Values[i]
        i = (i + 1) % capacity
   Keys[i] = key
   Values[i] = value
   ++size
get(key)
   i = hash(key)
   while Keys[i] != null
        if Keys[i] == key
            return Values[i]
        i = (i + 1) % capacity
    return null
```

Graph Algorithms

Depth First Search

```
class DepthFirstSearch
    Graph
    Marked

DepthFirstSearch(source)
    dfs(source)

dfs(v)
    Marked[v] = true
    for each w adjacent to v in Graph
```

```
if !Marked[w]
  dfs(w)
```

Breadth First Search

Connected Components

```
class ConnectedComponents
    Graph
    Marked
    Ids
    ComponentSize
    count
ConnectedComponents(Graph)
```

```
for v in [0:Graph.num_vertices())
        if !Marked[v]
            dfs(v)
            ++count
dfs(v)
   Marked[v] = true
   Ids[v] = count
   ++ComponentSize[count]
   for each w adjacent to v in Graph
        if !Marked[w]
            dfs(w)
id(v)
    return Ids[v]
size(v)
    return ComponentSize[Ids[v]]
connected(v, w)
    return id(v) == id(w)
```

Reachability

Depth First Paths

```
class DepthFirstPaths
Graph
Marked
EdgeTo
source
```

```
DepthFirstPaths(Graph, source)
   dfs(source)
dfs(v)
   Marked[v] = true
   for each w adjacent to v in Graph
        if !Marked[w]
            EdgeTo[w] = v
            dfs(w)
has_path_to(v)
    return Marked[v]
path_to(v)
   if !Marked[v]
        return null
   Path // stack
   for x = v; x != source; x = EdgeTo[x]
        Path.push(x)
    path.push(s)
    return path
```

Breadth First Paths

• before running bfs, init DistanceTo to -1, infinity, etc

```
class BreadthFirstPaths
    Graph
    Marked
    EdgeTo
    DistanceTo
    source

BreadthFirstPaths(Graph, source)
```

```
bfs(s)
    Queue
   DistanceTo[s] = 0
   Marked[s] = true
   Queue.enqueue(s)
   while Queue != 0
        v = Queue.dequeue()
        for each w adjacent to v in Graph
            if !Marked[w]
                EdgeTo[w] = v
                DistanceTo[w] = DistanceTo[v] + 1
                Marked[w] = true
                Queue.enqueue(w)
has_path_to(v)
    return Marked[v]
distance_to(v)
    return DistanceTo[v]
path_to(v)
   if !Marked[v]
        return null
   Path // stack
   for x = v; DistanceTo[x] != 0; x = EdgeTo[x]
        Path.push(x)
```

bfs(source)

```
path.push(v)
return path
```

Cycle (Undirected)

- · Graph undirected graph
- Marked boolean array signifying that the vertex has been visited where size = number of vertices
- EdgeTo integer array marking parent in path
- · Cycle stack containing the cycle if found

```
class Cycle
    Graph
    Marked
    EdgeTo
    Cycle
    Cycle()
        for each vertex v in G
            if !Marked(v)
                dfs(-1, v)
    has_cycle()
        return Cycle != 0
    dfs(u, v)
       Marked[v] = true
        for each w adjacent to v in Graph
            if Cycle != 0
                return
            if !Marked[w]
                EdgeTo[w] = v
                dfs(v, w)
            else if w != u
                for x = v; x != w; x = EdgeTo[x]
                    Cycle.push(x)
```

```
Cycle.push(w)
Cycle.push(v)
```

Directed Cycle

- · Graph directed graph
- Marked boolean array signifying that the vertex has been visited where size = number of vertices
- EdgeTo integer array marking parent in path
- · OnStack boolean array signifying if the vertex is part of the cycle
- · Cycle stack containing the cycle if found

```
class DirectedCycle
    Graph
    Marked
    EdgeTo
    OnStack
    Cycle
    Cycle()
        for each vertex v in G
            if !Marked(v) and Cycle == 0
                dfs(v)
    has_cycle()
        return Cycle != 0
    dfs(v)
        OnStack[v] = true
       Marked[v] = true
        for each w adjacent to v in Graph
            if Cycle != 0
                return
            else if !Marked[w]
                EdgeTo[w] = v
```

```
dfs(w)
else OnStack[w]
  for x = v; x != w; x = EdgeTo[x]
        Cycle.push(x)
        Cycle.push(w)
        Cycle.push(v)
```

Depth First Order

- · Graph directed graph
- · Marked boolean array that signifies if the vertex has been visited
- PreNumbering the preorder order number of the vertex
- PostNumbering the postorder order number of the vertex
- Preorder a queue containing the vertices in their preorder ordering
- Postorder a queue containing the vertices in their postorder ordering
- preCounter used to maintain the current preorder index of the current vertex
- postCounter used to maintain the current postorder index of the current vertex

```
Marked[v] = true
PreNumbering[v] = pre_counter++
Preorder.enqueue(v)
for each w adjacent to v in Graph
    if !Marked[w]
        dfs(w)
Postorder.enqueue(v)
PostNumbering[v] = post_counter++

reverse_post()
    Stack
    for v in Postorder
        Stack.push(v)
    return Stack
```

Topological Sort

- · Graph directed graph
- Order the reverse post order numbering generated by DFS

```
class TopologicalSort
    Graph
    Order

TopologicalSort()
    if !DirectedCycle(Graph).has_cycle()
        order = DepthFirstOrder(Graph).reverse_post()
```

Strong Components (Kosaraju-Sharir)

- · Graph directed graph
- Marked boolean array
- Id component identifiers

· count - number of strong components

```
class StrongComponents
   Graph
   Marked
   Ιd
    count
   StrongComponents(Graph)
       for s in DepthFirstOrder(Graph.reverse()).reverse_post()
            if !Marked(s)
                dfs(s)
                ++count
   dfs(v)
       Marked[v] = true
       Id[v] = count
       for each w adjacent to v in Graph
            if !Marked[w]
                dfs(w)
   strongly_connected(v, w)
        return Id[v] == Id[w]
```

Minimum Spanning Tree (Prim)

- Graph edge weighted graph
- PQ Index min priority queue

```
class MST
Graph
EdgeTo
DistanceTo
```

```
Marked
P0
MST(Graph)
    PQ.insert(0, 0.0)
    while !PQ.empty()
        visit(PQ.pop())
visit(v)
    Marked[v] = true
    for each e adjacent to v in Graph // uses an Edge object
        w = e.other(v)
        if Marked[w]
            continue
        if e.weight() < DistanceTo[w]</pre>
            EdgeTo[w] = e
            DistanceTo[w] = e.weight()
            if PQ.contains(w)
                PQ.change_key(w, DistanceTo[w])
            else
                PQ.insert(w, DistanceTo[w])
```

Minimum Spanning Tree (Kruskal)

- Graph edge weighted graph
- · Queue a queue of Edge objects

```
class MST
    Graph
    Queue

MST(Graph)
    PQ // min priority queue
    for e in Graph
```

```
PQ.push(e)
uf = UnionFind(Graph)
while Queue != 0 and Queue.size < Graph.num_vertices() - 1
    e = PQ.pop()
    v, w = vertices in e
    if uf.connected(v, w)
        continue
    uf.create_union(v, w)
    Queue.enqueue(e)</pre>
```

Shortest Paths (Djikstra)

- · Graph an edge-weighted directed graph
- EdgeTo array of directed edge objects
- DistanceTo the weighted distance to an edge from the source, initialized to infinity and 0.0 for the source
- PQ index min priority queue

```
class ShortestPaths
    Graph
    EdgeTo
    PQ

ShortestPaths(Graph, s)
    PQ.push(s, 0.0)
    while PQ != 0
        relax(PQ.pop())

relax(PQ.pop())

relax(P = 0)
    if DistanceTo[v] + e.weight() < DistanceTo[w]
        DistanceTo[w] = DistanceTo[v] + e.weight()
        EdgeTo[w] = e
        if PQ.contains(w)</pre>
```

Shortest Paths (Bellman-Ford)

```
class ShortestPaths
   Graph
   DistanceTo
   EdgeTo
   InQueue
   Queue
   Cycle
   cost
    ShortestPaths(Graph, s)
        Queue enqueue(s)
       OnQueue[s] = true
       while Queue != 0 and !has_negative_cycle()
            v = Queue.dequeue()
            OnQueue[v] = false
            relax(v)
    relax(v)
       for each e adjacent to v in Graph // uses a DirectedEdge object
            w = e.destination()
```

```
if DistanceTo[v] + e.weight() < DistanceTo[w]</pre>
            DistanceTo[w] = DistanceTo[v] + e.weight()
            EdgeTo[w] = e
            if !OnQueue[w]
                Queue enqueue (w)
                OnQueue[w] = true
        if cost++ % Graph.num_vertices() == 0
            find negative cycle()
find_negative_cycle()
    Spt // EdgeWeightedDigraph of size EdgeTo.length
   for v in [0:EdgeTo.length)
        if EdgeTo[v] != null
            Spt.add_edge(EdgeTo[v])
    CF // EdgeWeightedCycleFinder from Spt
    cycle = CF.cycle()
has_negative_cycle()
    return Cycle != 0
```

Dijkstra All-Pairs Shortest Paths

· AllShortestPaths - an array of Dijkstra shortest paths objects

```
class AllPairsShortestPaths
    Graph
    AllShortestPaths

AllPairsShortestPaths(Graph)
    for v in [0:Graph.num_vertices())
        AllShortestPaths[v] = ShortestPaths(G, v)
```

```
path(s, t)
    return AllShortestPaths[s].path_to( t)

distance_to(s, t)
    return AllShortestPaths[s].distance_to(t)
```

String Algorithms

LSD String Sort

- · A is an array of strings
- radix 256 for 8-bit char
- · very similar to counting sort

```
for i in [0:n)
A[i] = Aux[i]
```

MSD String Sort

 uses same technique as above but in reverse and calculates the character at a position of a string by first checking the length and otherwise returning -1

Trie Symbol Table

- · radix 256 for 8-bit chars
- · root Node
- keys are strings

```
class Node
   value
   Subtries // an array of Nodes of size radix
class Trie
    root
   get(key)
       x = get(root, key, 0)
       if x == null
            return null
        return x.value
    get(node, key, d) // dth key character for subtrie
        if node == null
            return null
       if d == key.length
            return x
        return get(x.Subtries[key[c]], key, d + 1)
```

```
put(key, value)
  root = put(root, key, value, 0)

put(node, key, value, d)
  if x == null
    x = Node
  if d == key.length
    x.value = value
    return x
  x.Subtries[key[d]] = put(x.Subtries[key[d]], key, value, d + 1)
  return x
```

TST

```
class Node
    char
   left
   mid
    right
   value
class TST
    root
    get(Key)
       x = get(root, Key, 0)
       if x == null
            return null
        return x.value
    get(node, Key, d)
```

```
if node == null
        return null
    c = Key[d]
   if c < node.char
        return get(node.left, Key, d)
    else if node.char < c
        return get(node.right, Key, d)
    else if d < Key.length - 1
        return get(node.mid, Key, d + 1)
    return node
put(Key, value)
    root = put(root, Key, value, 0)
put(node, Key, value, d)
    c = Key[d]
    if node == null
        node = Node
        node.char = c
   if c < node.char</pre>
        node.left = put(node.left, Key, value, d)
    else if node.char < c
        node.right = put(node.right, Key, value, d)
   else if d < Key.length - 1
        node.mid = put(node.mid, Key, value, d + 1)
    else
        node.value = value
    return node
```

Substring Search (Knuth-Morris-Pratt)

- · String the pattern to search for
- DFA two-dimensional array of integers (representing characters) of size radix X String.length
- radix 256 for 8-bit chars

```
class SubstringSearch
   Pattern
    DFA
    SubstringSearch(String)
       DFA[Pattern[0]][0] = 1
       x = 0
       for j in [1:Pattern.length)
           for c in [0:radix)
                DFA[c][j] = DFA[c][x]
           DFA[Pattern[j]][j] = j + 1
           x = DFA[Pattern[i]][x]
   search(Text)
       m = Pattern.length
       n = Text.length
        i = 0
       j = 0
       while i < n and j < m
           j = DFA[Text[i]][j]
           ++i
       if j == m
            return i - m // found - hit end of pattern
       else
            return n // not found - hit end of text
```

Substring Search (Boyer-Moore)

- RightOccurence integer (represents chars) of size radix, initialized to -1
- · radix 256 for 8-bit chars

```
class SubstringSearch
RightOccurence
Pattern
```

```
SubstringSearch(String)
   for i in [0:Pattern.length)
        RightOccurrence[Pattern[i]] = i
search(Text)
   m = Pattern.length
   n = Text.length
   skip = 0
   i = 0
   for i = 0; i \le n - m; i += skip
        skip = 0
        for j = m - 1; j >= 0; ---j
            if Pattern[j] != Text[i + j]
                skip = j - RightOccurrence[Text[i + j]]
                if skip < 1
                    skip = 1
                break
            if skip == 0
                return i
    return n
```

Substring Search (Rabin-Karp)

```
• radix - 256 for 8-bit char
```

```
• rm - radix ^ (pattern_length - 1) % large_prime
```

```
class SubstringSearch
  pattern_hash
  pattern_length
  large_prime
  rm
SubstringSearch(String)
```

```
for i in [1:pattern length - 1)
        rm = (radix * rm) % large prime
   pattern_hash = hash(Pattern, pattern_length)
hash(key, m)
   h = 0
   for j in [0:pattern length)
       h = (radix * h + key[j]] % large prime
    return h
search(Text)
   n = Text.length
   text_hash = hash(Text, m)
    if pattern hash == text hash
        return 0
   for i in [pattern_length:n)
       text_hash = (text_hash + large_prime - rm * Text[i - m] % large_prime) % large_prime
       text_hash = (text_hash * radix + Text[i]) % large_prime
        if text_hash == pattern_hash
            return i - pattern_length + 1
    return n
```

Regular Expression Pattern Matching

- Regex char array matching input regular expression
- · Digraph epsilon transitions
- num_states length of the regular expression

```
class NFA
Regex
Digraph
num_states
```

```
NFA(String)
    Ops // stack
    for i in [0:num_states)
        lp = i
        if Regex[i] == '(' or Regex[i] == '|'
            Ops.push(i)
        else if Regex[i] == ')'
            or = Ops.pop()
            if re[or] == '|'
                lp = Ops.pop()
                Digraph.add_edge(lp, or + 1)
                Digraph.add_edge(or, i)
            else
                lp = or
        if i < num_states - 1 and Regex[i + 1] == '*' // lookahead</pre>
            Digraph.add edge(lp, i + 1)
            Digraph.add_edge(i + 1, lp)
        if Regex[i] == '(' or Regex[i] == '*' or Regex[i] == ')'
            Digraph.add edge(i, i + 1)
recognizes(Text)
    PC // bag of integers
    dfs // directed DFS of the Digraph from 0
    for v in [0:Digraph.num_vertices())
        if dfs.marked(v)
            PC.add(v)
    for i in [0:Text.length)
        Match // bag of integers
        for v in PC
            if v < num states
                if Regex[v] == Text[i] or Regex[v] == '.'
                    Match.add(v + 1)
        PC // re-initialize
        dfs // directed DFS of the Digraph for all vertices in Match
        for v in [0:Digraph.num_vertices())
            if dfs.marked(v)
                PC.add(v)
    for v in PC
        if v == num_states
```

Huffman Compression

radix - 256 for 8-bit char

```
class Node
   char
   frequency
   left
   right
compress(String)
   Input // char array of String
   Frequency
   for i in [0:Inpute.length)
       ++Frequency[Input[i]]
    root = build_trie(Frequency)
    ST // array of strings of size radix
    build_code(ST, root, "")
   Encoded = ""
   for i in [0:Input.length)
       Code = ST[Input[i]]
       for j in Code
            Encoded += j
    return Encoded
build_code(ST, node, String)
   if node.is_leaf()
        ST[node.char] = String
        return
   build_code(ST, node.left, s + '0')
    build_code(ST, node.right, s + '1')
```

LZW Compression

```
· radix - 256 for 8-bit char
```

- num_codewords 4096 (number of codewords or 2^12)
- width 12 (codeword width)

General Algorithms

Longest Common Subsequence

• MaxLengths - 2D array, Str1.length x Str2.length, initialized to -1

```
class LCS
   MaxLengths
    Str1
   Str2
   LCS(Str1, Str2)
   lcs()
        return lcs(Str1.length - 1, Str2.length - 1)
   lcs(i, j)
       if i == 0 or j == 0
            return 0
        if MaxLengths[i][j] != −1
            return MaxLengths[i][j]
       if Str1[i] == Str2[j]
            result = 1 + lcs(i - 1, j - 1)
       else
            result = \max(lcs(i - 1, j), lcs(i, j - 1))
       MaxLengths[i][j] = result
        return result
```

Suffix Arrays

• good for actually returning value of longest common subsequence, longest common prefix, and longest repeated substring

Knapsack

- Options 2D array of ints, num items + 1 x max weight + 1
- Solution 2D array of bools, num_items + 1 x max_weight + 1
- num_items Profits.length (or Weights.length)
- max_weight constraint on weight allowed in knapsack
- NOTE: also assumes a reference to Profits and Weights is maintained
- NOTE: would also memoize get_max_profit and get_total_weight

```
class Knapsack
    Options
    Solution
    num items
    max_weight
    Knapsack(Profits, Weights)
        for i in [1:num_items] // closed-interval, includes num_items
            option1 = Options[i - 1][j]
            option2 = Int.min()
            if Weights[i - 1] <= j
                option2 = Profits[i - 1] + Options[i - 1][j - Weights[i - 1]]
            Options[i][j] = max(option1, option2)
            Solution[i][j] = option1 < option2;</pre>
    get_items_to_take()
        ItemsToTake // set of integers
        n = num items
       w = max_weight
        while n > 0
            if Solution[n][w]
                ItemsToTake.push(n)
                w = w - Weights[n - 1]
            --n
        return ItemsToTake
```

Maximum Subarray

```
max_subarray(A)
  max = 0
  local_max = 0
  for e in A
    local_max = max(0, local_max + e)
    max = max(max, local_max)
  return max
```

Divide-and-Conquer

Levenshtein Distance

• Distances - prefix distances, 2D array size of Str1 x size of Str2 initialized to -1

```
class Levenshtein
   Distances
    Str1
   Str2
   Levenshtein(Str1, Str2)
        distances(Str1.length - 1, Str2.length - 1)
   get_edit_distances(i, j)
       if i < 0
            return j + 1
       if j < 0
            i + 1
       if Distances[i][j] == −1
            if Str1[i] == Str2[i]
                Distances[i][j] = get_edit_distances(i - 1, j - 1)
            else
                a = get_edit_distances(i - 1, j - 1)
                b = get_edit_distances(i - 1, j)
                c = get_edit_distances(i, j - 1)
                Distances[i][j] = min(a, b, c)
        return Distances[i][j]
```

Permutations

Standard 1

```
permutations(A)
   permutations(\{\}, A)

permutations(P, S)
   n = S.length
   if n == 0
```

```
Out.push(P)
  return
for i in [0:n)
  permutations(P + S[i], S[0:i) + S[i + 1:))
```

Standard 2

```
permutations(A)
    permutations(A, A.length)

permutations(A, n)
    if n == 1
        Out.push(A)
        return
    for i in [0:n)
        swap(A[i], A[n - 1])
        permutations(A, n - 1)
        swap(A[i], A[n - 1])
```

K

Lexicographical

```
has_next(A)
    n = A.length
    k = 0
   for k = n - 2; k \ge 0; --k
       if A[k] < A[k + 1]
            break
    if k == -1
       return false
   j = n - 1
   while A[j] < A[k]
       -- j
    r = n - 1
    s = k + 1
   while r > s
        swap(A[r], A[s]
        --r
        ++5
    return true
permutations(A)
    Out.push(A)
   while has_next(A)
       Out.push(A)
```

Combinations

Standard 1

```
combinations(A)
  combinations({}, A)

combinations(P, S)
```

```
if S.length <= 0
    return
Out.push(P + S[0])
combinations(P + S[0], S[1:))
combinations(P, S[1:))</pre>
```

Standard 2

```
combinations(A)
  combinations(\{\}, A)

combinations(P, S)
  Out.push(P)
  for i in [0:S.length)
      combinations(P + S[i], S[i + 1:))
```

K on n elements

```
combinations(A, pos, next, k, n)
  if pos == k
     Out.push(A)
    return
  for i in [next:n)
    s[pos] = i
    combinations(A, pos + 1, i + 1, k, n)
```

K Lexicographic 1

```
combinations(A, k)
  combinations({}, A, k)

combinations(P, S, k)
```

```
if S.length < k
    return
if k == 0
    Out.push(P)
    return
combinations(P + S[0], S[1:), k - 1)
combinations(P, S[1:), k)</pre>
```

K Lexicographic 2

```
combinations(A, k)
  combinations(P, S, k)

if k == 0
     Out.push(P)
    return

for i in [0:S.length)
    combinations(P + S[i], S[i + 1:), k - 1)
```

Partitions

Backtracking

n-Queens

• call to Out.push(A) assumes the results can be one-dimensional arrays with index of queen for each row

```
is_consistent(A, n)
   for i in [0:n)
       if A[i] == A[n] // same column
            return false
       if A[i] - A[n] == n - i // same major diagonal
            return false
       if A[n] - A[i] == n - i // same minor diagonal
           return false
    return true
enumerate(n)
   A // size of n
   enumerate(A, 0)
enumerate(A, k)
   n = A.length
   if k == n
       Out.push(A)
       return
   for i in [0:n)
       A[k] = i
       if is_consistent(A, k)
           enumerate(A, k + 1)
```

Sudoku

• Board - 9 x 9 board of values with 0's in unspecified spots

```
solve(Board)
   return solve(Board, 0, 0)
solve(Board, i, j)
   if i == Board.length and j + 1 == Board[i].length // reached solution
        return true
   if i == Board.length // move to next row
       i = 0
       ++j
   if Board[i][j] != 0
       return solve(Board, i + 1, j)
   for val in [1:Board.size] // closed-interval, includes Board.size
       if is_valid(Board, i, j, val)
           Board[i][i] = val
           if solve(Board, i + 1, j)
                return true
   Board[i][i] = 0
    return false
is_valid(Board, row, column, val)
    for A in Board // check same column
       if A[column] == val
           return false
   for e in Board[row] // check same row
       if e == val
           return false
    r_sz = 3
   for a in [0:r_sz)
       for b in [0:r sz)
           if Board[r_sz * (row / r_sz) + a][r_sz * (column / r_sz) + b] == val
```

```
return false return true
```

Lexicographical Compare

```
compare(A, B)
  i = 0
  j = 0
  while i < A.length && j < B.length
      if A[i] < B[j]
          return true
      if B[j] < A[i]
          return false
      ++i
      ++j
  return i == A.length and j < B.length</pre>
```

Horner's Method

```
horners_method(Coefficients, x)
  result = 0
  for i = Coefficients.length - 1; i >= 0; --i
     result = result * x + Coefficients[i]
  return result
```

Matrix Operations

Matrix x Matrix

```
multiply(A, B)
m1 = A.length
```