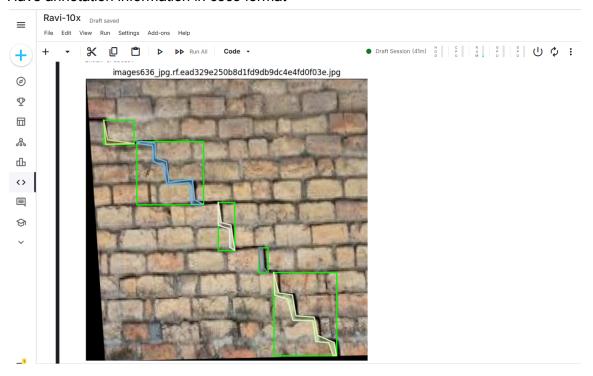
Project: Steps to train a text-guided segmentation model on custom data

 Visualize data from roboflow: Crack - seg masks + bbox masks Taping area - bbox masks

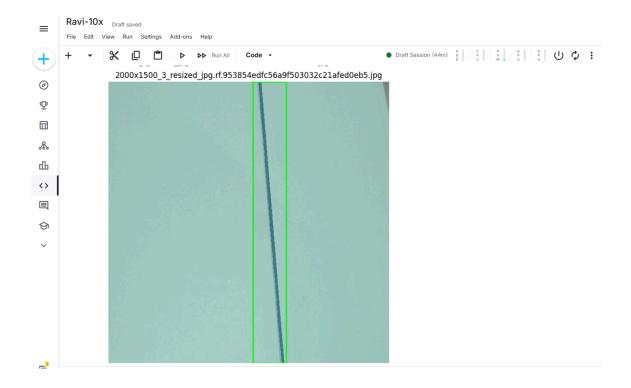
Have annotation information in coco format



2. Using SAM model (Segment Anything Model) to generate seg masks for taping area given bbox coordinates

https://docs.ultralytics.com/models/sam/#key-features-of-the-segment-anything-model-sam

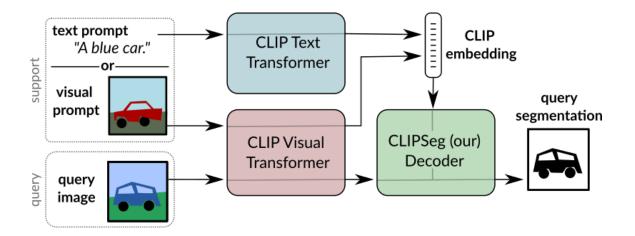
Saved masks as coco format (Preprocessing Notebook in the repo)



- Data preprocessing and DataLoader
 Data Augmentation done in Roboflow, while extracting dataset
 Using Train/Val split as provided in the dataset
- 4. Using CLIPSeg model: https://huggingface.co/docs/transformers/en/model_doc/clipseg

In warmup epochs, training only the decoder (SEG head) and, clip.text_projection, clip.visual_projection to align text embedding and vision embedding to decoder space

Then, training all params
Model Size: Total params: 150.75M



 Training Strategy and loss func: Started with BCE (binary cross-entropy) and dice loss Added Focal loss later

Changed image input dimension from 352 to 576

6. Model Training:

V0: Warmup epochs - 3
Full training epochs - 15

Loss: Dice + BCE Image size - 352

Runtime per epoch - 14 min Avg inference time/image - 0.6 second

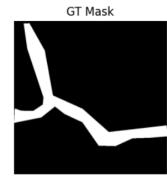
V1: Warmup epochs - 5
Full training epochs - 15

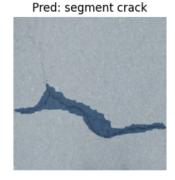
Loss: Dice +Focal BCE Image size - 576 LR scheduler - CosineAnnealingLR

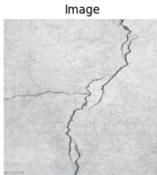
Runtime per epoch - 20 min Avg inference time/image - 1 second

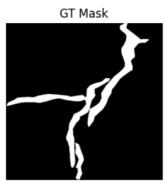
Some results while training

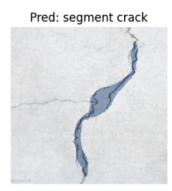


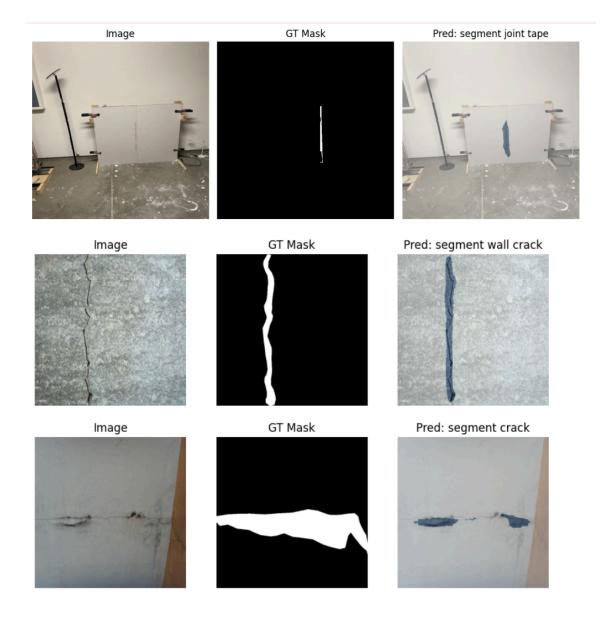


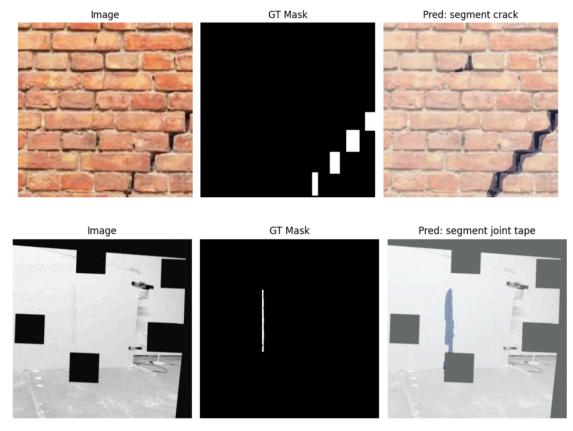






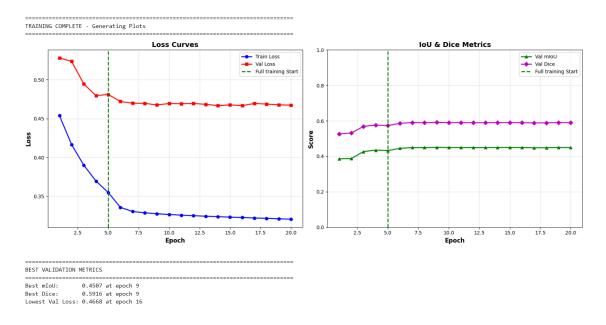






Failure Notes: Size mismatch, python libraries not compatible, etc

7. Loss plots and metrics on validation set:



8. Uploaded models to HuggingFace:

V0 - https://huggingface.co/RaviKush/clipseg_finetuned_dice_bce

V1: https://huggingface.co/RaviKush/clipseg_focal_loss_v1

- Ravi Kumar Kushawaha