

## Deadlock

In a multiprogramming system, a number of processes compete for limited no. of resources and if a resource is not available at that instance then process enters into waiting state.

If a process unable to change its waiting state indefinitely but the resources required by it are held by another waiting process then the system is said to be in deadlock.

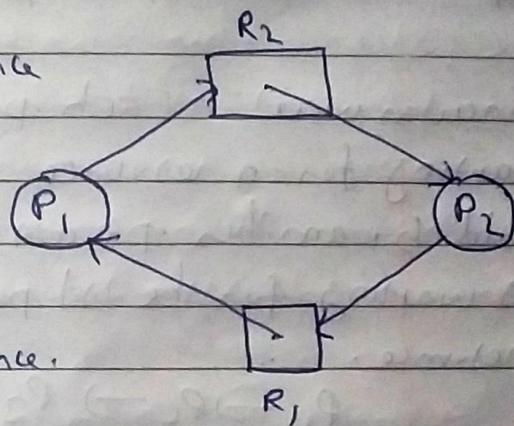
$P_1$  has acquired  $R_1$  resource

and requesting for

$R_2$  resource.

$P_2$  has acquired  $R_2$  and

requesting for  $R_1$  resource.



Resource allocation graph

## System model

→

every process will request for resource

→ If resource is granted then process will use the resource

→ Process must release the resource afterwards.

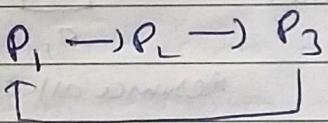
## Necessary Cond'n of deadlock

→ mutual exclusion: - at least one resource type in the system which can be used in non-shareable mode; i.e., mutual exclusion. e.g. Printer

Hold and wait :- A process is currently holding at least one resource and requesting additional resources which are being held by other processes.

No preemption :- A resource cannot be preempted from a process by any other process. Resource can be released by only voluntarily by the process holding it.

Circular wait :- Each process must be waiting for a resource which is being held by another process which in turn is waiting for the 1st process to release the resource.



here,  $P_1$  is waiting for  $P_2$  and  $P_2$  is waiting for  $P_3$ . upon here, if deadlock is satisfied. Let  $P_3$  is not waiting for resource then in this case, after sometime  $P_3$  will be finished and it will release its resources. So, deadlock will not occur. So, to avoid the deadlock, circular wait must be there.

## deadlock handling methods

- (1) Prevention :- means design such a system which violate at least one of four necessary cond's of deadlock and ensure independence from deadlock.
- (2) Avoidance :- system maintains a set of data using which it takes a decision whether to ~~take~~ entertain a new request or not, to be in safe state.
- (3) Detection and Recovery :- Here we wait until deadlock occurs and once we detect it, we recover from it.

Q)

### Deadlock Prevention:

mutual exclusion cannot be violated bcoz, whether a resource is shareable or not, depends on its hardware property. So R. g. Printer. So, while using the printer by a process, the US must have to ensure mutual exclusion, i.e. no other process can access the printer at that time.

### Violation of hold and wait

Conservative approach :- Process is allowed to start execution iff it has acquired all the resources (less efficient, not implementable, easy, deadlock independence)

or not hold :- In Process will acquire only desired resources but before making any fresh request it must release all the resources that it currently

~~hold~~ (Efficient, implementable)

~~hold time-out~~ :- A process can hold the resources upto a certain time limit and then it must release the resources.

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These sol's are useful will help in preventing the system from deadlock but after releasing the resources, some other process can use the released resources and can complete its execution.

### Violation of no preemption

forcefull preemption:- we allow a process to forcefullly preempt the resource held by other processes

→ this method may be used by high priority process or system process

→ the process which are in waiting state must be selected as a victim instead of process in the running state.

### Violation of circular wait

→ Circular wait can be eliminated by first giving a natural numbering the resources e.g.  $R_1, R_2, \dots, R_n$

→ allow every process to either only in the increasing or decreasing order of the resource number e.g. if a process wants  $R_1, R_3, R_7$  resources then it will request for  $R_1$  then  $R_3$  then  $R_7$ . On getting  $R_7$ , then  $R_3$  then  $R_1$ .

Let process  $P_1$  and  $P_2$  wants  $R_1$  and  $R_2$  resources.  
So, both  $P_1$  and  $P_2$  will try to get  $R_1$  1st.

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Let  $P_1$  got  $R_1$ , then as per the rule,

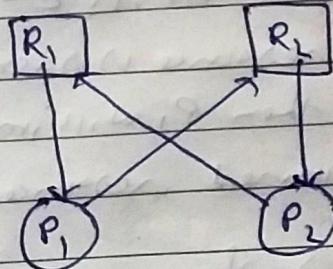
$P_2$  will not acquire  $R_1$  and it will wait to release  $R_1$  by  $P_1$ . So, circular wait will be avoided.

→ If during the execution, if a process wants a resource with less order number then it must release 1st all resources with high number than the required resource.

e.g. If  $P_1$  has acquired  $R_1, R_3, R_4$  and suddenly it wants  $R_2$  then it will have to release  $R_3$  and  $R_4$  resource.

$P_1 \rightarrow R_2 \rightarrow P_2 \rightarrow R_1$

Here, it is circular wait



Consider a system with 3 processes that share 4 instances of the same resource type. Each process can request a maxi. of  $K$  instances. Resource instances can be requested and released only one at a time. The largest value of  $K$  to avoid the deadlock.

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for  $K=1$ , no deadlock

for  $K=2$ , in the worst case, we should not give 2 resources to a process. We should give one less resource to a process to analyze the worst case.

So,  $P_1 \leftarrow R_1, P_2 \leftarrow R_2, P_3 \leftarrow R_3$

now, 1 resource is remaining. If it is assigned to  $P_1$ , then  $P_1$  will immediately release all its 2 acquired resources. So, no deadlock

If  $K=3$ , then deadlock must occur.

So,  $K=2$  is largest.

Suppose  $n$  processes,  $P_1, \dots, P_n$  share  $m$  identical resource units, which can be reserved and released one at a time. The maxi. resource requirement of process  $P_i$  is  $S_i$ , where  $S_i > 0$ . Which one of the following is a sufficient cond' for ensuring that deadlock does not occur?

$P_1$  need  $S_1$  resources

$$P_1 \sim S_1 \sim$$

$$\vdots$$
$$P_n \sim S_n \sim$$

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To analyse the worst case, let  $P_1$  holds  $S_1 - 1$ ,  
 $P_2$  holds  $S_2 - 1$  resources,  $P_3$  holds  $S_3 - 1$  resources  
 $P_n$  holds  $S_n - 1$  resources. So, prevent the deadlock

i.

$$(S_1 - 1) + (S_2 - 1) + (S_3 - 1) + \dots + (S_n - 1) < m$$

$$\sum_{i=1}^n S_i - n < m$$

$$\therefore \sum_{i=1}^n S_i < m + n$$

## Deadlock Avoidance

Problem with prevention:- Different deadlock prevention approach put different type of restriction on cond's on the processes and resources bcoz of which system becomes slow and resource utilization and reduced system throughput.

### Avoidance

→ To avoid deadlocks we require additional information about how resources are to be requested, which resources a process will request and use during its lifetime, i.e. max. no. of resources of each type that it may need.

→ With this additional knowledge, the OS can decide for each request whether process should wait or not.

	max need			Allocation			
	E	F	G	P <sub>0</sub>	P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>
P <sub>0</sub>	4	3	1	1	0	1	
P <sub>1</sub>	2	1	4	1	1	2	
P <sub>2</sub>	1	3	3	1	0	3	
P <sub>3</sub>	5	4	1	2	0	0	

	current need			System may			Available		
	E	F	G	E	F	G	E	F	G
P <sub>0</sub>	3	3	0	8	4	6	3	3	0
P <sub>1</sub>	1	0	2						
P <sub>2</sub>	0	3	0						
P <sub>3</sub>	3	4	1						

- A deadlock avoidance algo. dynamically examines the resource allocn state
- the resource allocn state is defined by the no. of available and allocated resources and the maxi. demands of the processes before allowing that request first.

Initially, current need of  $P_0$  and  $P_1$  can be satisfied.

Let current need of  $P_0$  is satisfied then  $P_0$  will release all its resources.

So, now available will be 3 3 0  
$$\begin{array}{r} 1 \ 0 \ 1 \\ - \ 1 \ 0 \ 1 \\ \hline 0 \ 3 \ 1 \end{array}$$

Now, let  $P_1$  current need of  $P_2$  is satisfied then  $P_2$  will release all its resources

So, now available will be 1 3 1  
$$\begin{array}{r} 1 \ 0 \ 3 \\ - \ 5 \ 3 \ 4 \\ \hline 5 \ 3 \ 4 \end{array}$$

Now, let current need of  $P_1$  is satisfied

So, available will be 5 3 4  
$$\begin{array}{r} 1 \ 1 \ 2 \\ - \ 6 \ 4 \ 6 \\ \hline 5 \ 3 \ 4 \end{array}$$

Now,  $P_2$  is satisfied

So, available 6 4 6  
$$\begin{array}{r} 2 \ 0 \ 0 \\ - \ 8 \ 4 \ 6 \end{array}$$

which is max. system resources

So,  $P_0 \rightarrow P_2 \rightarrow P_1 \rightarrow P_3$  can be said as a safe sequence, i.e. if processes are given the resources in that sequence then deadlock can be avoided.

A single processor system has 3 resources types  $X, Y, Z$ , which shared by 3 processes. There are 5 units of each resource type. Consider the following scenario, where the column 'Allocation' denotes the no. of units of each resource type allocated to each process and the column 'Request' denotes the no. of units of each resource type requested by a process in order to complete execution. Find the safe sequence.

	Max. System resources -			X	Y	Z	
	Allocation			5	5	5	
$P_0$	1	2	1	$P_0$	1	0	3
$P_1$	2	0	1	$P_1$	0	1	2
$P_2$	2	2	1	$P_2$	1	2	0

Here, request means current need

with this availability of ~~present~~ resources,  
current need of  $P_1$  can be satisfied.

Let  $P_1$  is granted. So,  $P_1$  will release its

resources. So, Available  $\times \begin{matrix} 7 & 2 \\ 0 & 1 \\ 2 & 0 \end{matrix} \begin{matrix} 2 \\ - \\ 2 \end{matrix} \begin{matrix} 1 & 3 \\ 1 & 2 \\ 3 & 3 \end{matrix}$

now,  $P_2$  can be granted.

So, available  $\begin{matrix} 2 & 1 & 3 \\ 1 & 2 & 1 \\ \hline 3 & 3 & 4 \end{matrix}$

now,  $P_2$  can be granted. So, available ~~available~~  
~~should be equal~~ after resource released by  
 $P_2$ , available resources should be equal to  
maxi. system resources.

Available  $\begin{matrix} 3 & 3 & 4 \\ 2 & 2 & 1 \\ \hline 5 & 5 & 5 \end{matrix}$

So, safe sequence is  $P_1 \rightarrow P_0 \rightarrow P_2$

∴

1 resource with 12 instances

man need Allocation

$P_1$	10	5
$P_2$	4	2
$P_3$	9	3

Current need

Availability  
 $12 - 10 = 2$

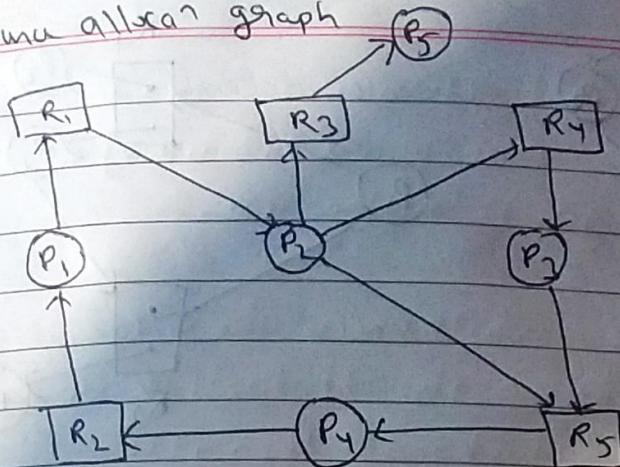
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P <sub>1</sub>	5
P <sub>2</sub>	2
P <sub>3</sub>	6

Now P<sub>2</sub> is granted. So, available  $2+2=4$

but now no process can be granted. So system is in unsafe state. However, it does not mean that system is in deadlock.

Resource allocation graph



here,  $P_1$  is waiting for  $R_1$  which is allocated to  $P_2$ . So,  $P_1 \rightarrow P_2$

$P_2$  is waiting for  $R_4$  which is allocated to  $P_3$ .

So,  $P_2 \rightarrow P_3$

$P_3$  is waiting for  $R_5$  which is allocated to  $P_4$ .

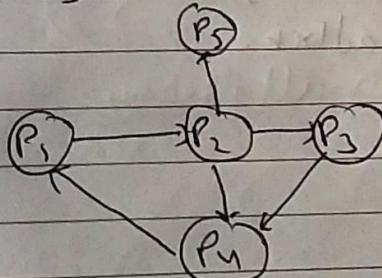
So,  $P_3 \rightarrow P_4$

$P_4$  is waiting for  $R_5$  which is allocated to  $P_5$ .

So,  $P_4 \rightarrow P_5$

$P_5$  is waiting for  $R_3$  which is allocated to  $P_2$ .

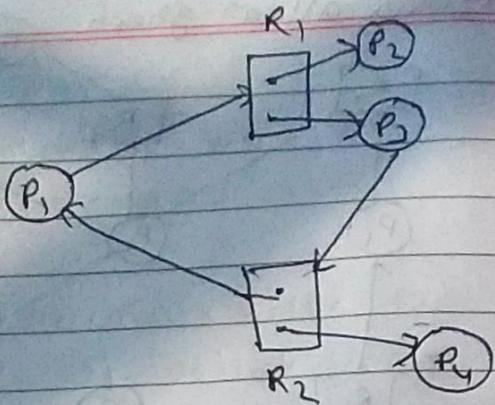
So,  $P_5 \rightarrow P_2$



Here, a cycle is formed. So, deadlock.

If only one instance of each resource is available then detection of cycle is necessary and sufficient cond<sup>n</sup> for detect<sup>n</sup> of deadlock.

Initially,  $P_1$  and  $P_2$



Initially,  $P_1$  and  $P_2$  are forming a cycle but once,  $P_2$  and  $P_4$  are served, they will release  $R_2$  the acquired resource ~~resource~~, i.e., 1 instance of  $R_1$  and 1 instance of  $R_2$  which can be served to  $P_2$  and  $P_4$ . So, even though cycle exist, it may not lead to deadlock.

So, in case of multiple instances of resources, detecting a cycle is necessary but not sufficient and of detection of deadlock.

## Deadlock Detect and Recovery

Here we do not check safety. In this case, when a process request for some resource then its request is granted immediately.

To check the possibility of deadlock, two approaches are followed

(a) Active approach: - Here, detection algo. are invoked at definite interval of time.

(b) Lazy approach: - Detection algo. are invoked when unusual performance is observed e.g. CPU utilization goes below 40%.

If resources have single instances then deadlock can be detected by detecting a cycle in resource allocation graph.

In case of multiple instances of resources, if cycle detected, safety algo. need to be run.

After detecting the deadlock, recovery from the deadlock is needed

Recovery in terms of resources:-

- (a) Preempt :- Preempt one resource of one user and give it to other user.
- (b) Rollback :- While executing the OS can maintain checkpoints. If deadlock is detected in a checkpoint then it can be rolled back to the previous checkpoint where there was no deadlock. In this process, some processes will have to release their acquired resources.

Recovery in terms of processes

- (a) Kill one process at a time. However, here choosing which process to kill is a difficult task.
- (b) Kill all processes.