

Machine Learning

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Lect 8

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SVM : Support Vector Machines : hyperplane based classifiers

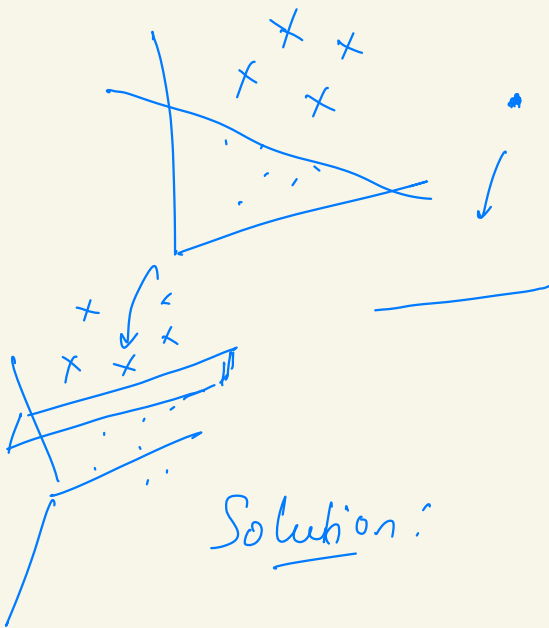
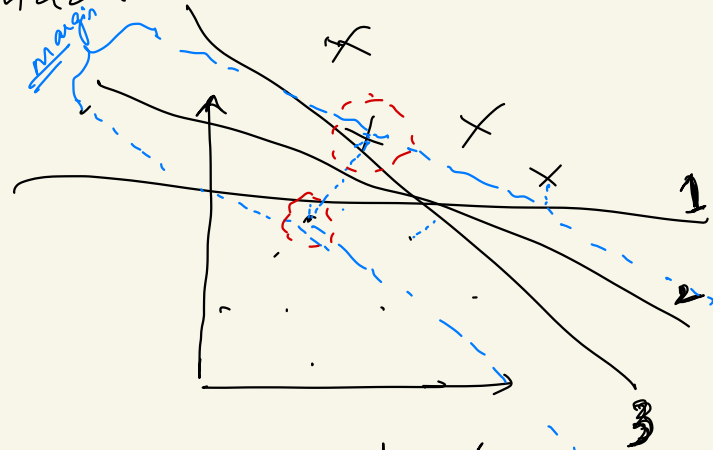
Vapnik Chernozhuk

[VC dimension]

$\Downarrow$   
complexity of machine

Twin SUM  
MCM: Minimal  
complexity  
machine

$$\approx O(n) \\ = O(n)$$



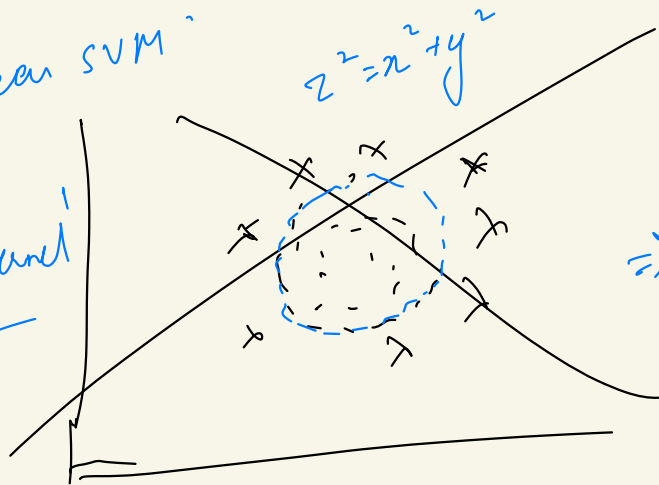
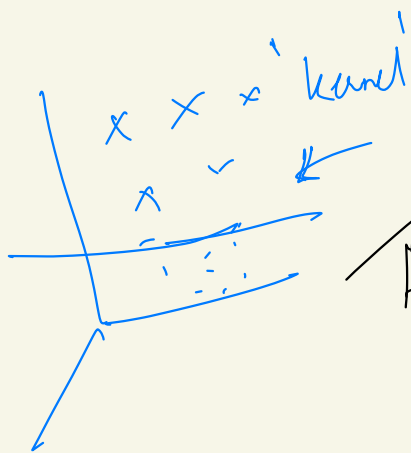
1, 2, 3 valid hyperplanes  
1, 2, 3 is a good hyperplane?

Solution:

Find that hyperplane  
which has maximum  
margin!

Support vectors

non linear SVM



low dimensional space  
is non linearly separable  
Mercer's condition  
kernel trick

line  $\rightarrow$  plane  
manifold learning

high dimensional space  
linearly separable

homogeneous coordinate system

$x, y \rightarrow$

$w$

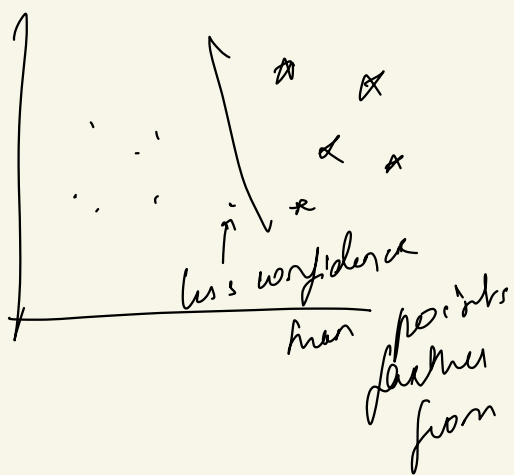
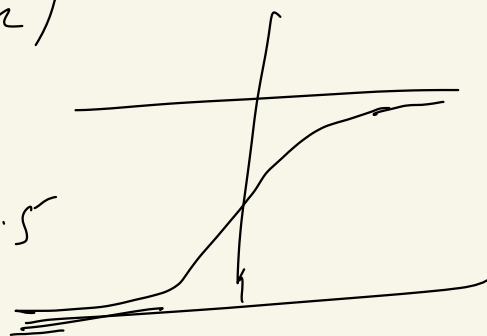
$\frac{x}{w}, \frac{y}{w}, w$

Logistic Regression:

$$P(y=1|x) = h(x) = \sigma(\beta^T x)$$

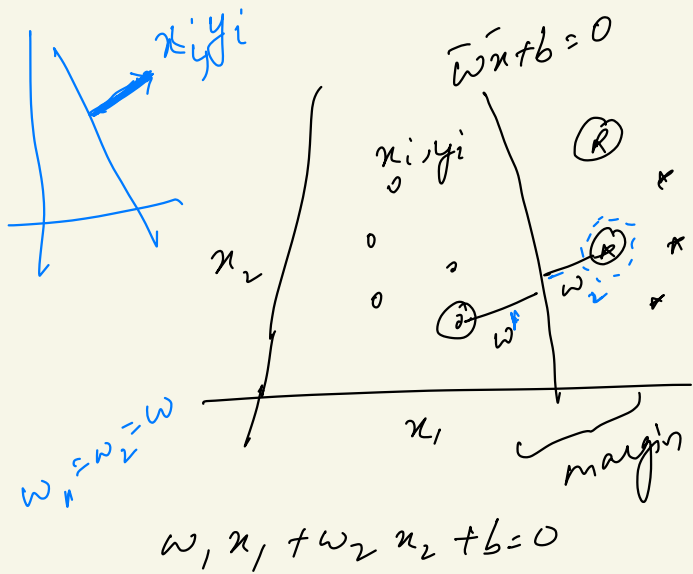
predict 1 when  $h(x) > 0.5$

0 when  $h(x) < 0.5$



large no of features  
use Bayesian Learning  
we look at all possible classifiers  
weigh them by their

aposteriori probability & combined to get the answer  
It is not computationally efficient.



Goal: margin width is highest  
& classifier has highest generalization ability  
points closest to margin: Support vectors

Distance of closest +ve = distance of closest -ve  
minimum of 2 support vectors

Functional margin: dist of  $x_i, y_i$  from decision boundary  
 $x_i, y_i$  w.r.t  $w, b$

$2w$   
= Margin

Larger functional margin more confidence to classify

$$\gamma^i = y_i (w^T x_i + b) = \text{Normal to the line}$$

$$S = \{(x_1, y_1) \dots (x_m, y_m)\}$$

$$\gamma = \min_{i=1}^m \gamma^i$$

and also depends on coefficients of line

$P = Q + \frac{w}{\|w\|}$  on coefficients of line (scaling factors)

$$\text{Line: } 2x + 3y + 1 = 0$$

Geometric margin: to get rid of scaling factors

$$\text{unit vector: } \frac{w}{\|w\|}$$

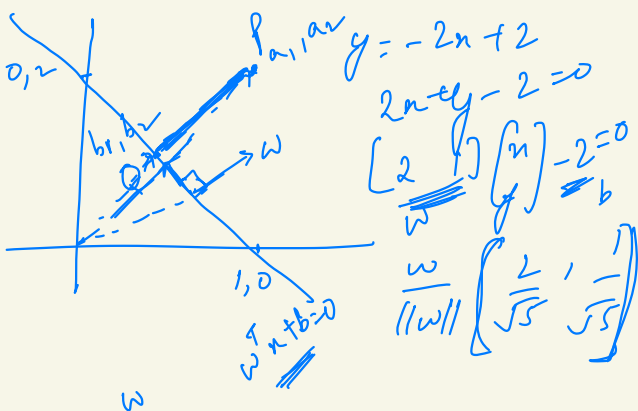
$$= \left( \frac{2}{\sqrt{13}}, \frac{3}{\sqrt{13}} \right)$$

$$P = Q + \gamma \frac{w}{\|w\|}$$

$$(a_1, a_2) = (b_1, b_2) + \gamma \frac{w}{\|w\|}$$

$$w^T (a_1, a_2) - \gamma \frac{w^T w}{\|w\|} + b = 0$$

$$\gamma = \frac{w^T (a_1, a_2) + b}{\|w\|}$$



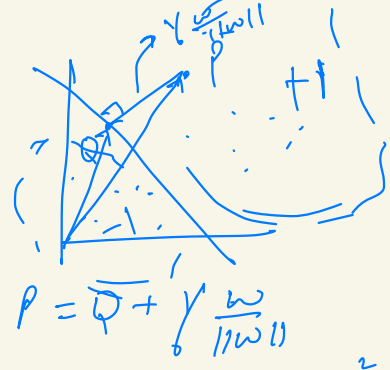
$$y = \min_{i=1, \dots, m} y_i \rightarrow \text{GM}$$

$$z = \frac{w^T (q_1, q_2) + b}{\|w\|}$$

$$f = y \frac{w^T (q_1, q_2) + b}{\|w\|}$$

let  $\|w\| = 1$  (after normalization)

$$y_i \rightarrow (GM) \quad y = y_i (w^T (a_1, a_2) + b) \quad \text{class label}$$



$$w^T P = w^T Q + y \frac{w^T w}{\|w\|}$$

$$w^T P = w^T Q + y \|w\|$$

# Maximize Margin width  
 $\rightarrow$  Maximize  $\frac{y}{\|w\|}$  subject to

$$y_i (w^T x_i + b) \geq 1 \quad \text{for } i=1, 2, \dots, m$$

$\rightarrow$  scale so that new geometric margin = 1

$\rightarrow$  Maximizing  $\frac{1}{\|w\|}$  is same as minimizing  $\|w\|$

$\rightarrow$  minimize  $w \cdot w$  subject to constraints

for all  $x_i, y_i, i=1, \dots, m$ :

$$\begin{aligned} w^T x_i + b &\geq 1 & \text{if } y_i = 1 \\ w^T x_i + b &\leq -1 & \text{if } y_i = -1 \end{aligned}$$

if  $(w, b)$  is decision boundary

$\frac{y}{\|w\|}$  is the geometric margin

proof

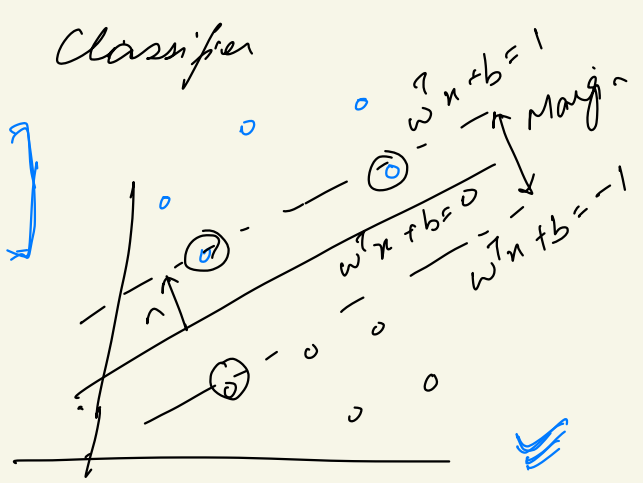
# # Large Margin Linear Classifier

Formulation:

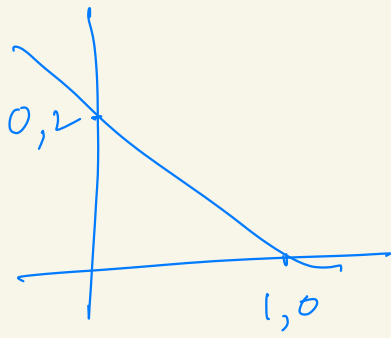
$$\text{minimize } \frac{1}{2} \|w\|^2$$

such that

$$y_i (w^T x_i + b) \geq 1$$



- Optimization problem with convex quadratic objectives &  $m$  inequality linear constraints
- Can be solved using QP
- Lagrange duality to get the optimization problem's dual form.
- Allow us to use kernels to get optimal margin classifiers to work efficiently in very high dimensional spaces.
- Allow us to derive an efficient algorithm for solving the above optimization problem that will typically do much better than generic QP software.



$$x + \frac{y}{2} = 1$$

$$2x + y = 2$$

$$2x + y - 2 = 0$$

$$w = \begin{bmatrix} 2 & 1 \end{bmatrix}$$

$$\frac{w}{\|w\|} = \begin{bmatrix} \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}$$