Shreyas Ravi

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Education

Oxford Brookes University, Oxford, UK

M.Sc. Motorsport Engineering, Merit September 2018 - September 2019

Conducted research on Driverless vehicle analysis and compared control theories for Formula Student Autonomous Vehicle as master's dissertation.

SRM University, Chennai, India

B. Tech, Automobile Engineering, 8.3 GPA July 2014 - May 2018

Designed, analyzed, and fabricated Variable Length Intake Manifold as B. tech project.



Skills

CAD: Catia V5, Solidworks CFD: Ansys fluent, star ccm+

Other: LS-dyna, Matlab/Simulink, Adams, EcoCal, EM-tune (engine calibration software), Avl vsm;

MoTec i2, Ni multisim

Projects

Driverless Formula Student Vehicle, Control strategies and event analysis

- Conducted research and analysis of autonomous electric vehicle.
- Studied various control theories and control strategies used in the Formula student and DARPA challenge for autonomous vehicle.
- for OBR electric Vehicle.
- State space models prepared for each controller design.

Variable Length Intake Manifold for small 4S IC engine

- Active length variation design to adapt the RAM supercharging between 3000-7000 RPM range.
- Rack & pinion design for length variation.
- Construction of self-designed rope dynamometer for testing and validation with 80% accuracy.

CFD analysis of wing & nose of F1 car

- Study of effect of yaw in lift and downforce generation experienced during cornering of F1 car.
- The design is as such to produce maximum downforce at 6-degree yaw angle.

IED Blast simulation on V-hull tank

- Developed V-Hull tank from the old v-hull military design material properties.
- CATIA v5 for meshing and LS-DYNA for Blast simulation.
- Oasys was used as post-processing tool.
- Model was successfully analysed for blast simulation on the undertray of military tank.

Experience

Post Graduate Mechanical Engineer

Coexlion, Bengaluru, India

Managing R&D projects.

04/2022 - PRESENT

Sr. Research & Development Mechanical Engineer

InGO Electric, Bengaluru, India

04/2021 - 03/2022

- Leading the design team of 4.
- Developing novel powertrain system with SRM Motor to effectively utilize the Low-end torque.
- Developing mathematical 1D Matlab/Simulink model of the motor-CVT system.
- Defining processes and methodologies like FMEA, DFM, GD&T, etc.
- Providing CAE team with load case development for static and fatigue loading at component and full vehicle level.
- MBD model development for the FLEE and TRON models for studying Vehicle
- Won the ASC '21 (Altair Start-up Challenge), securing 3.5lac Rs award

Team Member (AI, EV & CV)

Oxford Brookes Racing, Oxford, UK

09/2018 - 01/2020

- Being a stand-in powertrain EV lead, managed a team of five to design, fabricate and document reports for competition.
- Conceptualized and carried out the calculations for the exhaust manifold to reduce noise by 3-4 dB and improve performance using AQWT.
- Developed a lateral controller for autonomous car using Simulink and hardware requirements for testing software, being control systems engineer.

Team Leader

Developed MPC and Lateral-Stanley controller Infieon Supermileage, Chennai, India

02/2017 - 04/2018

- Managed a team of 26 People, the team won Its first award overseas for technical innovation at shell eco-marathon Asia '18.
- Introduced a variety of new sub teams to restructure the team, improving productivity with the limited resources available, resulting in the team attaining best Indian team status.

Team Driver and Powertrain Lead

Infieon Supermileage, Chennai, India

04/2015 - 02/2017

- As the combustion powertrain leader, developed a unique rear wheel hub specific for the vehicle and proposed an innovative clutch design to improve coasting distance by 56% and reduce rolling resistance.
- Converted carbureted engine to fuel injected engine, while also developing ram intake and ceramic coating, improving fuel efficiency by 16%.

SUMMER INTERN

TAFE, Chennai, India

June 2017

Studied different gear production methodologies and understanding the gear architecture of TAFE gear cum steering casing.

Publications

"MPC Controller for Autonomous Formula Student Vehicle", SAE Technical Paper 2020-01-0089, 2020, doi: 10.4271/2020-01-0089

"Design optimisation of Bicycle Wheel Hub Assembly for Automotive Applications", SAE Technical Paper 2022-01-0262, 2022, doi: 10.42771/2022-01-0262

Additional Certifications

Model-based Automotive Systems Engineering

Chalmers-edX

Modelling and simulation of system dynamics in automotive engineering