ResNet (Residual Networks) is a deep learning architecture introduced by Kaiming He et al. in 2015 through their research paper "Deep Residual Learning for Image Recognition." It was designed to tackle the vanishing gradient problem in very deep neural networks. ResNet played a crucial role in enabling deep networks with hundreds or even thousands of layers while maintaining training stability and accuracy.

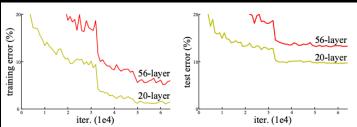
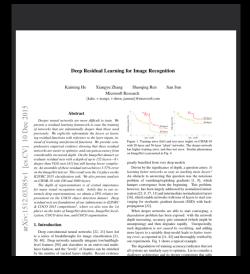
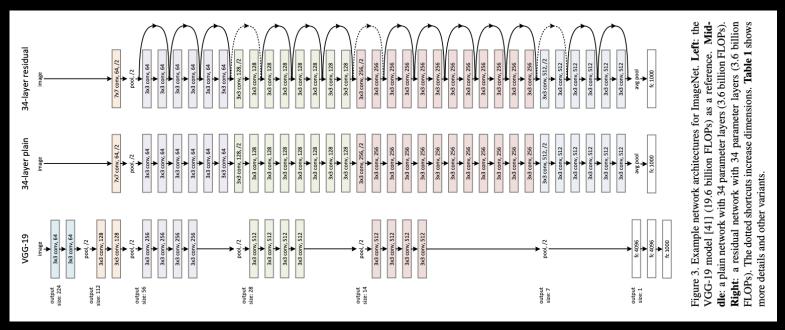


Figure 1. Training error (left) and test error (right) on CIFAR-10 with 20-layer and 56-layer "plain" networks. The deeper network has higher training error, and thus test error. Similar phenomena on ImageNet is presented in Fig. 4.

Agenda

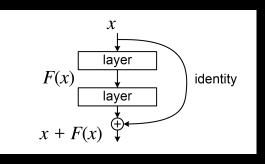
- Network Architecture
- 2. Residual Learning
- 3. Resnet Variants
- 4. Solving Vanishing Gradient Problem

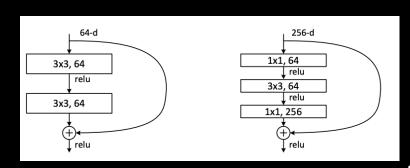




1) Frature Reuse 2) Solving VGD 3) Dequadation

Residual Blocks





x + f(x)

1) Basic Residual Block -> Resnet 34

2) Residual Bottle Block __ Resnet 50, 101,
152

Structure: - 2 ou 3 Convlayurs

BRB

Batch Noum

Relu Act

Skip Connections

RBB Studetwee: - IXI Conv 3×3 Conv

computationally
efficient

X | Conv

layer name	output size	18-layer	34-layer	50-layer	101-layer	152-layer
conv1	112×112			7×7, 64, stride 2	2	
		3×3 max pool, stride 2				
conv2_x	56×56	[3×3 64]	$\left[\begin{array}{c}3\times3,64\\3\times3,64\end{array}\right]\times3$	[1×1, 64]	[1×1, 64]	[1×1, 64]
	30×30	3×3,64 ×2		3×3, 64 ×3	3×3, 64 ×3	3×3, 64 ×3
		[3 \ 3 \ , 0 4]		[1×1, 256]	[1×1, 256]	[1×1, 256]
conv3_x		[2 \ 2 129]	$\left[\begin{array}{c} 3\times3, 128\\ 3\times3, 128 \end{array}\right] \times 4$	[1×1, 128]	[1×1, 128]	[1×1, 128]
	28×28	$\begin{bmatrix} 3\times3,128\\3\times3,128 \end{bmatrix} \times 2$		3×3, 128 ×4	3×3, 128 ×4	3×3, 128 ×8
ı'				[1×1, 512]	[1×1, 512]	[1×1, 512]
		[22 256]	$ \left[\begin{array}{c} 3\times3,256\\3\times3,256 \end{array}\right]\times6 $	[1×1, 256]	[1×1, 256]	[1×1, 256]
conv4_x	14×14	3×3,256 ×2		3×3, 256 ×6	3×3, 256 ×23	3×3, 256 ×36
!		[3×3, 230]		[1×1, 1024]	[1×1, 1024]	[1×1, 1024]
		[22 512]	$ \begin{bmatrix} 3 \times 3, 512 \\ 3 \times 3, 512 \end{bmatrix} \times 3 $	[1×1,512]	[1×1, 512]	[1×1, 512]
conv5_x	7×7	$\begin{bmatrix} 3 \times 3, 512 \\ 2 \times 2, 512 \end{bmatrix} \times 2$		3×3, 512 ×3	3×3, 512 ×3	3×3, 512 ×3
		[3×3, 312]	[3×3, 312]	L 1×1, 2048	[1×1, 2048]	[1×1, 2048]
	1×1	average pool, 1000-d fc, softmax				
FLOPs		1.8×10 ⁹	3.6×10 ⁹	3.8×10 ⁹	7.6×10 ⁹	11.3×10 ⁹

Input = (224,224,3) Reneral Structure

1) (onv + MP (7x7) 2) Multiple Residual Blocks

3) GAP 4) FC 5) Softmax

Solving VMD

1) Skip Connections

2) Identity Mapping

Risket 50

Stages	layers
Conv 1 Stage 1 Stage 2	7xx Conv, S2 + MP 3 x Bottle Neck (1x1,3x3,1x1) 4 x Bottle Neck 6 x Bottle Neck
Stage 3 Stage 4 GAP	3 x BoHle Neck
FC with	Softmax