Problem 1

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Problem

Let θ, β be 3×3 skew-symmetric matrices and σ be a 3×3 matrix. Find symmetric S, T such that:

$$(S - \theta)(T - \beta) = \sigma$$

Solution

Assuming nonsingularity whenever necessary

From
$$(S - \theta)(T - \beta) = \sigma$$
 we have $S = \theta + \sigma(T - \beta)^{-1}$

S is hermitian if and only if

$$S = \theta + \sigma (T - \beta)^{-1} = \theta^{\dagger} + ((T - \beta)^{-1})^{\dagger} \sigma^{\dagger}$$

or equivalently:

$$2\theta = (T+\beta)^{-1}\sigma^{\dagger} - \sigma(T-\beta)^{-1}$$
$$2(T+\beta)\theta(T-\beta) = \sigma^{\dagger}(T-\beta) - (T+\beta)\sigma$$
$$2T\theta T + (2\beta\theta - \sigma^{\dagger})T + T(\sigma - 2\theta\beta) - 2\beta\theta\beta + \sigma^{\dagger}\beta + \beta\sigma = 0$$

We denote
$$R = 2\theta$$
; $A = (2\theta\beta - \sigma)$; $Q = -2\beta\theta\beta + \sigma^{\dagger}\beta + \beta\sigma$

then $A^{\dagger} = (2\beta\theta - \sigma^{\dagger})$

The equation becomes

$$TRT + A^{\dagger}T - TA + Q = 0$$

with given A and skew-hermitian R, Q.

To find 1 solution we assume that
$$T$$
 is diagonal.

Denote $\mathbf{R} = \begin{pmatrix} 0 & c & b \\ -c & 0 & a \\ -b & -a & 0 \end{pmatrix}$, $\mathbf{A} = \begin{pmatrix} m_1 & m_2 & m_3 \\ m_4 & m_5 & m_6 \\ m_7 & m_8 & m_9 \end{pmatrix}$, $\mathbf{Q} = \begin{pmatrix} 0 & q_1 & q_2 \\ -q_1 & 0 & q_3 \\ -q_2 & -q_3 & 0 \end{pmatrix}$, $\mathbf{T} = \begin{pmatrix} x & 0 & 0 \\ 0 & y & 0 \\ 0 & 0 & z \end{pmatrix}$

Then we have
$$TRT = \begin{pmatrix} 0 & cxy & bxz \\ -cxy & 0 & ayz \\ -bxz & -ayz & 0 \end{pmatrix}, A^{\dagger}X = \begin{pmatrix} 0 & m_4y & m_7z \\ m_2x & 0 & m_8z \\ m_3x & m_6y & 0 \end{pmatrix}$$

Then we have the explicit form of the equation

$$cxy + m_4y - m_2x = q_1(1)$$

$$bxz + m_7z - m_3x = q_2(2)$$

$$ayz + m_8z - m_6y = q_3(3)$$

This system of equations is solved by eliminate z (by (2) and (3)) then calculate y from x (by the identity of xy). Then we are left with a quadratic equation of x.

Have x we can solve y, z.

The explicit solution is obtainable but not worth calculated by hand.