

Statistical Machine Learning

Lecture 4: Classification

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Organization - Homeworks

- Participating in the homework exercises is optional.
 - If you sign up be responsive and a team player.
 - Testate is only relevant for the corresponding homework.
 - No passing needed for participating in exam.
- Testate has to be done in person.
 - Part of the grade, i.e., same rules as for exams apply.
 - Only remote in exceptional cases (e.g., visa issues, illness) and with corresponding proof possible to do it online.
 - Sign up as group for a slot. Do not mix groups.
- Exercises are hard.
 - They also get you a bonus of up to 1.0 for the exam.
 - Partial bonus is possible.

Classification



■ What do you remember about classification?

Today's Objectives



- Make you understand how to do build a discriminative classifier!
- Covered Topics:
 - Discriminant Functions
 - Multi-Class Classification
 - Fisher Discriminate Analysis
 - Perceptrons
 - Logistic Regression

Outline



- 1. Discriminant Functions
- 2. Fisher Discriminant Analysis
- 3. Perceptron Algorithm
- 4. Logistic Regression
- 5. Wrap-Up



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Reminder of Bayesian Decision Theory

■ We want to find the a-posteriori probability (posterior) of the class C_k given the observation (feature) x

$$p(C_k \mid x) = \frac{p(x \mid C_k)p(C_k)}{p(x)} = \frac{p(x \mid C_k)p(C_k)}{\sum_j p(x \mid C_j)p(C_j)}$$

- $\blacksquare p(C_k \mid x)$ class posterior
- $p(x \mid C_k)$ class-conditional probability (likelihood)
- $p(C_k)$ class prior
- p(x) normalization term



Reminder of Bayesian Decision Theory

- Decision rule
 - Decide C_1 if $p(C_1 | x) > p(C_2 | x)$
 - Using the definition of conditional distributions, equivalent to

$$p(x \mid C_1) p(C_1) > p(x \mid C_2) p(C_2) \equiv \frac{p(x \mid C_1)}{p(x \mid C_2)} > \frac{p(C_2)}{p(C_1)}$$

A classifier obeying this rule is called a Bayes optimal classifier



Reminder of Bayesian Decision Theory

Current approach

- $\mathbf{p}\left(\mathsf{C}_{k}\mid x\right) = p\left(x\mid \mathsf{C}_{k}\right)p\left(\mathsf{C}_{k}\right)/p\left(x\right)$ (Bayes' rule)
- Model and estimate the class-conditional density $p(x \mid C_k)$ and the class prior $p(C_k)$
- Compute posterior $p(C_k \mid x)$
- Minimize the error probability by maximizing $p(C_k \mid x)$

■ New approach

- Directly encode the decision boundary
- Without modeling the densities directly
- Still minimize the error probability



Discriminant Functions

- Formulate classification using comparisons
 - Discriminant functions

$$y_1(x),\ldots,y_K(x)$$

 \blacksquare Classify x as class C_k iff

$$y_k(x) > y_j(x) \quad \forall j \neq k$$

More formally, a discriminant maps a vector x to one of the K available classes



Discriminant Functions

Example of discriminant functions from the Bayes classifier

$$y_k(x) = p(C_k | x)$$

$$y_k(x) = p(x | C_k) p(C_k)$$

$$y_k(x) = \log p(x | C_k) + \log p(C_k)$$

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Discriminant Functions

Base case with 2 classes

$$y_1(x) > y_2(x)$$

 $y_1(x) - y_2(x) > 0$
 $y(x) > 0$

Example from the Bayes classifier

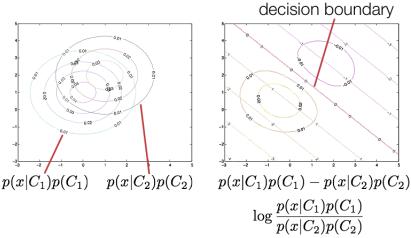
$$y(x) = p(C_1 | x) - p(C_2 | x)$$

 $y(x) = \log \frac{p(x | C_1)}{p(x | C_2)} + \log \frac{p(C_1)}{p(C_2)}$



Example - Bayes Classifier

■ Base case with 2 classes and Gaussian class-conditionals





■ Base case with 2 classes

$$y(\mathbf{x}) > 0$$
 decide class 1, otherwise class 2

- Simplest case: linear decision boundary
 - In *linear* discriminants, the decision surfaces are (hyper)planes
 - Linear Discriminant Function

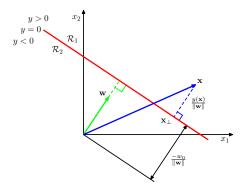
$$y(\mathbf{x}) = \mathbf{w}^\mathsf{T} \mathbf{x} + w_0$$

■ Where **w** is the normal vector and w_0 the offset

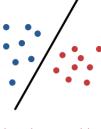


■ Illustration of the 2D case

$$y(\mathbf{x}) = \mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0, \quad \mathbf{x} = \begin{bmatrix} x_1 & x_2 \end{bmatrix}^{\mathsf{T}}$$







Linearly separable

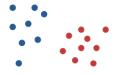


Not linearly separable



Discriminant Functions

■ Why might we want to use discriminant functions?



■ We could easily fit the class-conditionals using Gaussians and use a Bayes classifier



Discriminant Functions

■ How about now? Do these points matter for making the decision between the two classes?





Distribution-free Classifiers

We do not necessarily need to model all the details of the class-conditional distributions to come up with a good decision boundary. (The class-conditionals may have many intricacies that do not matter at the end of the day)

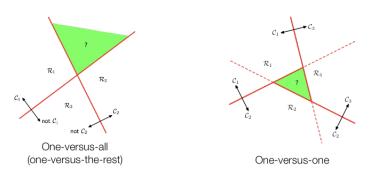


- If we can learn where to place the decision boundary directly, we can avoid some of the complexity
- It would be unwise to believe that such classifiers are inherently superior to probabilistic ones. We shall see why later...



Multi-Class Case

■ What if we constructed a multi-class classifier from several 2-class classifiers?



■ If we base our decision rule on binary decisions, this may lead to ambiguities, where we can votes for several classes such as C_1 , C_2 respectively C_1 , C_2 , C_3

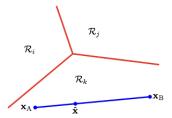


Multi-Class Case - Better Solution

Use a discriminant function to encode how strongly we believe in each class

$$y_1(x),\ldots,y_K(x)$$

■ Decision rule: Decide k if $y_k(x) > y_j(x)$ $\forall j \neq k$



■ If the discriminant functions are linear, the decision regions are connected and convex



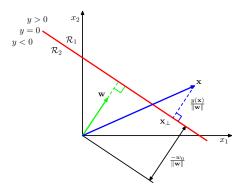
Outline

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■ Illustration of the 2D case

$$y(\mathbf{x}) = \mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0, \quad \mathbf{x} = \begin{bmatrix} x_1 & x_2 \end{bmatrix}^{\mathsf{T}}$$





■ Try to achieve a certain value of the discriminative function

$$y(\mathbf{x}) = +1 \Leftrightarrow \mathbf{x} \in C_1$$

 $y(\mathbf{x}) = -1 \Leftrightarrow \mathbf{x} \in C_2$

- lacksquare Training data inputs: $X = \left\{ oldsymbol{x}_1 \in \mathbb{R}^d, \dots, oldsymbol{x}_n
 ight\}$
- Training data labels: $Y = \{y_1 \in \{-1, +1\}, \dots, y_n\}$
- Linear Discriminant Function
 - Try to enforce $\mathbf{x}_i^\mathsf{T} \mathbf{w} + w_0 = y_i, \quad \forall i = 1, \dots, n$
 - There is one linear equation for each training data point/label pair



■ Linear system of equations

$$\mathbf{x}_i^\mathsf{T}\mathbf{w} + w_0 = y_i, \quad \forall i = 1, \dots, n$$

- lacksquare Define $\hat{m{x}}_i = \left[egin{array}{ccc} m{x}_i & 1 \end{array}
 ight]^\intercal \in \mathbb{R}^{(d+1) imes 1}, \, \hat{m{w}} = \left[egin{array}{ccc} m{w} & w_0 \end{array}
 ight]^\intercal \in \mathbb{R}^{(d+1) imes 1}$
- Rewrite the equation system

$$\hat{\boldsymbol{x}}_{i}^{\mathsf{T}}\hat{\boldsymbol{w}}=\boldsymbol{y}_{i}, \quad \forall i=1,\ldots,n$$

■ In matrix-vector notation we have

$$\hat{\mathbf{X}}^{\mathsf{T}}\hat{\mathbf{w}} = \mathbf{v}$$

$$lacksquare$$
 With $\hat{\pmb{X}} = [\hat{\pmb{x}}_1, \dots, \hat{\pmb{x}}_n] \in \mathbb{R}^{(d+1) \times n}$ and $\pmb{y} = [y_1, \dots, y_n]^{\mathsf{T}}$



$$\hat{\mathbf{X}}^{\mathsf{T}}\hat{\mathbf{w}} = \mathbf{y}$$

- An overdetermined system of equations
- There are n equations and d+1 unknowns



■ Look for the least squares solution

$$\hat{\pmb{w}}^* = \arg\min_{\hat{\pmb{w}}} \left\| \hat{\pmb{X}}^\mathsf{T} \hat{\pmb{w}} - \pmb{y} \right\|^2$$

How to solve this problem?

$$\hat{\boldsymbol{w}}^* = \arg\min_{\hat{\boldsymbol{w}}} \left(\hat{\boldsymbol{X}}^{\mathsf{T}} \hat{\boldsymbol{w}} - \boldsymbol{y} \right)^{\mathsf{T}} \left(\hat{\boldsymbol{X}}^{\mathsf{T}} \hat{\boldsymbol{w}} - \boldsymbol{y} \right)$$

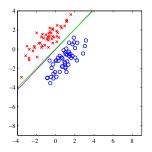
$$= \arg\min_{\hat{\boldsymbol{w}}} \hat{\boldsymbol{w}}^{\mathsf{T}} \hat{\boldsymbol{X}} \hat{\boldsymbol{X}}^{\mathsf{T}} \hat{\boldsymbol{w}} - 2 \boldsymbol{y}^{\mathsf{T}} \hat{\boldsymbol{X}}^{\mathsf{T}} \hat{\boldsymbol{w}} + \boldsymbol{y}^{\mathsf{T}} \boldsymbol{y}$$

$$\nabla_{\hat{\boldsymbol{w}}} \left(\hat{\boldsymbol{w}}^{\mathsf{T}} \hat{\boldsymbol{X}} \hat{\boldsymbol{X}}^{\mathsf{T}} \hat{\boldsymbol{w}} - 2 \boldsymbol{y}^{\mathsf{T}} \hat{\boldsymbol{X}}^{\mathsf{T}} \hat{\boldsymbol{w}} + \boldsymbol{y}^{\mathsf{T}} \boldsymbol{y} \right) = 0$$

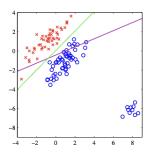
$$\implies \hat{\boldsymbol{w}} = \underbrace{\left(\hat{\boldsymbol{X}} \hat{\boldsymbol{X}}^{\mathsf{T}} \right)^{-1} \hat{\boldsymbol{X}} \boldsymbol{y}}_{\mathsf{pseudo-inverse}}$$



Problem: Least-squares is very sensitive to outliers



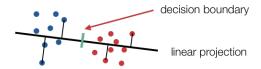
Without outliers least-squares discriminant works



With outliers least-squares discriminant breaks down



- Take a different view on linear classification
- Find a linear projection of our data and classify the projected values



- The same thing as a linear discriminant function
 - Projection: $y = \mathbf{w}^{\mathsf{T}}\mathbf{x}$
 - Checking against a threshold: $\mathbf{w}^{\mathsf{T}}\mathbf{x} \geq -w_0$ or $\mathbf{w}^{\mathsf{T}}\mathbf{x} + w_0 \geq 0$



- What is a good projection w?
 - Idea: Maximize the "distance" between the two classes to allow for a good separation
- First attempt: Maximize the distance between the class means

$$m_1 = \frac{1}{|C_1|} \sum_{i \in C_1} x_i \quad m_2 = \frac{1}{|C_2|} \sum_{i \in C_2} x_i$$

Projection of the means on the 1D line of real numbers

$$m_1 = \mathbf{w}^\mathsf{T} \mathbf{m}_1 \quad m_2 = \mathbf{w}^\mathsf{T} \mathbf{m}_2$$

■ Maximize squared distance between means

$$\max (m_1 - m_2)^2$$



Maximize squared distance between means

$$\mathbf{w}^* = \arg\max_{\mathbf{w}} (\mathbf{w}^\mathsf{T} \mathbf{m}_1 - \mathbf{w}^\mathsf{T} \mathbf{m}_2)^2$$

Can this maximization problem be solved?

- lacktriangledown Obvious problem: Grows unboundedly with the norm of $oldsymbol{w}$
- Obvious solution: Fix the norm of w

$$\max_{\boldsymbol{w}} \quad (\boldsymbol{w}^{\mathsf{T}} \boldsymbol{m}_1 - \boldsymbol{w}^{\mathsf{T}} \boldsymbol{m}_2)^2$$
s.t.
$$\|\boldsymbol{w}\|^2 = 1$$

Constrained optimization problem!



$$\max_{\boldsymbol{w}} \quad (\boldsymbol{w}^{\mathsf{T}} \boldsymbol{m}_1 - \boldsymbol{w}^{\mathsf{T}} \boldsymbol{m}_2)^2$$
 s.t. $\|\boldsymbol{w}\|^2 = 1$

Necessary conditions

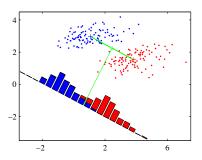
$$\nabla_{\mathbf{x}} f(\mathbf{x}) + \lambda \nabla_{\mathbf{x}} g(\mathbf{x}) = 0$$
$$2 (\mathbf{w}^{\mathsf{T}} \mathbf{m}_1 - \mathbf{w}^{\mathsf{T}} \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2) + 2\lambda \mathbf{w} = 0$$

It follows that

$$\mathbf{w} = \frac{\mathbf{m}_1 - \mathbf{m}_2}{\|\mathbf{m}_1 - \mathbf{m}_2\|}$$



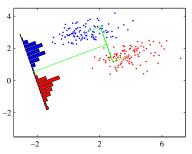
Here's what we get



Obvious problem: large class overlap



Here's what we could get



- Much better separation between classes
- How do we get this?
 - Idea: Separate the means as far as possible while minimizing the variance of each class



- Second (and final) attempt:
 - Define within-class variances:

$$s_1^2 = \sum_{n \in C_1} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_n - m_1)^2 \quad s_2^2 = \sum_{n \in C_2} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_n - m_2)^2$$

where
$$m_1 = \boldsymbol{w}^{\mathsf{T}} \boldsymbol{m}_1$$
 and $m_2 = \boldsymbol{w}^{\mathsf{T}} \boldsymbol{m}_2$

■ Fisher criterion

$$\max_{\mathbf{w}} J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2}$$



Fisher criterion

$$\max_{\mathbf{w}} J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2}$$

Rewrite the numerator

$$(m_1 - m_2)^2 = (\mathbf{w}^{\mathsf{T}} \mathbf{m}_1 - \mathbf{w}^{\mathsf{T}} \mathbf{m}_2)^2$$

$$= (\mathbf{w}^{\mathsf{T}} (\mathbf{m}_1 - \mathbf{m}_2))^2$$

$$= \mathbf{w}^{\mathsf{T}} \underbrace{(\mathbf{m}_1 - \mathbf{m}_2) (\mathbf{m}_1 - \mathbf{m}_2)^{\mathsf{T}}}_{\text{between-class covariance}} \mathbf{w}$$



■ Fisher criterion

$$\max_{\mathbf{w}} J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2}$$

Rewrite the denominator

$$s_{1}^{2} + s_{2}^{2} = \sum_{n \in C_{1}} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_{n} - \mathbf{m}_{1})^{2} + \sum_{n \in C_{2}} (\mathbf{w}^{\mathsf{T}} \mathbf{x}_{n} - \mathbf{m}_{2})^{2}$$

$$= \sum_{n \in C_{1}} (\mathbf{w}^{\mathsf{T}} (\mathbf{x}_{n} - \mathbf{m}_{1}))^{2} + \sum_{n \in C_{2}} (\mathbf{w}^{\mathsf{T}} (\mathbf{x}_{n} - \mathbf{m}_{2}))^{2}$$

$$= \sum_{n \in C_{1}} \mathbf{w}^{\mathsf{T}} (\mathbf{x}_{n} - \mathbf{m}_{1}) (\mathbf{x}_{n} - \mathbf{m}_{1})^{\mathsf{T}} \mathbf{w} + \sum_{n \in C_{2}} \mathbf{w}^{\mathsf{T}} (\mathbf{x}_{n} - \mathbf{m}_{2}) (\mathbf{x}_{n} - \mathbf{m}_{2})^{\mathsf{T}} \mathbf{w}$$

$$= \mathbf{w}^{\mathsf{T}} \left[\sum_{n \in C_{1}} (\mathbf{x}_{n} - \mathbf{m}_{1}) (\mathbf{x}_{n} - \mathbf{m}_{1})^{\mathsf{T}} + \sum_{n \in C_{2}} (\mathbf{x}_{n} - \mathbf{m}_{2}) (\mathbf{x}_{n} - \mathbf{m}_{2})^{\mathsf{T}} \right] \mathbf{w}$$

$$=: \mathbf{S}_{\mathbf{W}}$$

witnin-class covariance



Fisher criterion

$$\max_{\mathbf{w}} J(\mathbf{w}) = \frac{(m_1 - m_2)^2}{s_1^2 + s_2^2} = \frac{\mathbf{w}^{\mathsf{T}} \mathbf{S}_B \mathbf{w}}{\mathbf{w}^{\mathsf{T}} \mathbf{S}_W \mathbf{w}}$$

lacksquare Differentiating w.r.t. $oldsymbol{w}$ and setting to 0 we have

$$(\boldsymbol{w}^{\mathsf{T}}\boldsymbol{S}_{\!B}\boldsymbol{w})\,\boldsymbol{S}_{\!W}\boldsymbol{w}=(\boldsymbol{w}^{\mathsf{T}}\boldsymbol{S}_{\!W}\boldsymbol{w})\,\boldsymbol{S}_{\!B}\boldsymbol{w}$$

What can we say about $(\mathbf{w}^{\mathsf{T}}\mathbf{S}_{B}\mathbf{w})$ and $(\mathbf{w}^{\mathsf{T}}\mathbf{S}_{W}\mathbf{w})$?

■ Since $(w^{\mathsf{T}}S_{B}w)$ and $(w^{\mathsf{T}}S_{W}w)$ are scalars, we have that

$$S_W w \parallel S_B w$$

where || means collinearity.



Also, we know that

$$\mathbf{S}_{B}\mathbf{w} = (\mathbf{m}_{1} - \mathbf{m}_{2})(\mathbf{m}_{1} - \mathbf{m}_{2})^{\mathsf{T}}\mathbf{w} \implies \mathbf{S}_{B}\mathbf{w} \parallel (\mathbf{m}_{1} - \mathbf{m}_{2})$$

Hence, we have

$$S_W w \parallel (m_1 - m_2) \ w \parallel S_W^{-1} (m_1 - m_2)$$

■ Fisher's Linear Discriminant

$$\mathbf{w} \propto \mathbf{S}_{W}^{-1}(\mathbf{m}_{1}-\mathbf{m}_{2})$$



$$\mathbf{w} \propto \mathbf{S}_W^{-1} (\mathbf{m}_1 - \mathbf{m}_2)$$

- The Fisher linear discriminant only gives us a projection
 - We still need to find the threshold
 - E.g., use Bayes classifier with Gaussian class-conditionals
- Bayes optimality
 - Fisher's linear discriminant is Bayes optimal if the class-conditional distributions are equal, with diagonal covariance
- Essentially equivalent to Linear Discriminant Analysis (LDA)



- We won't go through this here, but Fisher's linear discriminant can be shown to be equivalent to a certain case of a least-squares linear classifier (see Bishop 4.1.5)
- Problem with this method: it is still very sensitive to noise!
- By The Way: This method is a true classic (it dates back to 1936)
 - Fisher, R.A., *The Use of Multiple Measurements in Taxonomic Problems*. Annals of Eugenics, 7: 179-188 (1936)

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New Strategy

■ If our classes are linearly separable, we want to make sure that we find a separating (hyper)plane





- First such algorithm we will see
 - The perceptron algorithm [Rosenblatt, 1962]





Rosenblatt [1928-1971]

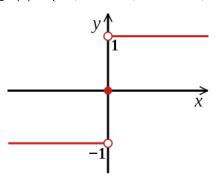


Perceptron Algorithm

■ Perceptron discriminant function

$$y(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^{\mathsf{T}}\mathbf{x} + b)$$

■ where sign $(x) = \{+1, x > 0; 0, x = 0; -1, x < 0\}$





Perceptron Algorithm

■ Perceptron Algorithm

- Initialize the weight vector \mathbf{w} and bias b
- For all pairs of data points (x_i, y_i) , where $y_i \in \{-1, +1\}$, do
 - If \mathbf{x}_i is correctly classified, i.e., $y(\mathbf{x}_i) = y_i$, do nothing
 - Else if $y_i = 1$ update the parameters with

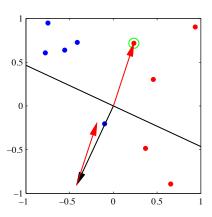
$$\boldsymbol{w} \leftarrow \boldsymbol{w} + \boldsymbol{x}_i, \quad b \leftarrow b + 1$$

■ Else if $y_i = -1$ update the parameters with

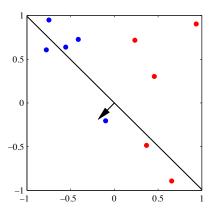
$$\boldsymbol{w} \leftarrow \boldsymbol{w} - \boldsymbol{x}_i, \quad b \leftarrow b - 1$$

■ Repeat until convergence

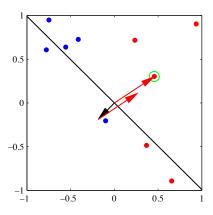




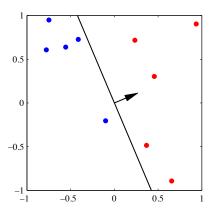














Perceptron Algorithm

- Why does this algorithm work?
- We have an optimization problem

$$\max_{\mathbf{w}} J(\mathbf{w}) = |\{\mathbf{x} \in C_1 : \mathbf{w}^\mathsf{T} \mathbf{x} > 0\}| + \dots$$
$$= \sum_{\mathbf{x} \in C_1 : \mathbf{w}^\mathsf{T} \mathbf{x} < 0} \mathbf{w}^\mathsf{T} \mathbf{x} + \dots$$

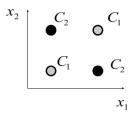
And also a gradient method

$$\frac{\partial J}{\partial \mathbf{w}} = \sum_{\mathbf{x} \in C_1: \mathbf{w}^\mathsf{T} \mathbf{x} < 0} \mathbf{x} + \dots$$



But is the Perceptron Algorithm useful?

- How often is data linearly separable?
- A simple failure example is the XOR function

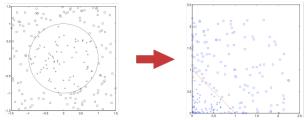


■ History: Minsky & Papert [1969] criticized the perceptron for not being able to handle this case, which halted research on this and related techniques for decades



Other Feature Spaces

- It took a long time until people had realized that there is a simple way out
- Key idea: Transform the input data nonlinearly so that the problem becomes linearly separable!



- There is an important message to get out from this
 - Create features instead of learning from raw data
 - Neural networks and kernel methods do it automatically for you

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Generative vs. Discriminative

- There are two different views to solve the classification problem
- Generative modelling
 - We model the class-conditional distributions $p(x \mid C_2)$ and $p(x \mid C_1)$
 - We classify by computing the class posterior using Bayes' rule
 - E.g.: Naive Bayes
- Discriminative modelling
 - We model the class-posterior directly, e.g. $p(C_1 \mid x)$
 - Consequence: We only care about getting the classification right, and not whether we fit the class-conditional well
 - E.g.: Logistic Regression



Probabilistic Discriminative Models

For now, we will write the class posterior using Bayes' rule

$$p(C_{1} \mid \mathbf{x}) = \frac{p(\mathbf{x} \mid C_{1}) p(C_{1})}{p(\mathbf{x})} = \frac{p(\mathbf{x} \mid C_{1}) p(C_{1})}{\sum_{i} p(\mathbf{x}, C_{i})}$$

$$= \frac{p(\mathbf{x} \mid C_{1}) p(C_{1})}{\sum_{i} p(\mathbf{x} \mid C_{i}) p(C_{i})}$$

$$= \frac{p(\mathbf{x} \mid C_{1}) p(C_{1})}{p(\mathbf{x} \mid C_{1}) p(C_{1}) + p(\mathbf{x} \mid C_{2}) p(C_{2})}$$

$$= \frac{1}{1 + p(\mathbf{x} \mid C_{2}) p(C_{2}) / (p(\mathbf{x} \mid C_{1}) p(C_{1}))}$$

$$= \frac{1}{1 + \exp(-a)} = \sigma(a) \rightarrow \text{logistic sigmoid function}$$

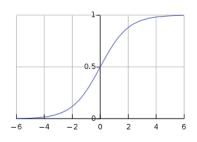
with
$$a = \log \frac{p(\mathbf{x}|C_1)p(C_1)}{p(\mathbf{x}|C_2)p(C_2)}$$

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Sigmoid

■ Logistic / Sigmoid function

$$\sigma\left(a\right) = \frac{1}{1 + \exp\left(-a\right)}$$



[Wikipedia]

- Sigmoid: 'S-shaped'
- Squashes real numbers into the [0, 1] interval



Probabilistic Discriminative Models

Class posterior

$$p(C_1 \mid \mathbf{x}) = \sigma(a)$$
 with $a = \log \frac{p(\mathbf{x} \mid C_1) p(C_1)}{p(\mathbf{x} \mid C_2) p(C_2)}$

- Logistic regression
 - \blacksquare Assume that a is given by a linear discriminant function

$$p(C_1 \mid \boldsymbol{x}) = \sigma(\boldsymbol{w}^{\mathsf{T}}\boldsymbol{x} + w_0)$$

- Find **w** and w_0 so that the class-posterior is modeled best
- When is this an appropriate assumption?
 - When the class conditionals are Gaussians with equal covariance
 - But also for a number of other distributions
 - Some independence of the form of the class-conditionals



Logistic Regression

Model the class posterior as

$$p(C_1 \mid \boldsymbol{x}) = \sigma(\boldsymbol{w}^{\mathsf{T}}\boldsymbol{x} + w_0)$$

- Maximize the likelihood
 - Data (as always) is i.i.d. and define $y_i = \begin{cases} 0 & \mathbf{x}_i \text{ belongs to } C_1 \\ 1 & \mathbf{x}_i \text{ belongs to } C_2 \end{cases}$

$$p\left(Y \mid X; \boldsymbol{w}, w_{0}\right) = \prod_{i=1}^{N} p\left(y_{i} \mid \boldsymbol{x}_{i}; \boldsymbol{w}, w_{0}\right)$$

$$= \prod_{i=1}^{N} p\left(C_{1} \mid \boldsymbol{x}_{i}; \boldsymbol{w}, w_{0}\right)^{1-y_{i}} p\left(C_{2} \mid \boldsymbol{x}_{i}; \boldsymbol{w}, w_{0}\right)^{y_{i}}$$

$$= \prod_{i=1}^{N} \sigma(\boldsymbol{w}^{\mathsf{T}} \boldsymbol{x}_{i} + w_{0})^{1-y_{i}} \left(1 - \sigma(\boldsymbol{w}^{\mathsf{T}} \boldsymbol{x}_{i} + w_{0})\right)^{y_{i}}$$



Logistic Regression

- We won't do the derivation here (see Bishop 4.3), but basically you can apply the logarithm to $p\left(Y \mid X; \boldsymbol{w}, w_0\right)$ and do gradient descent
- Later, we will turn to a very different interpretation of this:
 - Logistic regression as a neural network

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Outline

- 1. Discriminant Functions
- 2. Fisher Discriminant Analysis
- 3. Perceptron Algorithm
- 4. Logistic Regression
- 5. Wrap-Up



5. Wrap-Up

You know now:

- What a Bayesian Optimal Classifier is
- What a discriminant function is
- How to formalize (with intuition and mathematically) the classification problem as linearly-separable
- How to compute the least squares solution for classification and why it fails
- What Fisher's Linear Discriminant is and how it differs from least-squares
- What the perceptron is, why it fails in the XOR problem and how to overcome it with feature spaces
- The difference between Generative and Discriminative modelling
- What logistic regression is



Self-Test Questions

- How do we get from Bayesian optimal decisions to discriminant functions?
- How to derive a discriminant function from a probability distribution?
- How to deal with more than two classes?
- What does linearly-separable mean?
- What is Fisher discriminant analysis? How does it relate to regression?
- Is Fisher's linear discriminant Bayes optimal?
- What are perceptrons? How can we train them?
- What is logistic regression? How to derive the parameter update rule?

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Homework

- To get a deeper understanding towards today's topics
 - Bishop, Chapter 4
 - The Elements of Statistical Learning, Chapter 3