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# Ravindra Bisram
# Deep Learning Homework 4
import pickle
import sys
import os
import numpy as np
import tensorflow as tf
from tensorflow.keras.layers import Conv2D, Dropout, MaxPool2D,
Flatten, Add, Dense, Activation, BatchNormalization, Lambda, ReLU,
PReLU
from tensorflow.keras.layers import Conv2D, AveragePooling2D,
MaxPooling2D, Flatten, Input, concatenate, ZeroPadding2D, LeakyReLU,
GlobalAveragePooling2D
from tensorflow.keras.models import Model, Sequential
from tensorflow.keras.regularizers import 12
from tensorflow.keras.optimizers import Adam, SGD, RMSprop
from tensorflow.keras.callbacks import ReduceLROnPlateau,
ModelCheckpoint, LearningRateScheduler
from sklearn.model selection import train test split
from keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.metrics import TopKCategoricalAccuracy
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os.environ['TF_CPP_MIN_LOG_LEVEL'] = '3'

The CIFAR10 and CIFAR100 datasets were downloaded through the official website. Each training batch for CIFAR10 was unpickled and then appended to each other to create one large training set. The images were preprocessed to convert the initial row vector to shape (32, 32, 3) through reshaping and transposing. The class output data was one hot encoded. My preliminary architecture recycled my model for the MNIST dataset, with an alteration for the input size. This resulted in a test accuracy of 67%. The second architecture I tried was a VGG with fractional max pooling, based on a paper by Benjamin Graham. While this definitely outperformed the previous model, the computational time and rate at which the model learned seemed to slow, and ultimately converged around 86% accuracy. At this point I tried playing around with a GoogleNet implementation, which was effective, but still very slow to train. I continued to roughly follow the VGG type CNN architecture, opting to make it shallower and introducing data augmentation, learning rate decay, variable learning rate, and early stopping. All of these factors combinedresulted in a network that had very fast steps and converged well after only a hundred or so epochs. I setteld on this architecture since it had reached an accuracy of 90% for CIFAR10, and over 95% for CIFAR100. As instructed in office hours, I also implemented a residual network, and found that this model got me similar results in the 88-90% range for CIFAR10. To keep my submission short, I have only included the model I settled on (which I termed ravnet) and the ResNet, though I coded up many different models in a similar way.

I would like to give shoutouts to Bob for the tip to try and use

GoogleNet, and Joey Berkowitz for introducing me to early stopping. Danny Hong also helped me find good dropout percentages for the raynet.

Misc attempts at improvement:

- I tried reducing training time by using only one of the 5 training batches and doubling the batch size to 512, but the tradeoff with accuracy was way too high.
- I played around with different optimization functions, including SGD with momentum, and RMS prop.
- Using ravnet with no dropout in the initial layers worked great for CIFAR10, but was not useful for CIFAR100.
- I played around with model checkpoints to save progress, but ended up never actually reloading weights.
- Played around with different kernel initializers.

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Thus concludes my voyage for hw4.
# Fractional max pooling
# - https://arxiv.org/abs/1412.6071
https://github.com/laplacetw/vgg-like-cifar10/blob/master/fmp cifar10.
py
# https://www.binarystudy.com/2021/09/how-to-load-preprocess-
visualize-CIFAR-10-and-CIFAR-100.html#routine
BTEST = '../data/test batch'
meta_file = '../CIFAR10-data/batches.meta'
NUM TRAINING BATCHES = 5
BATCH SIZE = 128 #128
LAMBDA = 1e-5
EPOCHS = 150
IMG SIDE LEN = 32
LR = 5e-3
DATASET = "CIFAR10"
MODEL = "resnet34"
COARSE = False
def unpickle(file):
    with open(file, 'rb') as fo:
        u = pickle._Unpickler( fo )
        u.encoding = 'latin1'
        dict = u.load()
    return dict
def load training data():
    # The whole data batch 1 has 10,000 images. And each image is a 1-
D array having 3,072 entries.
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First 1024 entries for Red, the next 1024 entries for Green and

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last 1024 entries for Blue channels.
    print("Loading Data:")
    features, classes = np.empty((0,32,32,3)), np.empty((0,10))
    for i in range(NUM TRAINING BATCHES):
        print(f"Batch {i+1}")
        batch_path = f'../data/data_batch_{i+1}'
        x, y = reshape features(batch path)
        features = np.append(features, x, axis=0)
        classes = np.append(classes, y, axis=0)
    return features, classes
def reshape features(feat path, CIFAR100=False):
    labels = ('coarse labels' if COARSE else 'fine labels') if
CIFAR100 else 'labels'
    unpickled data = unpickle(feat path)
(unpickled_data['data'].reshape(len(unpickled_data['data']),3,32,32).t
ranspose(0,2,3,1) / 255,
            tf.keras.utils.to categorical(unpickled data[labels]))
def frac max pool(x):
    return tf.nn.fractional max pool(x, [1.0, 1.41, 1.41, 1.0],
pseudo random=True, overlapping=True)[0]
def poly decay(epoch):
  maxEpochs = EPOCHS
  baseLR = LR
  power = 1.0
  alpha = baseLR * (1 - (epoch / float(maxEpochs))) ** power
  return alpha
datagen = ImageDataGenerator(
    rotation range=15,
    horizontal flip=True,
    width shift range=0.1,
    height shift range=0.1
)
stopping = tf.keras.callbacks.EarlyStopping(
          monitor="val accuracy",
          min_delta=0,
          patience=25,
          verbose=1,
          mode="max",
          baseline=None,
          restore best weights=True)
def normalize_x_data(x_train, x_test):
    eps = 1e-7
    mean = np.mean(x train,axis = (0, 1, 2, 3))
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std = np.std(x train,axis = (0, 1, 2, 3))
    x train = (x train - mean)/(std + eps)
    x_{test} = (x_{test} - mean)/(std + eps)
    return x train, x test
class Data10(object):
    def init (self):
        self.x train, self.y train = load training data()
        self.x test, self.y test = reshape features(BTEST)
        self.x train, self.x test = normalize x data(self.x train,
self.x test)
        self.x train, self.x val, self.y train, self.y val =
train test split(self.x train, self.y train, test size=0.2,
random state=31415)
class Data100(object):
    def init (self):
      self.x train, self.y train = reshape features('../data/train',
CIFAR100=True)
      self.x test, self.y test = reshape features('../data/test',
CIFAR100=True)
      self.x train, self.x val, self.y train, self.y val =
train_test_split(self.x_train, self.y_train, test_size=0.2,
random state=31415)
def double conv module(input, num filters, activation, kern reg,
dropout, padding="same"):
    input = Conv2D(filters = num_filters, kernel_size = (3, 3),
activation = activation, padding = padding, kernel regularizer =
kern reg)(input)
    input = BatchNormalization(axis=-1)(input)
    input = Conv2D(filters = num filters, kernel size = (3, 3),
activation = activation, padding = padding, kernel regularizer =
kern reg)(input)
    input = BatchNormalization(axis=-1)(input)
    input = MaxPooling2D(pool size = (2, 2))(input)
    input = Dropout(dropout)(input)
    return input
# Primary model I was going to submit until Monday office hours resnet
suggestion
def rav model(width, height, depth, classes):
    inputShape=(height, width, depth)
    weight decay = 0.001
    inputs = Input(shape=inputShape)
    KR = None #12(weight decay)
    x = double conv module(inputs, 32, activation='relu', kern reg=KR,
dropout = 0.1, padding='same')
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x = double conv module(x, 64, activation='relu', kern reg=KR,
dropout = 0.2, padding='same')
    x = double_conv_module(x, 128, activation='relu', kern reg=KR,
dropout = 0.3, padding='same')
    x = double conv module(x, 128, activation='relu', kern reg=KR,
dropout = 0.4, padding='same')
    x = Flatten()(x)
    x = Dense(512, activation='relu', kernel regularizer=None)(x)
    x = BatchNormalization(axis=-1)(x)
    x = Dropout(0.5)(x)
    x = Dense(classes)(x)
    x = Activation("softmax")(x)
    model = Model(inputs, x, name="rav net")
    return model
# Materials Referenced for Residual Implementation:
# https://www.analyticsvidhya.com/blog/2021/08/how-to-code-your-
resnet-from-scratch-in-tensorflow/
# https://towardsdatascience.com/building-a-resnet-in-keras-
e8f1322a49ba
# https://machinelearningknowledge.ai/googlenet-architecture-
implementation-in-keras-with-cifar-10-dataset/
# https://sebastianwallkoetter.wordpress.com/2018/04/08/layered-
layers-residual-blocks-in-the-sequential-keras-api/
https://github.com/Adeel-Intizar/CIFAR-10-State-of-the-art-Model/blob/
master/CIFAR-10%20Best.ipynb
def identity block(x, filter):
    # Maintain the input for the skip connection
    x \text{ skip} = x
    x = Conv2D(filter, (3,3), padding = 'same')(x)
    x = BatchNormalization(axis=3)(x)
    x = Activation('relu')(x)
    x = Conv2D(filter, (3,3), padding = 'same')(x)
    x = BatchNormalization(axis=3)(x)
    # Residual part --> add the input to the output
    x = Add()([x, x skip])
    x = Activation('relu')(x)
    return x
def convolutional_block(x, filter):
    x \text{ skip} = x
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x = Conv2D(filter, (3,3), padding = 'same', strides = (2,2))(x)
    x = BatchNormalization(axis=3)(x)
    x = Activation('relu')(x)
    x = Conv2D(filter, (3,3), padding = 'same')(x)
    x = BatchNormalization(axis=3)(x)
    # Process the residual with a (1,1) convolution
    x \text{ skip} = \text{Conv2D}(\text{filter}, (1,1), \text{ strides} = (2,2))(x \text{ skip})
    x = Add()([x, x skip])
    x = Activation('relu')(x)
    return x
def ResNet(shape = (32, 32, 3), classes = 10):
    inputs = Input(shape)
    x = ZeroPadding2D((3, 3))(inputs)
    # Initial Conv layer and Maxpooling
    x = Conv2D(64, kernel size=7, strides=2, padding='same')(x)
    x = BatchNormalization()(x)
    x = Activation('relu')(x)
    x = MaxPool2D(pool size=3, strides=2, padding='same')(x)
    # Size of sub-blocks and initial filter size
    block layers = [3, 4, 6, 3]
    filter size = 64
    # Resnet Blocks
    for i in range (4):
        if i == 0:
            for j in range(block layers[i]):
                x = identity block(x, filter size)
        else:
            # One Residual/Convolutional Block followed by Identity
blocks
            filter size = filter size*2 # Filter size increases by
factors of 2
            x = convolutional_block(x, filter_size)
            for j in range(block layers[i] - 1):
                x = identity_block(x, filter_size)
    # Recycle the dense layers from my previous model
    x = AveragePooling2D((2,2), padding = 'same')(x)
    x = Flatten()(x)
    x = Dense(512, activation = 'relu')(x)
    x = Dense(classes)(x)
    x = Activation("softmax")(x)
    model = Model(inputs = inputs, outputs = x, name = "ResNet")
    return model
```

```
if __name__ == "__main_ ":
  if DATASET == 'CIFAR10':
    data = Data10()
    NUM CLASSES = 10
  else:
    data = Data100()
    NUM CLASSES = 20 if COARSE else 100
  x train, y train = data.x train, data.y train
  x test, y test = data.x test, data.y test
  x val, y val = data.x val, data.y val
  lr scheduler = LearningRateScheduler(poly decay)
  variable learning rate = ReduceLROnPlateau(monitor='val loss',
factor = 0.2, patience = 2)
  if MODEL == "ravnet":
    model = rav model(width=32, height=32, depth=3,
classes=NUM CLASSES)
  elif MODEL == "resnet":
    model = ResNet(classes=NUM CLASSES)
  opt=Adam(learning rate=0.001,decay=0, beta 1=0.9, beta 2=0.999,
epsilon=1e-08)
  if DATASET == "CIFAR10":
    model.compile(loss=tf.keras.losses.categorical crossentropy,
metrics=['accuracy'],optimizer=opt)
  else:
    model.compile(loss=tf.keras.losses.categorical crossentropy,
metrics=[TopKCategoricalAccuracy(k = 5)],optimizer=opt)
  model.summary()
  history=model.fit(datagen.flow(x train, y train,
batch size=BATCH SIZE),
                    batch size=BATCH SIZE,
                    epochs=EPOCHS,
                    callbacks=[variable learning rate, lr scheduler,
stopping],
                    validation data=(x val, y val),
                    verbose=1,
                    steps per epoch = len(x train) // BATCH SIZE)
  score = model.evaluate(x test, y test, verbose=0)
  print('Test loss:', score[0])
  print('Test accuracy:', score[1])
```

CIFAR 10 Dataset:

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Total params: 854,826 Trainable params: 852,394 Non-trainable params: 2,432

Epoch 1/200 Epoch 2/200 Epoch 3/200 Epoch 4/200 Epoch 5/200 Epoch 190/200 312/312 [============] - 20s 64ms/step - loss: 0.1220 - accuracy: 0.9576 - val_loss: 0.3223 - val_accuracy: 0.9089 - lr: 2.7500e-04 Epoch 191/200 Epoch 192/200 312/312 [============] - 20s 65ms/step - loss: 0.1201 - accuracy: 0.9581 - val_loss: 0.3213 - val_accuracy: 0.9105 - lr: 2.2500e-04 Epoch 193/200 312/312 [=============] - 20s 64ms/step - loss: 0.1203 - accuracy: 0.9572 - val_loss: 0.3184 - val_accuracy: 0.9124 - lr: 4.0000e-05 Epoch 194/200 312/312 [============] - 20s 64ms/step - loss: 0.1176 - accuracy: 0.9584 - val_loss: 0.3199 - val_accuracy: 0.9126 - lr: 1.7500e-04 Epoch 195/200 312/312 [============] - 20s 65ms/step - loss: 0.1194 - accuracy: 0.9573 - val_loss: 0.3206 - val_accuracy: 0.9120 - lr: 3.0000e-05 Epoch 196/200 Epoch 197/200 312/312 [=========] - 20s 64ms/step - loss: 0.1182 - accuracy: 0.9585 - val loss: 0.3207 - val accuracy: 0.9120 - lr: 2.0000e-05 Epoch 198/200 Epoch 199/200 Epoch 200/200 Test loss: 0.3363804817199707 Test accuracy: 0.907800018787384

CIFAR 100: (ignore the warnings, I accidentally left the same early stopping metric I used for my CIFAR10 run, and by the time I realized I was too deep into the run).

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_____
Total params: 859,956
Trainable params: 857,524
Non-trainable params: 2,432
Epoch 1/200
WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
accuracy: 0.4984 - 1r: 0.0050
Epoch 2/200
WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
al_loss,val_top_k_categorical_accuracy,lr
312/312 [=============] - 19s 62ms/step - loss: 2.5115 - top_k_categorical_accuracy: 0.6461 - val_loss: 2.6826 - val_top_k_categorical
_accuracy: 0.6061 - lr: 0.0050
Epoch 3/200
312/312 [====
            WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
_accuracy: 0.7198 - lr: 0.0049
Epoch 4/200
          312/312 [====
WARNING: tensorflow: Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss, top_k_categorical_accuracy, v
al_loss,val_top_k_categorical_accuracy,lr
312/312 [============] - 20s 65ms/step - loss: 2.2736 - top k categorical accuracy: 0.7196 - val loss: 2.6097 - val top k categorical
_accuracy: 0.6179 - lr: 0.0049
WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
al_loss,val_top_k_categorical_accuracy,lr
312/312 [===========] - 19s 61ms/step - loss: 0.4372 - top k categorical accuracy: 0.9890 - val loss: 0.9320 - val top k categorical
 accuracy: 0.9544 - lr: 3.0000e-05
Epoch 196/200
312/312 [=============== ] - ETA: 0s - loss: 0.4342 - top k categorical accuracy: 0.9891
WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
al_loss,val_top_k_categorical_accuracy,lr
               =========] - 19s 61ms/step - loss: 0.4342 - top_k_categorical_accuracy: 0.9891 - val_loss: 0.9339 - val_top_k_categorical
 accuracy: 0.9538 - 1r: 1.2500e-04
Epoch 197/200
WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
 al_loss,val_top_k_categorical_accuracy,lr
accuracy: 0.9540 - lr: 2.0000e-05
Fnoch 198/200
312/312 [=====
            WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
al_loss,val_top_k_categorical_accuracy,lr
                 accuracy: 0.9549 - 1r: 7.5000e-05
 Epoch 199/200
WARNING:tensorflow:Early stopping conditioned on metric 'val_accuracy' which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
al_loss,val_top_k_categorical_accuracy,lr
               ========] - 20s 64ms/step - loss: 0.4313 - top_k_categorical_accuracy: 0.9891 - val_loss: 0.9339 - val_top_k_categorical
312/312 [=====
 _accuracy: 0.9547 - lr: 1.0000e-05
Epoch 200/200
 312/312 [=======================] - ETA: 0s - loss: 0.4249 - top_k_categorical_accuracy: 0.9891
WARNING:tensorflow:Early stopping conditioned on metric `val_accuracy` which is not available. Available metrics are: loss,top_k_categorical_accuracy,v
al_loss,val_top_k_categorical_accuracy,lr
312/312 [====
                             - 19s 61ms/step - loss: 0.4249 - top k_categorical_accuracy: 0.9891 - val_loss: 0.9339 - val_top_k_categorical
 _accuracy: 0.9547 - 1r: 2.5000e-05
Test loss: 0.9218876957893372
Test accuracy: 0.9524000287055969
```