

CO224 – LAB5

PART-5

E/19/105, E/19/106

GROUP - 19

We have extended our CPU with sll, srl, sra, ror, bne instructions as extra instructions.

1. sll & srl instructions

Opcodes

00001000	:	sll
00001001	:	srl

ALU module

For these two instructions a separate module named as LOGICALSHIFT is implemented inside ALU. According to a given control signal (SHIFTSIDE) the ALU performs logical right shift or logical left shift by the given amount (SHIFTAMOUNT).

```
//Logical Shift module
module LOGICALSHIFT (OPERAND, SHIFTAMOUNT, SHIFTSIDE, RESULT);
    //Port declarations
    input [7:0] OPERAND, SHIFTAMOUNT;
    input SHIFTSIDE;                //If 0 leftshift, if 1 rightshift
    output reg [7:0] RESULT;
    reg [7:0] tempOperand;          //temporary register
    reg [6:0] temp;                 //temporary register
    integer i;                     //for looping

    always @(SHIFTAMOUNT, OPERAND) begin
        #1
        tempOperand = OPERAND;
        for (i = 1; i<=SHIFTAMOUNT; i++ ) begin
            if (SHIFTSIDE == 0) begin //Leftshift operation
                temp = tempOperand[6:0];
                RESULT[7:1] = temp;
                RESULT[0] = 1'b0;
                tempOperand = RESULT;
            end else begin           //Rightshift operation
                temp = tempOperand[7:1];
                RESULT[6:0] = temp;
                RESULT[7] = 1'b0;
                tempOperand = RESULT;
            end
        end
    end
endmodule
```

Timing Diagram

PC Update	Instruction Memory Read		Register Read	ALU
#1	#2		#2	#1
	PC+4 Adder		Decode	
	#1		#1	
Register Write				
#1				

Changes in Datapath & Control

For this an additional control signal (isRIGHTSHIFT) is added. The value of this control signal is assigned for sll instruction to zero and for srl instruction to one.

2. sra instruction

Opcode

00001010

ALU module

For this instruction a separate module named as ARITHMETICSHIFT is implemented inside ALU. According to the given amount (SHIFTAMOUNT) the ALU performs arithmetic right shift.

```
//Arithmetic Shift module
module ARITHMETICSHIFT(OPERAND, SHIFTAMOUNT, RESULT);
    //Port declarations
    input [7:0] OPERAND, SHIFTAMOUNT;
    output reg [7:0] RESULT;
    reg [7:0] tempOperand;           //temporary register
    reg [6:0] temp;                  //temporary register
    integer j;                       //for looping

    always @(OPERAND, SHIFTAMOUNT) begin
        #1
        tempOperand = OPERAND;
        for (j = 1; j<=SHIFTAMOUNT ; j++) begin
            if (tempOperand[7]==1'b0) begin //If MSB is 0 add leading
zeros
                temp = tempOperand[7:1];
                RESULT[6:0] = temp;
                RESULT[7] = 1'b0;
                tempOperand = RESULT;
            end
        end
    end
endmodule
```

```

        end else begin                                //If MSB is 1 add leading ones
            temp = tempOperand[7:1];
            RESULT[6:0] = temp;
            RESULT[7] = 1'b1;
            tempOperand = RESULT;
        end
    end
end
endmodule

```

Timing Diagram

PC Update #1	Instruction Memory Read #2		Register Read #2	ALU #1	
	PC+4 Adder #1		Decode #1		
Register Write #1					

Changes in Datapath & Control

No additional control signals for this module.

3. bne instruction

Opcode

00001011

ALU module

No changes in ALU module. It uses only the ZERO indicator (output of ALU module) for comparing.

Timing Diagram

PC Update #1	Instruction Memory Read #2		Register Read #2	2's Comp #1	ALU #2
	PC+4 Adder #1		Branch/Jump Target Adder #2		
			Decode #1		

Changes in Datapath & Control

An additional control signal (isBNE) is added to the CPU.

This control signal is then passed to mux_pc mux to select whether the instruction need to be jumped or not.

```
//MUX module for jump and branch instructions
module mux_pc(DATA1,DATA2,JUMPSELECT,BEQSELECT,BNESELECT,ZEROSELECT,OUTPUT);
    //Declaration of ports
    input [31:0] DATA1,DATA2;
    input JUMPSELECT, BEQSELECT, BNESELECT, ZEROSELECT;
    output reg [31:0] OUTPUT;

    //direct on of the data to the output according to the select value
    always@(*) begin
        if (JUMPSELECT) begin
            OUTPUT = DATA1; //If the instruction is j,
            assign the NextPC value to the target address
        end else if (BEQSELECT && ZEROSELECT) begin //If the instruction is
            beq and equal condition is satisfied,
            OUTPUT = DATA1; // assign the NextPC value
            to the target address
        end else if (BNESELECT && !ZEROSELECT) begin //If the instruction
            is bne and notequal condition is satisfied
            OUTPUT = DATA1; // assign the NextPC
            value to the target address
        end else begin
            OUTPUT = DATA2; //Else nextPC value is
            increased by 4 from currentPC value
        end
    end
end
endmodule
```

4. ror instruction

Opcode

00001100

ALU module

An additional module named as ROTATE has been implemented inside the ALU module.

According to the given amount (ROTATEAMOUNT) the input number is rotated right side.

```

//Rotate right module
module ROTATE(OPERAND, ROTATEAMOUNT, RESULT);
    input [7:0] OPERAND, ROTATEAMOUNT;
    output reg [7:0] RESULT;
    reg tempLSB;                //temporary register
    reg [6:0] temp;              //temporary register
    reg [7:0] tempOperand;       //temporary register
    integer k;                   //for looping

    always @(OPERAND, ROTATEAMOUNT) begin
        #1
        tempOperand = OPERAND;
        tempLSB = OPERAND[0];    //Save the LSB

        //ROtate through a loop
        for ( k=1 ; k<=ROTATEAMOUNT ; k++) begin
            temp = tempOperand[7:1];
            RESULT[6:0] = temp;
            RESULT[7] = tempLSB;
            tempOperand = RESULT;
            tempLSB = RESULT[0];
        end
    end
end
endmodule

```

Timing Diagram

PC Update	Instruction Memory Read		Register Read	ALU
#1	#2		#2	#1
	PC+4 Adder		Decode	
	#1		#1	
Register Write				
#1				

Changes in Datapath & Control

No additional control signals for this module.