



Mid semester presentation for Master Thesis Project on

CONTACTLESS RADAR-BASED VITAL SIGN MONITORING

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Motivation

Contactless radar-based vital sign monitoring project can fulfill the need for remote, and continuous monitoring of a person's vital signs. Here are several compelling reasons for pursuing such a project:

- ▶ Patient Comfort and Safety
- ▶ Continuous Monitoring
- ▶ Reduced Healthcare Costs
- ▶ Home Healthcare



Fig.1.Current model to monitor vital sign

Objective

- ▶ Design a Radar system that can measure the breathe rate of single person without any contact.
- ▶ Design a Radar system that can measure the breathe rate of multiple person without any contact.
- ▶ Design a Radar system that can measure the breathe rate of new born babies without any contact.

Literature

| Title | Applications | Publication year |
|--|-----------------------------|------------------|
| Implementation of FMCW Radar by Using SDR S. Kaya, A. Ç. Yapıcı, B. Tıbıkoğlu and Ş. O. Yazıcı, "Implementation of FMCW Radar by Using SDR," 2021 <i>13th International Conference on Electrical and Electronics Engineering (ELECO)</i> , Bursa, Turkey, 2021, pp. 234-238. | Range detection of a object | 2021 |
| A Simple Radar Based on USRP Software Defined Radio B. Bleszynski, "A simple radar based on USRP software defined radio," 2017 <i>Signal Processing Symposium (SPSymposium)</i> , Jachranka, Poland, 2017, pp. 1-4. | Range detection of a object | 2017 |
| Stationary and Moving Targets Detection on FMCW Radar Using GNU Radio-Based Software Defined Radio S. Aulia, A. B. Suksmono and A. Munir, "Stationary and moving targets detection on FMCW radar using GNU radio-based software defined radio," 2015 <i>International Symposium on Intelligent Signal Processing and Communication Systems (ISPACS)</i> , Nusa Dua Bali, Indonesia, 2015, pp. 468-473. | Range detection of a object | 2015 |

Mathematical Modelling

- Propagation Delay

$$\tau = \frac{2R}{c} \dots\dots(1)$$

Where

R-Range of Object

c-Speed of light

- Range Resolution

$$\Delta R = \frac{c}{2B} \dots(2)$$

Where

B- Bandwidth

- Relation between range(R) and beat frequency (Δf)

$$R = \frac{c \cdot \Delta f \cdot T_s}{2B} \dots\dots\dots(3)$$

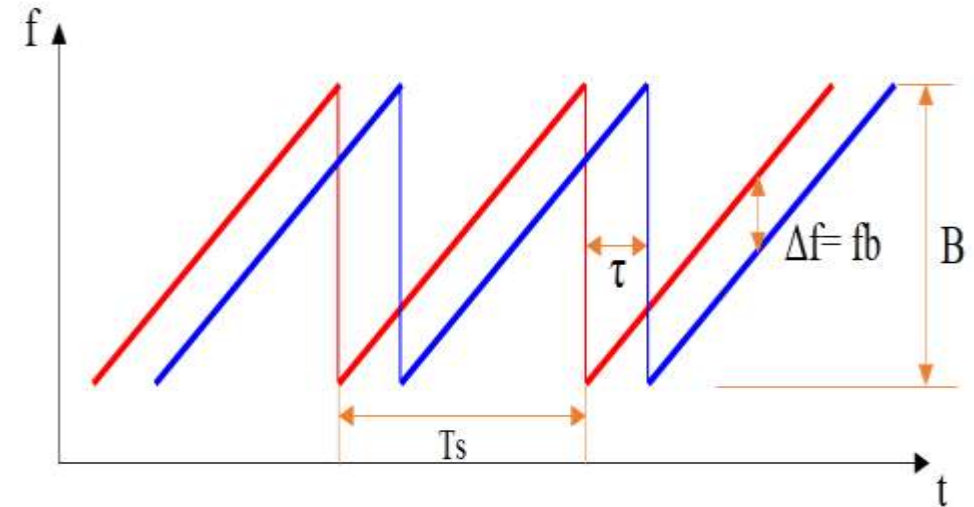


Fig.2.FMCW Radar chirp signal

Simulink Setup

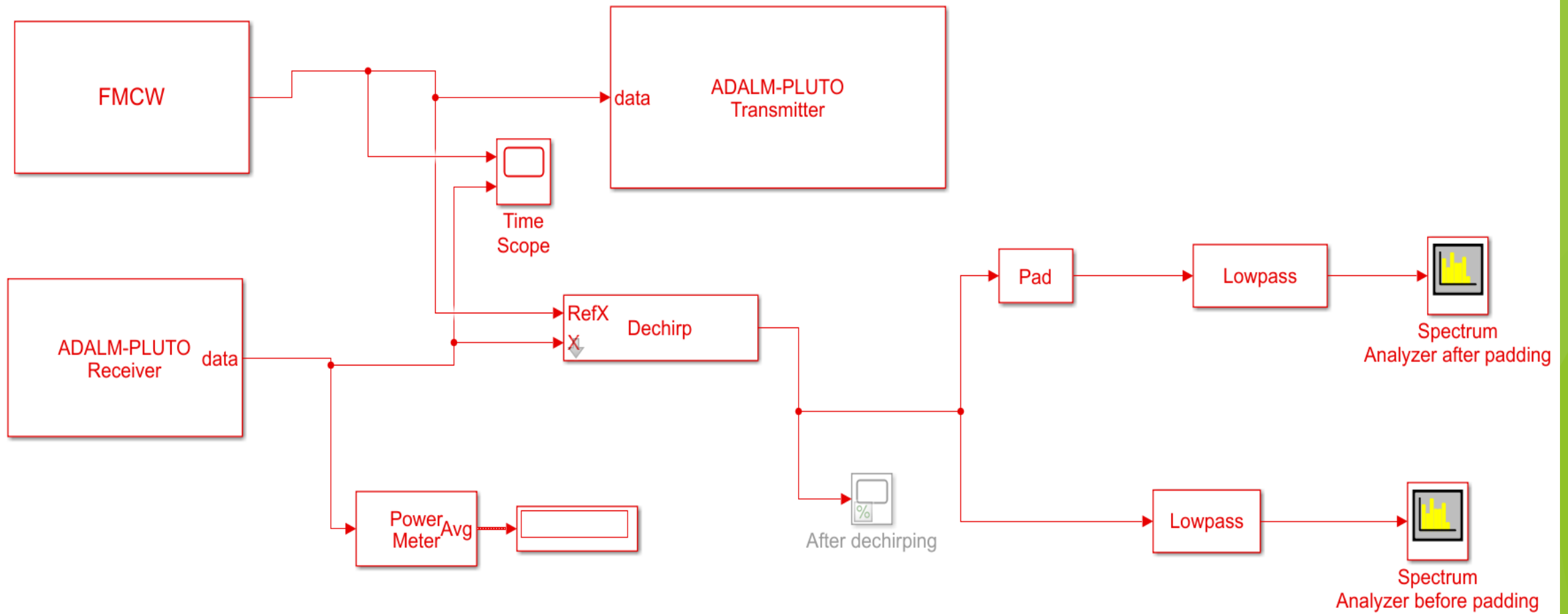


Fig.3.Block Diagram of FMCW Radar

Test Setup



Fig.4.Setup at 4 meter distance from object

Simulated Results



Fig.5(a).Real Transmitted Waveform

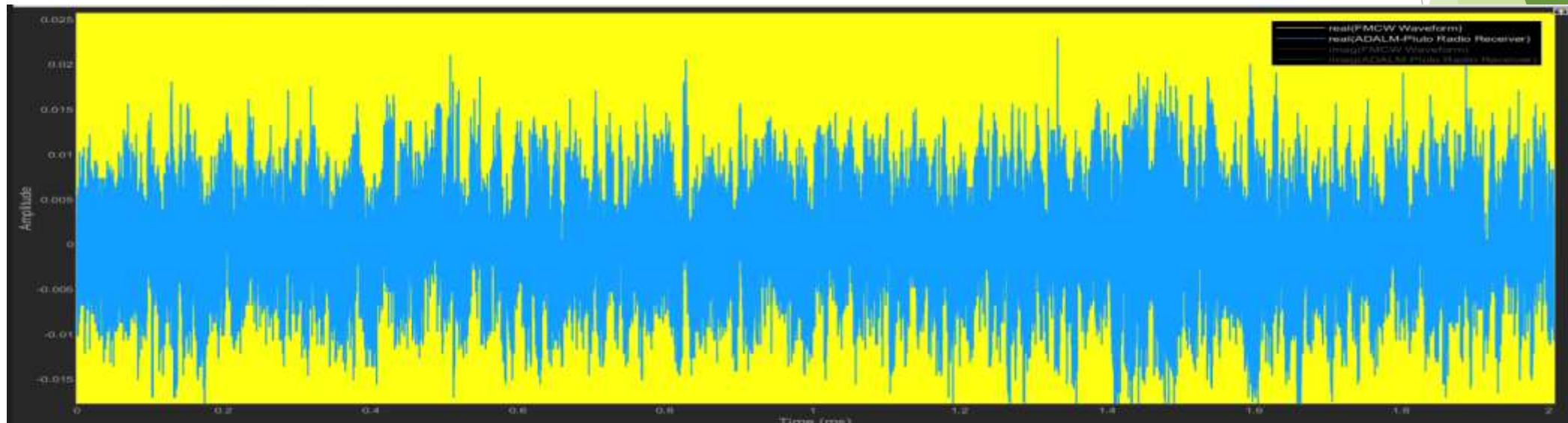


Fig.5(b).Real Received Waveform

Simulated Results

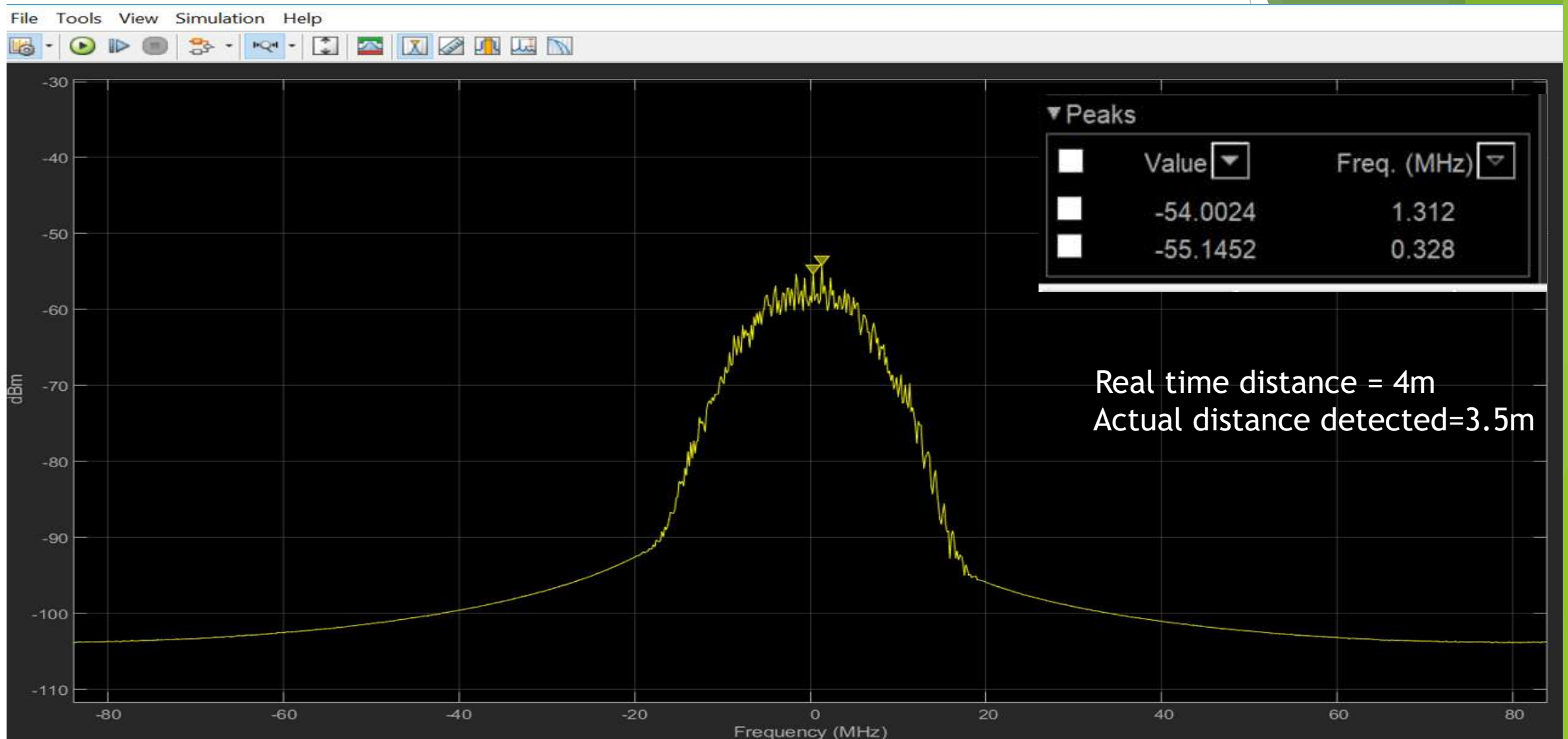
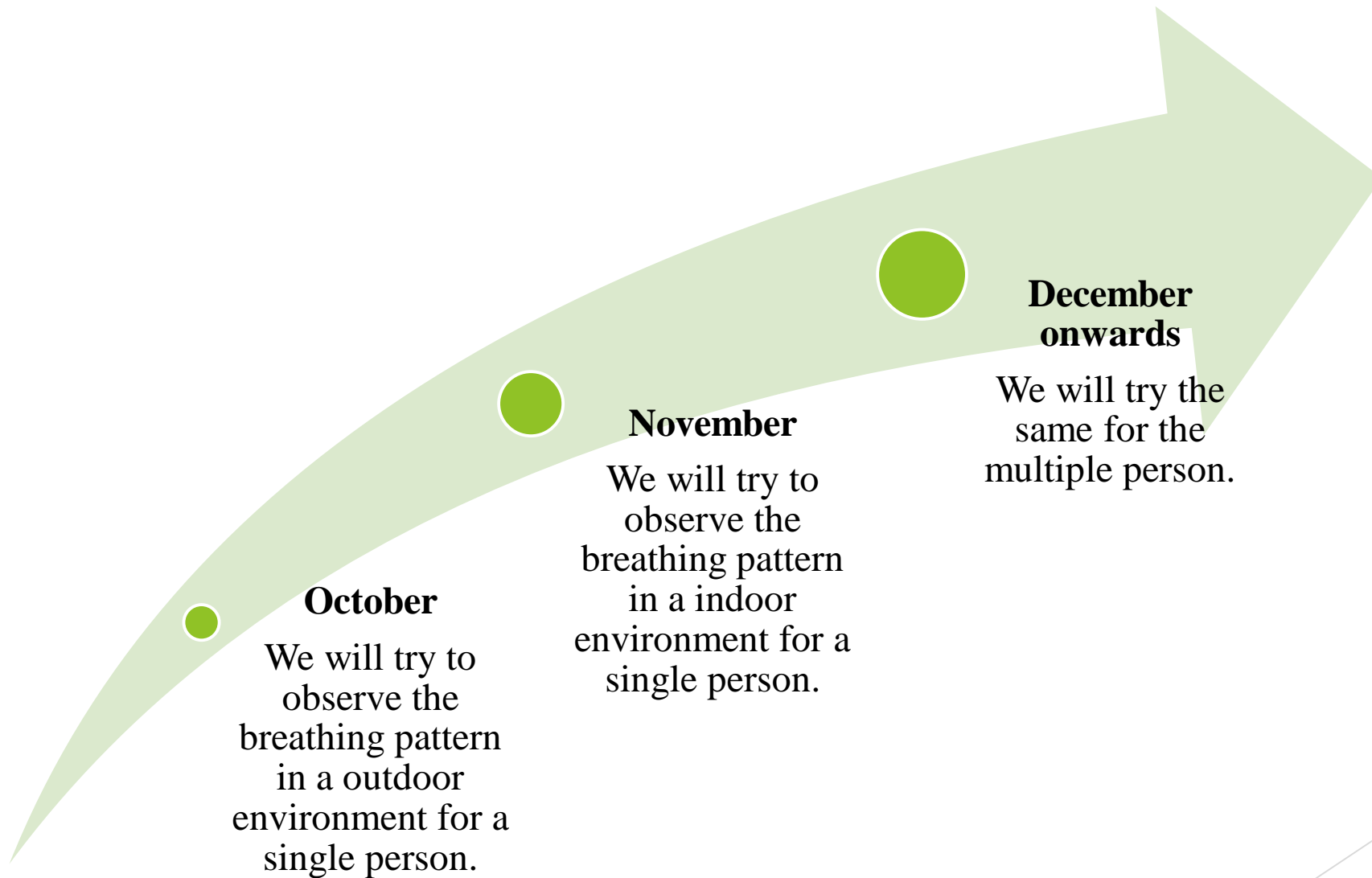


Fig.6.Real time beat Frequency detection by performing FFT on beat signal

Future Work Time line



Conclusion

- ▶ Till now we have approximately detected the range of a static object.
- ▶ Range detection of a static object in indoor system is difficult to achieve due to multipath components.
- ▶ To achieve high accuracy of range detection we have to use directional antenna.
- ▶ Due to limited bandwidth of Adalm Pluto Radio(56MHz) , range resolution of FMCW radar will be less.

