

No more learning rate tuning in gradient descent

Introduction to Machine Learning CSC2515 Project Proposal

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Abstract

We propose a variation of the gradient descent algorithm in the which the learning rate η is not fixed. Instead, we learn η itself, either by another gradient descent (first-order method), or by Newton's method (second-order). That way, gradient descent for any machine learning algorithm can be optimized.

1 Context

For a generic gradient descent problem with a cost function L that we want to minimize, let's introduce the following notations:

- $\omega(t)$ represents the weights at instant t
- $g(t) = \nabla L(\omega(t))$ the gradient of the cost function at instant t
- $\eta(t)$ is the learning rate at instant t

and the gradient descent problem with an adaptive learning rate can be written:

$$\omega(t+1) = \omega(t) - \eta(t).g(t) \quad (1)$$

$$\eta(t+1) = \eta(t) - \alpha.f'(\eta(t)) \text{ at the first order} \quad (2)$$

$$\text{or } \eta(t+1) = \eta(t) - \frac{f'(\eta(t))}{f''(\eta(t))} \text{ at the second order} \quad (3)$$

where α is a meta-learning rate and f is the real function defined by:

$$f : \eta \rightarrow L(\omega(t) - \eta.g(t))$$

Getting the first derivative of f is straightforward:

$$f'(\eta) = -g(t)^T.\nabla L(\omega(t) - \eta.g(t)) \text{ for any } \eta \quad (4)$$

Let's note that:

$$f'(\eta(t)) = -g(t)^T \cdot g(t+1) \quad (5)$$

but its second derivative is a bit harder to get.

It seems that the first-order method is easier to compute. However, it requires to choose and tune another learning rate, α . The second order method presents the advantage of being scale-invariant.

2 2^{nd} order method

2.1 Analytical formula

The analytical formula for the second derivative is given by:

$$f''(\eta) = g(t)^T \cdot H_{\omega(t)-\eta \cdot g(t)}(-g(t)) \quad (6)$$

However, with n parameters in the model, the Hessian has dimension $n \times n$, so it is very expensive to compute. We would then need a cheap way to approximate this second derivative.

2.2 Finite differences

We propose to approximate the second derivative of f via the **finite differences** method, which has a very nice expression in this case:

For any ϵ :

$$f'(\eta(t)) \approx \frac{f(\eta(t) + \epsilon) - f(\eta(t) - \epsilon)}{2\epsilon} \quad (7)$$

and:

$$f''(\eta(t)) \approx \frac{f(\eta(t) + 2\epsilon) + f(\eta(t) - 2\epsilon) - 2f(\eta(t))}{4\epsilon^2} \quad (8)$$

so:

$$\eta(t+1) \approx \eta(t) - 2\epsilon \frac{f(\eta(t) + \epsilon) - f(\eta(t) - \epsilon)}{f(\eta(t) + 2\epsilon) + f(\eta(t) - 2\epsilon) - 2f(\eta(t))} \quad (9)$$

To avoid overflowing problems, we can introduce **Laplacian smoothing**:

$$\eta(t+1) \approx \eta(t) - 2\epsilon \frac{f(\eta(t) + \epsilon) - f(\eta(t) - \epsilon) + \alpha}{f(\eta(t) + 2\epsilon) + f(\eta(t) - 2\epsilon) - 2f(\eta(t)) + \alpha} \text{ for a small real } \alpha \text{ to set} \quad (10)$$

Finally, to avoid having to set both parameters ϵ and α , we can first set $\alpha = \epsilon$, which leads to the formula:

$$\eta(t+1) \approx \eta(t) - 2\epsilon \frac{f(\eta(t) + \epsilon) - f(\eta(t) - \epsilon) + \epsilon}{f(\eta(t) + 2\epsilon) + f(\eta(t) - 2\epsilon) - 2f(\eta(t)) + \epsilon} \quad (11)$$

3 Experiments

We plan on exploring the effects of both first-order and second-order methods on the quality of convergence. Quality means both **speed of convergence**, and avoidance of **local minima**. This general method for automatic learning rate setting can be applied to any machine learning task involving gradient descent. We will compare traditional gradient descent with a fixed learning rate with our method on the following examples:

- Linear Regression. The proposed dataset is the Boston House Prices dataset studied in Assignment 1.
- Logistic Regression.
- Image classification via neural networks. Application to simple datasets such as MNIST or CIFAR-10.

4 Further exploration.

We can combine an adaptive learning rate method with other optimization algorithms, such as **momentum**. In this case the learning schedule could have the following form:

$$\delta(t+1) = -\eta(t).g(t) + \lambda.\delta(t) \tag{12}$$

$$\omega(t+1) = \omega(t) + \delta(t) \tag{13}$$

$$\eta(t+1) = \eta(t) - \frac{f'(\eta(t))}{f''(\eta(t))} \tag{14}$$