AVR Interfacing ADC

Agenda

- Introduction to ADC.
- AVR ADC.
- AVR ADC Registers.
- AVR ADC Programming.

Introduction to ADC

- In the Real World, a **sensor** senses any physical parameter and converts into an equivalent analog electrical signal this analog signal is converted into a digital signal using an Analog to Digital Converter (ADC).
- ADC can be defined by
 - ☐ The ADC **precision** is the number of distinguishable ADC inputs that ADC can measure (e.g. 1024 alternatives for 10 bits ADC).
 - ☐ The ADC **range** is the maximum and minimum ADC input (e.g. 0 to +5V).
 - he ADC **resolution** is the smallest distinguishable change in input voltage that can be sensed by ADC. The resolution is the change in input that causes the digital output to change by 1.

Resolution(volts) =
$$\frac{\text{Range(volts)}}{\text{Precision(alternatives)}} = \frac{5V-0}{1024} = 4.88\text{mv}$$

$$ADC = \frac{V_{IN} \times 1024}{V_{REF}}$$

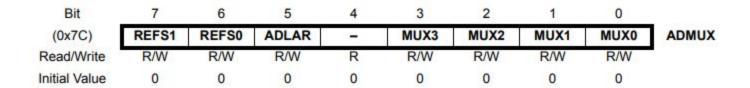
Introduction to ADC

- ADC Prescaler
 The ADC of the AVR converts analog signal into digital signal at some regular interval. This interval is determined by the clock frequency.
 The prescaler acts as frequency division factor.
 There are some predefined division factors 2, 4, 8, 16, 32, 64, and 128.
 For example, a prescaler of 128 implies

 F ADC = F CPU/8. For F CPU = 16MHz, F ADC = 16M/128 =
 - so time required to convert the analog signal to digital is 1/125 ms.

125kHz.

ADMUX - ADC Multiplexer Selection Register

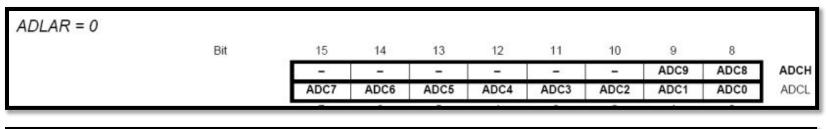


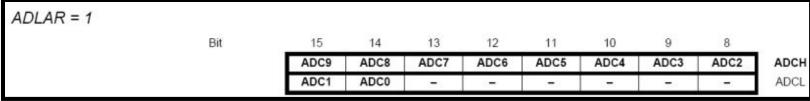
ightharpoonup Bits 7:6 – REFS1:0 – ADC V_{ref} Reference Selection Bits These bits select the voltage reference for the ADC. The internal voltage reference options may not be used if an external reference voltage is being applied to the AREF pin

REFS1	REFS0	Voltage Reference Selection		
0	0	AREF, internal V _{REF} turned off		
0	1	AV _{CC} with external capacitor at AREF pin		
1	0	Reserved		
1	1	Internal 1.1V voltage reference with external capacitor at AREF pin		

☐ Bit 5 – ADLAR – ADC Left Adjust Result

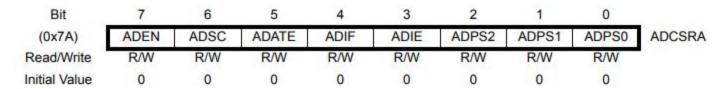
The ADLAR bit affects the presentation of the ADC conversion result in the ADC Data Register. Write one to ADLAR to left adjust the result. Otherwise, the result is right adjusted.





☐ Bits 3:0 – MUX4:0 – Analog Channel Bits There are 6 ADC channels (PC0...PC5).

ADCSRA – ADC Control and Status Register A



☐ Bit 7 – ADEN – ADC Enable

This is enabled, ADC operations. Otherwise the pins behave as GPIO ports.

□ Bit 6 – ADSC – ADC Start Conversion

1 is written as long as the conversion is in progress, When the conversion is complete, it returns to zero.

□ Bit 5 – ADATE – ADC Auto Trigger Enable

1 enables auto trigger where the ADC will start a conversion on a positive edge of the selected trigger signal.

□ Bit 4 – ADIF – ADC Interrupt Flag

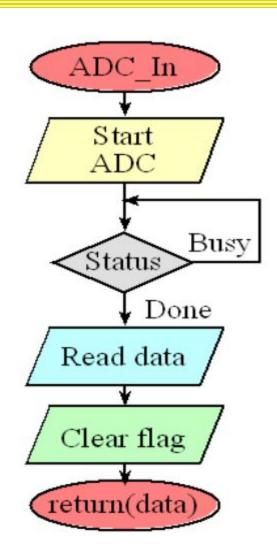
This bit is set when an ADC conversion completes and the Data Registers are updated.

- □ Bit 3 ADIE ADC Interrupt Enable
- ☐ Bits 2:0 ADPS2:0 ADC Prescaler Select Bits

ADPS2	ADPS1	ADPS0	Division Factor
0	0	0	2
0	0	1	2
0	1	0	4
0	1	1	8
1	0	0	16
1	0	1	32
1	1	0	64
1	1	1	128

ADCL and ADCH – ADC Data Registers

The result of the ADC conversion is stored here.



ADC Initialization

The following code segment initializes the ADC

```
void adc_init()
{
    // AREF = AVcc
    ADMUX = (1<<REFS0);

    // ADC Enable and prescaler of 128
    // 16000000/128 = 125000
    ADCSRA = (1<<ADEN)|(1<<ADPS2)|(1<<ADPS1)|(1<<ADPS0);
}</pre>
```

Reading ADC Value

The following code segment reads the value of the ADC

```
uint16 t adc read(uint8 t ch)
  // select the corresponding channel 0~5
  // ANDing with '7' will always keep the value
  // of 'ch' between 0 and 5
  ch &= 0b00000111; // AND operation with 7
  ADMUX = (ADMUX \& 0xF8) | ch; // clears the bottom 3 bits before ORing
  // start single conversion
  // write '1' to ADSC
  ADCSRA \mid = (1 << ADSC);
  // wait for conversion to complete
  // ADSC becomes '0' again
  // till then, run loop continuously
  while (ADCSRA & (1 << ADSC));
  return (ADC);
```

The following circuit describes the connection of potentiometer.

The following code reads ADC value and checks if the reading is above 500, the led will be turned on. Otherwise, the led will be turned off.

```
void main()
                                                                  +Vcc
   uint16 t adc result0;
    DDRB = 0x20; // to connect led to PB5
                                                                               +Vcc
    // initialize adc
                                                                     R1
    adc init();
                                                                               MCU
    while (1)
                                                                             ADC_IN
        adc_result0 = adc_read(0); // read adc value at PC0
                                                                    P1
                                                                        V_{ADC}
        // condition for led to turn on or off
        if (adc result0 > 500)
            PORTB = 0x20;
        else
            PORTB = 0 \times 00;
```

Using ADC interrupt:

- Replacing conversion waiting to be completed with firing a flag or signal that called "ADC interrupt".
- The main difference that will happen in the previous code to be adopted with the ADC interrupt, will be as following;
 - ☐ In *ADC Initialization*, global interrupt and ADC interrupt enable have to be set.
 - In Reading ADC Value, while loop which waiting for the conversion ending will be remove and global flag will checked if it comes high or not, In case of the flag comes high the ADC read will be ready to be returned from the function.
 - ☐ This flag is controlled in the interrupt function (ISR).

ADC Initialization

The following code segment initializes the ADC

```
void adc init()
    // AREF = AVCC
    ADMUX = (1 << REFS0);
    // ADC Enable and prescaler of 128
    // 16000000/128 = 125000
    // (1 << ADIE) = 1 \square set ADC interrupt enable
    ADCSRA = (1 << ADEN) | (1 << ADPS2) | (1 << ADPS1) | (1 << ADPS0)
               | (1 << ADIE) ;
    // Set global interrupt
    sei();
```

Reading ADC Value

```
uint8 t ADC endconversion Flag=0;
int16 t adc read(uint8 t ch)
 // select the corresponding channel 0~5
 // ANDing with '7' will always keep the value
 // of 'ch' between 0 and 5
  ch &= 0b00000111; // AND operation with 7
 ADMUX = (ADMUX \& 0xF8) | ch; // clears the bottom 3 bits before ORing
 // start single conversion
 // write '1' to ADSC
 ADCSRA \mid = (1 << ADSC);
 // wait for conversion to complete
                                           ISR(ADC vect)
 // ADSC becomes '0' again
 // till then, run loop continuously
                                              ADC endconversion Flag=1;
  if (ADC endconversion Flag==1) {
    ADC endconversion Flag=0;
         return (ADC);
 else
    return (-1);
```

Main function:

```
void main()
                                                                +Vcc
    uint16 t adc result0;
    DDRB = 0x20;
                       // to connect led to PB5
                                                                              +Vcc
    // initialize adc
    adc init();
                                                                   R1
    while (1)
                                                                             MCU
                                                                           ADC_IN
        adc_result0 = adc_read(0);  // read adc value at PA0
                                                                   P1
        // condition for led to turn on or off
                                                                      V_{ADC}
        if(adc result0!=-1){
            if (adc result0 > 500)
                PORTB = 0x20;
            else if ()
                PORTB = 0x00;
```