MAEG5720

Computer Vision in Practice

Assignment 3

Date: 29th, October 2021

Due Date: 12th, November 2021

Submission Guidelines

The folder you hand in must contain the following:

README.txt – contains anything about the assignment that you want to tell the TA, including a brief introduction of the usage of the code.

Code/ - directory containing all your code (only .m files and image files allowed) for this assignment, which is expected to have at least one .m file along with one .jpg or .png files.

Report.pdf – only 1 document showing the question number, result and comments.

Rename the folder as <your student ID>-Asgn2, and compress it into <your student ID>Asgn2.zip, and upload it to the blackboard system. (For example, 1155123456-Asgn2/ and 1155123456Asgn2.zip, pay attention to the name.)

Please read the guidelines CAREFULLY. If you fail to meet the deadline because of a submission problem on your side, marks will still be deducted.

The late submission policy is as follows:

- 1 day late: -20 marks
- 2 days late: -40 marks
- 3 days late: -100 marks

Pay attention to the format before. **10% deduction for every wrong format** (filename, function name, etc.).

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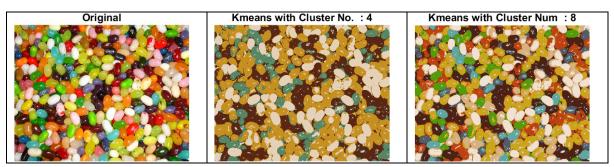
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Aim:

Images usually consist of many different objects. To better understand the image, we need to separate the objects for further processing. The process group pixels into different clusters with similar features, such as colours or spatial distance. This process is known as segmentation.

In this assignment, you will implement a well-known k-means algorithm. This is a general algorithm which groups the data into a set of k clusters, where k is defined by the user. One particular application of k-means is image segmentation in which the pixels with similar features (colours or spatial distance) are grouped into same cluster.

The following figures shows the results of *k*-means Segmentations



The k-means algorithm is easy to implement. The pseudo-code as follow:

Algorithm k-means

Input: RGB Images with $m \times n$ pixels. The user defined number of clusters, kMax iteration number it_{max}

Output: A set of k labels, $\iota_1, \iota_2 \dots \iota_k$

```
1. Initialise k cluster centre c_1, c_2 \dots c_k
2.
3.
       for each pixel p_i, do
4.
             \iota_i = 0
5.
             dist_{min} = \infty
             for each cluster centre, c_i do
6.
7.
                   dist_i= distance of p_i to c_i
8.
                   if dist_i < dist_{min} then
9.
                      \iota_i = j
10.
                      dist_{min} = dist_i
11.
                   end if
             end for
12.
13.
         end for
14.
      for each cluster centre, c_k do
          c_k = mean(p_i \text{ which label } \iota_i = k)
15.
16.
      end for
17. end do while n < it_{max}
18. change each pixel p_i to it's label c_k where k = l_i for display
```

Question 1: Please write your own MATLAB code to implement the above algorithm

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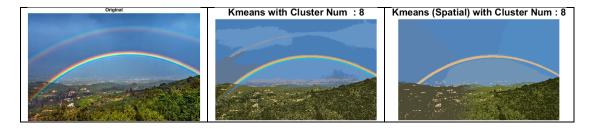
- (a) Read an RGB image into your workspace
- (b) Randomly Initialize the centre $c_1, c_2 \dots c_k$
- (c) Using the RGB value to compute the distance $dist(p_i, c_i)$ (30%)

$$dist(p_i, c_j) = \sqrt{\left(R_{p_i} - R_{c_j}\right)^2 + \left(G_{p_i} - G_{c_j}\right)^2 + \left(B_{p_i} - B_{c_j}\right)^2}$$

to perform the segmentation. Show the result for different number of clusters. (for instance, 4, 8). You can set the termination a fixed number of iterations.

- (d) The termination criteria also another concern. You can do fixed number of iterations. Or you can do the following
 - (i) After each iteration, check if **each centre** c_j **changes** within certain threshold value (20%)
 - (ii) After each iteration, check if the *number of points changes labels* within certain threshold value. (20%)

Question 2: Besides RGB value, you can also put spatial distance into consideration.



The distance function can be easily modified as follow

$$dist(p_i, c_j) = \sqrt{\left(R_{p_i} - R_{c_j}\right)^2 + \left(G_{p_i} - G_{c_j}\right)^2 + \left(B_{p_i} - B_{c_j}\right)^2 + \left(x_{p_i} - x_{c_j}\right)^2 + \left(y_{p_i} - y_{c_j}\right)^2}$$

Please implemented the k-means segmentation with the above distance function. You can use termination method in either d(i) or d(ii). (30%)

What to submit: A pdf file with questions and answers. The .m files of the code. A readme.txt if you have additional information for TA.