

31<sup>st</sup> August, 2020

## 1. Exercise 1

Consider the 1D heat equation in the domain  $(0, d)$

$$\begin{cases} \frac{\partial u(t, x)}{\partial t} - \frac{\partial^2 u(t, x)}{\partial x^2} = f(t, x), & 0 < x < d, 0 < t \leq T, \\ u(t, 0) = 0, & 0 < t \leq T, \\ \frac{\partial u(t, d)}{\partial x} = g(t), & 0 < t \leq T, \\ u(0, x) = u_0(x), & 0 < x < d, \end{cases} \quad (1)$$

for suitable functions  $f$ ,  $g$ , and  $u_0$

### 1.1.

#### Question

Introduce the **semi-discrete Galerkin** Finite Element formulation of (1), suitably defining the introduced function space(s).

#### Solution

We start by multiplying for each  $t > 0$  the differential equation by a test function  $v = v(\mathbf{x})$  and integrating on  $(0, d)$ . We set the set to which the test function belongs as  $V = H_{1_D}^1(\Omega)$  and for each  $t > 0$  we aim to find  $u(t) \in V$  such that

$$\int_{\Omega} \frac{\partial u(t)}{\partial t} v \, d\Omega + \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} f(t) v \, d\Omega \quad \forall v \in V$$

where  $\Omega = (0, d)$ .

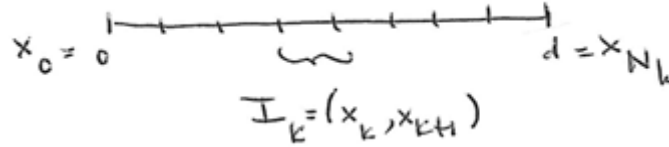
At this point we discretize the equation into (note how the rightmost term appears as a result of integration by parts)

$$\begin{aligned} \int_0^d \frac{\partial u_h(t)}{\partial t} v_h \, dx + \int_0^d \frac{\partial u_h(t)}{\partial x} \frac{\partial v_h(t)}{\partial x} \, dx &= \int_0^d f \, v_h \, dx + \\ &+ g \, v_h \quad \forall v_h \in V_h \end{aligned} \quad (2)$$

where we've set  $u_h(t=0) = u_{0_h} \in V_h$  and  $V_h$  is the space of continuous on  $(0, d)$  piece-wise polynomials of degree  $\leq r$ , in short we seek a solution  $u_h(t) \in V_h$  where

$$V_h = \left\{ v_h \in C^0(0, d): v_h(0) = 0, v_h|_{I_k} \in \mathbb{P}^r \quad \forall k = 0, \dots, N_h - 1 \right\}$$

where each  $I_k$  is a piece of the interval



Discretization of the interval

## 1.2.

### Question

Write the  $\theta$ -method for the full discretization of (1)

### Solution

The  $\theta$ -method generalizes numerical approximation schemes for time discretization of space-discretized schemes where  $0 \leq \theta \leq 1$  taking (2) we discretize the time derivative as a simple difference normalize by the timestep, in essence

$$\frac{1}{\Delta t} \int_0^d (u_h^{n+1} - u_h^n) v_h \, dx + \int_0^d (\theta u_{h_x}^{n+1} + (1 - \theta) u_{h_x}^n) v_h \, dx = \int_0^d (\theta f^{n+1} + (1 - \theta) f^n) v_h \, dx + (\theta g^{n+1} + (1 - \theta) g^n) v_h \quad \forall v_h \in V_h \wedge n = 0, 1, \dots$$

where each timestep is  $n\Delta t$  long.

For  $\theta = 0$  and  $\theta = 1$  we obtain respectively **forward** and **backward Euler** methods which are accurate to order one with respect  $\Delta t$ , while for  $\theta = \frac{1}{2}$  we obtain the **Crank-Nicolson** which is of second order in  $\Delta t$ , more precisely  $\theta = \frac{1}{2}$  is the only value for which we obtain a second-order method,

## 1.3.

### Question

Discuss the numerical stability of the scheme, depending upon the value of  $\theta$  (no proof needed).

### Solution

Given that  $f \neq 0$ .

- If  $\theta < \frac{1}{2}$  it can be shown that the  $\theta$ -method is absolutely stable only for

$$\Delta t \leq \frac{2}{(1 - 2\theta)\lambda_h^{N_h}}$$

where  $\lambda_h^{N_h}$  is the largest eigenvalue of the generalized eigenvalue problem  $A\mathbf{x} = \lambda M\mathbf{x}$ . It can be shown that  $\lambda_h^{N_h} \lesssim h^{-2}$  therefore

$$\Delta t \approx \frac{2h^2}{(1 - 2\theta)}$$

- If  $\theta \geq \frac{1}{2}$  then it is unconditionally absolutely stable.

## 1.4.

### Question

Prove the stability properties of the backward Euler discretization (assume for simplicity  $g = 0$ ).

### Solution

Backward Euler is equivalent to applying  $\theta = 1$ , therefore we take (2), apply  $g = 0$  and ,finally, impose the test function  $v_h = u_h^{n+1}$ , then we get

$$\underbrace{\frac{1}{\Delta t} \int_0^d (u_h^{n+1} - u_h^n) u_h^{n+1} dx}_{(1)} + \underbrace{\int_0^d (u_h^{n+1})^2 dx}_{(2)} = \underbrace{\int_0^d f^{n+1} u_h^{n+1} dx}_{(3)}$$

where  $\Omega = (0, d)$ .

1. We apply  $(a - b, a) \geq \frac{1}{2}(\|a\|^2 - \|b\|^2) \quad \forall a, b$  to get

$$(1) \geq \frac{1}{2\Delta t} (\|u_h^{k+1}\|_{L^2}^2 - \|u_h^k\|_{L^2}^2)$$

2. We use the coercivity of  $a(\cdot, \cdot)$  to get

$$(2) \geq \alpha \|u_h^{k+1}\|_{L^2}^2$$

3. We apply Cauchy-Schwartz  $\rightarrow$  Poincare  $\rightarrow$  Young

$$\begin{aligned} \left| \int_0^d f^{n+1} u_h^{n+1} \right| &\underbrace{\leq}_{\text{C-S}} \|f^{n+1}\|_{L^2} \|u_h^{n+1}\|_{L^2} \\ &\underbrace{\leq}_{\text{Poincare}} \|f^{n+1}\|_{L^2} C_p \|u_{h_x}^{n+1}\|_{L^2} \\ &\underbrace{\leq}_{\text{Young}} \frac{1}{2} (\|f^{n+1}\|_{C_p})^2 + \frac{1}{2} \|u_{h_x}^{n+1}\|_{L^2}^2 \end{aligned}$$

16<sup>th</sup> June, 2023

## 1. Problem 1

This problem isn't in the course material for AA 2023/2024, won't be in future exams.

## 2. Problem 2

Consider the following problem for  $\Omega = (0, 1)^2$

$$\begin{cases} -\operatorname{div}(\varepsilon \nabla u) + \frac{\partial u}{\partial y} = f & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega, \end{cases} \quad (2)$$

where  $\varepsilon > 0$ , and  $f \in L^2(\Omega)$ ,  $g \in L^2(\partial\Omega)$  are two *suitable* functions.

## 2.1.

### Question

Introduce the variational (weak) formulation of (2) and explain why a standard Galerkin Finite Element approximation may not be suitable for (2) when  $\varepsilon \ll 1$

### Solution

Problem (2) is the non-conservative form of the **Advection-Diffusion-Reaction** equation where  $\mathbf{b} = 1$  and  $\sigma = 0$ , we multiply both sides of the equation by a test function and integrate over the domain.

The problem then becomes finding  $u \in V = H_0^1(\Omega)$  such that

$$a(u, v) = F(v) \quad \forall v \in V$$

where the bilinear form and the linear forms are defined as

$$a(u, v) = \int_{\Omega} \varepsilon \nabla u \cdot \nabla v d\Omega + \int_{\Omega} \frac{\partial u}{\partial y} v d\Omega,$$

$$F(v) = \int_{\Omega} f v$$

In cases where  $\varepsilon \ll 1$  the Peclet number becomes too big and therefore **GLS** or **SUPG** methods are needed to stabilize the method.

## 2.2.

### Question

Introduce a Finite Element **Galerkin-Least-Squares (GLS)** approximation of (2) for  $g = 0$

### Solution