Title

Mechatronic Project 478
Final Report

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Executive summary

Title of Project
...
Objectives
...
What is current practice and what are its limitations?
...
What is new in this project?
...
If the project is successful, how will it make a difference?
...
What are the risks to the project being a success? Why is it expected to be successful?
...
What contributions have/will other students made/make?
...
Which aspects of the project will carry on after completion and why?
...
What arrangements have been/will be made to expedite continuation?
...

Acknowledgements

Table of contents

List of figures

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List of symbols

Constants

$L_0 =$	$300\,\mathrm{mm}$	

Variables

Re_{D}	Reynolds number (diameter)	$[\,]$
x	Coordinate	$[\,\mathrm{m}\,]$
$\ddot{x}$	Acceleration	$[\,\mathrm{m/s^2}\,]$
θ	Rotation angle	$[\,\mathrm{rad}\,]$
τ	Moment	$[\,\mathrm{N{\cdot}m}\,]$

Vectors and Tensors

$\vec{v}$	Physical vector, see equation ...

Subscripts

a	Adiabatic
a	Coordinate

Abreviations

DEM	Discrete Element Method
FEA	Finite Element Analysis

Chapter 1

Introduction

1.1 Background

Starting from the big picture, gradually narrow focus down to this project and where this report fits in. Hello world.

1.2 Objectives

The objectives of the project (in some cases the objectives of the report). If necessary describe limitations to the scope.

1.3 Motivation

Why this specific project/report is worthwhile.

Chapter 2

Literature Review

2.1 Background

The advantage of the [[Jet-Tipped Helicopter]] is the omission of the transmission and [[tail rotor]], thus making it more simple and cheaper to produce. The decreased weight allows it to have a larger payload. No need for a high-speed gear boxes, clutches, transmission shafts, oil system w/ tanks...

2.2 Objectives

The objectives of the project (in some cases the objectives of the report). If necessary describe limitations to the scope.

2.3 Motivation

Why this specific project/report is worthwhile.

Chapter 3

Literature review

3.1 Discrete element method

The Discrete Element Method (DEM) analysis (**?**) uses spherical objects. **?** developed a DEM model for ellipsoids.

Chapter 4

Content chapter

Unless the chapter heading already makes it clear, an introductory paragraph that explains how this chapter contributes to the objectives of the report/project.

4.1 Heading level 2

4.1.1 Heading level 3

4.1.1.1 Deepest heading, only if you cannot do without it

Equations: An equation must read like part of the text. The solution of the quadratic equation $ax^2 + bx + c = 0$ given by the following expression (note the full stop after the equation to indicate the end of the sentence):

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2b}. \tag{4.1}$$

In other cases the equation is in the middle of the sentence. Then the paragraph following the equation should start with a small letter. Euler's identity is

$$e^{i\pi} + 1 = 0, \tag{4.2}$$

where e is Euler's number, the base of natural logarithms.

The `amsmath` has a wealth of structure and information on formatting of mathematical equations.

Symbols and numbers: Symbols that represent values of properties should be printed in italics, but SI units and names of functions (e.g. sin, cos and tan) must not be printed in italics. There must be a small hard space between a number and its unit, e.g. 120 km. Use the `siunitx` package to typeset numbers, angles and quantities with units:

`\num{1.23e3}`	→	1.23×10^3
`\ang{30}`	→	30°
`\qty{20}{N.m}`	→	$20\,\mathrm{N \cdot m}$

Figures and tables: The `graphicx` package can import `PDF`, `PNG` and `JPG` graphic files.

Table 4.1: Standard ISO paper sizes

Paper	Sizes	
	W	H
	[mm]	[mm]
A0	841	1189
A1	594	841
A2	420	594
A3	297	420
A4	210	297
A5	148	210

Figure 4.1: Water plants

Chapter 5

Conclusions

Appendix A

Mathematical proofs

A.1 Euler's equation

Euler's equation gives the relationship between the trigonometric functions and the complex exponential function.

$$e^{i\theta} = \cos\theta + i\sin\theta \tag{A.1}$$

Inserting $\theta = \pi$ in (A.1) results in Euler's identity

$$e^{i\pi} + 1 = 0 \tag{A.2}$$

A.2 Navier Stokes equation

The Navier–Stokes equations mathematically express momentum balance and conservation of mass for Newtonian fluids. Navier-Stokes equations using tensor notation:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_j}\left[\rho u_j\right] = 0 \tag{A.3a}$$

$$\frac{\partial}{\partial t}\left(\rho u_i\right) + \frac{\partial}{\partial x_j}\left[\rho u_i u_j + p\delta_{ij} - \tau_{ji}\right] = 0, \quad i = 1, 2, 3 \tag{A.3b}$$

$$\frac{\partial}{\partial t}\left(\rho e_0\right) + \frac{\partial}{\partial x_j}\left[\rho u_j e_0 + u_j p + q_j - u_i \tau_{ij}\right] = 0 \tag{A.3c}$$

Appendix B

Experimental results