

# RAYEN GHALI

+1 506-925-0056 | rayenghali02@gmail.com | linkedin.com/in/rayenghali | github.com/Rayen023

## EDUCATION

### University of Moncton, Faculty of Engineering

Master of Applied Science (MASC) | CGPA: 4.15/4.3

Expected Dec 2025

New Brunswick, Canada

### University of Carthage, National Institute of Applied Science and Technology (INSAT)

Engineering Diploma in Instrumentation and Industrial Maintenance | Graduated with High Honours

Sept 2023

Tunis, Tunisia

## PROJECTS

### Vision Language Action Models for Industrial Robotic Manipulation

Master's Thesis

- Applied parameter-efficient fine-tuning (QLoRA) to pretrained VLMs to generate discrete action tokens for robotic control using the Unsloth framework and OpenX-Embodiment dataset
- Investigated trade-offs between discrete action tokenization and continuous action generation using diffusion-based decoders for robotic manipulation
- Fine-tuned pretrained VLA models (NVIDIA Isaac GR00T N1.5 and SmolVLA) on manually collected datasets with imitation learning. Evaluated on real-world tasks using a SO-ARM101 robotic arm
- Explored reinforcement learning methods to improve visuomotor policy generalization
- Executed and managed multi-GPU training jobs through the CCDB Canada Compute platform

## EXPERIENCE

### Research Assistant

May 2025 – Aug 2025

CFRIA, University of Moncton

New Brunswick, Canada

- Architected a stateful LangGraph agent for natural language robot control (KUKA KR 50 R2100), featuring persistent conversational memory and tools for pick-and-place, Cartesian, and joint space movements
- Designed and implemented a multimodal pipeline processing continuous audio streams with Voice Activity Detection for speech segmentation and efficient transcription, achieving < 2.6s end-to-end latency
- Implemented a robust error recovery system with safety checks, rollback to safe state, automatic retry mechanisms grounded in robot state and real-time voice feedback
- Co-authored: "LLM-driven agent for speech-enabled control of industrial robots: A case study in snow-crab quality inspection" published in Results in Engineering 2025

### Research Assistant

Jan 2025 – Apr 2025

CFRIA, University of Moncton

New Brunswick, Canada

- Migrated 15 years of Acadian student survey data from 7 schools, converting Excel files to a PostgreSQL database
- Built a multi-agent swarm workflow using LangGraph with human-in-the-loop validation for natural language queries
- Developed a Streamlit web application with automated plotting for query results (chatcapitalhumain.ca)

### Research Assistant

June 2024 – Dec 2024

Centre d'études acadiennes Anselme-Chiasson (CEAAC)

New Brunswick, Canada

- Developed a RAG-based conversational agent for querying Acadian genealogical records (1700-1900) (chatacadien.ca)
- Implemented advanced RAG techniques (parent-child chunking, reranking, context compression, HyDE) to prevent identity conflation caused by unrelated namesakes in large-scale unstructured text data and reduce hallucinations
- Evaluated system performance using RAGAS metrics (faithfulness, context precision/recall) on real user interactions
- Built a Streamlit web application for archival image search with VLM-generated descriptions (chatpatrimoineacadien.ca)

### Research Assistant

Apr 2023 – June 2024

CFRIA, University of Moncton

New Brunswick, Canada

- Benchmarked modern object detection models (YOLOv5-v9, RT-DETR) on industrial datasets, identifying optimal performance-speed balance
- Developed SSL-YOLO, a few-shot learning framework combining contrastive self-supervised pre-training with YOLOv8
- Co-authored and presented conference papers "Real-time defect detection systems for steel and wood inspection", IEEE CECCE 2024 and "Benchmarking few-shot learning techniques for steel surface defect detection", IEEE SWC 2025

## SKILLS

Languages: Python, SQL

Technologies: Streamlit, PyTorch, Transformers, LangChain, Google GenAI, LeRobot, Git, Docker, Supabase

## LANGUAGES

Arabic: Native | French: Bilingual | English: Proficient